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Towards more precise rewriting approximations $\stackrel{\star}{\sim}$

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ABSTRACT

To check a system, some verification techniques consider a set of terms I that represents the initial configurations of the system, and a rewrite system R that represents the system behavior. To check that no undesirable configuration is reached, they compute an over-approximation of the set of descendants (successors) issued from I by R, expressed by a tree language. Some techniques have been presented using regular tree languages, and more recently using non-regular languages to get better approximations: using context-free tree languages [1] on the one hand, using synchronized tree languages [2] on the other hand. In this paper, we merge these two approaches to get even better approximations: we compute an over-approximation of the descendants, using synchronized-context-free tree languages expressed by logic programs. We give several examples for which our procedure computes the descendants in an exact way, unlike former techniques.

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1. Introduction

To check systems like cryptographic protocols or Java programs, some verification techniques consider a set of terms *I* that represents the initial configurations of the system, and a rewrite system *R* that represents the system behavior [3–5]. To check that no undesirable configuration is reached, they compute an over-approximation of the set of descendants¹ (successors) issued from *I* by *R*, expressed by a tree language. Let $R^*(I)$ denote the set of descendants of *I*, and consider a set *Bad* of *undesirable* terms. Thus, if a term of *Bad* is reached from *I*, i.e. $R^*(I) \cap Bad \neq \emptyset$, it means that the protocol or the program is flawed. In general, it is not possible to compute $R^*(I)$ exactly. Instead, one computes an over-approximation *App* of $R^*(I)$ (i.e. $App \supseteq R^*(I)$), and checks that $App \cap Bad = \emptyset$, which ensures that the protocol or the program is correct.

However, *I*, *Bad* and *App* have often been considered as regular tree languages, recognized by finite tree automata. In the general case, $R^*(I)$ is not regular, even if *I* is. Moreover, the expressiveness of regular languages is poor. Then the over-approximation *App* may not be precise enough, and we may have $App \cap Bad \neq \emptyset$ whereas $R^*(I) \cap Bad = \emptyset$. In other words, the protocol is correct, but we cannot prove it. Some work has proposed CEGAR-techniques (Counter-Example Guided Approximation Refinement) to conclude as often as possible [3,6,7]. However, in some cases, no regular over-approximation works [8].

To overcome this theoretical limit, the idea is to use more expressive languages to express the over-approximation, i.e. non-regular ones. However, to be able to check that $App \cap Bad = \emptyset$, we need a class of languages closed under intersection

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 $^{^{1}}$ I.e. terms obtained by applying arbitrarily many rewrite steps on the terms of I.

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and whose emptiness is decidable. Actually, if we assume that *Bad* is regular, closure under intersection with a regular language is enough. The class of context-free tree languages has these properties, and an approximation technique using context-free tree languages has been proposed in [1]. On the other hand, the class of synchronized tree languages [9] also has these properties, and an approximation technique using synchronized tree languages has been proposed in [2]. Both classes include regular languages, but they are incomparable. Context-free tree languages cannot express dependencies between different branches, except in some cases, whereas synchronized tree languages cannot express vertical dependencies.

We want to use a more powerful class of languages that can express the two kinds of dependencies together: the class of synchronized-context-free tree-(tuple) languages [10,11], which has the same properties as context-free languages and as synchronized languages, i.e. closure under union, closure under intersection with a regular language, decidability of membership and emptiness.

In this paper, we propose a procedure that always terminates and that computes an over-approximation of the descendants obtained by a linear rewrite system, using synchronized-context-free tree-(tuple) languages expressed by logic programs. Compared to our previous work [2], we introduce "input arguments" in predicate symbols, which is a major technical change that highly improves the quality of the approximation, and that requires new results and new proofs. This work is a first step towards a verification technique offering more than regular approximations. Some on-going work is discussed in Section 6 in order to make this technique be an acceptable verification technique.

The paper is organized as follows. Term rewriting and synchronized-context-free tree languages are introduced in Section 2. Then technical results needed in the sequel are established in Section 3. Our main contribution, i.e. computing approximations, is presented in Section 4. Finally, in Section 5 our technique is applied to examples, in particular when $R^*(I)$ can be expressed in an exact way neither by a context-free language, nor by a synchronized language.

Comparison with [1–5]: If no input arguments are used, this paper is equivalent to [2], which actually also needed the rewrite system to be left-and-right linear (the erratum of [2] is given in [12]), due to the semantics of logic programs. An extension of [2] to deal with nonright-linear rewrite system is proposed in [13].

If no input arguments are used, predicate symbols have only one argument, and assuming some additional restrictions, the logic program can be viewed as a finite tree automaton (predicate symbols are considered as states), which then generates a regular language. In this particular case, the procedure presented in this paper works as the tree automaton completion of [3-5]. However, [3-5] only need left-linearity, and [3] uses a set of equation *E* as an heuristics for guiding the approximation, whereas our procedure does not because equations do not make sense when working with predicate symbols with several arguments, i.e. with tree-tuples. On the other hand, our procedure always terminate, but [3-5] could also always terminate if a bound for the number of states was fixed.

The completion procedure of [1] computes an over-approximation of the descendants using a context-free tree language defined by an indexed linear tree grammar (ILTG). Actually, ILTGs look like and are equi-expressive with (top-down) pushdown tree automata. The rewrite system is assumed to be left-linear, and the procedure always terminate. Roughly speaking, when rewriting a term t generated by the current grammar (to get the descendants of t), the substitution (which is a match) is stored into the stack. However, to make the stack alphabet finite, substitutions are pruned, which amounts to merge various substitutions. Compared to our procedure, [1] is more automated, because it does not need additional heuristics to guide the approximation. However, it is limited by the use of context-free tree languages. Unfortunately, it is difficult to compare our procedure with that of [1], because they are quite different and use different formalisms.

Other Related Work: The class of tree-tuples whose overlapping coding is recognized by a tree automaton on the product alphabet [14] (called "regular tree relations" by some authors), is strictly included in the class of rational tree relations [15]. The latter is equivalent to the class of non-copying² synchronized languages [16], which is strictly included in the class of synchronized languages.

Context-free tree languages (i.e. without assuming a particular strategy for grammar derivations) [17] are equivalent to OI (outside-in strategy) context-free tree languages, but are incomparable with IO (inside-out strategy) context-free tree languages [18,19]. The IO class (and not the OI one) is strictly included in the class of synchronized-context-free tree languages. The latter is equivalent to the "term languages of hyperedge replacement grammars", which are equivalent to the tree languages definable by attribute grammars [20,21]. However, we prefer to use the synchronized-context-free tree languages, which use the well known formalism of pure logic programming, for its implementation ease.

Much other work computes the descendants in an exact way using regular tree languages (in particular the recent paper [22]). In general the set of descendants is not regular even if the initial set is. Consequently strong restrictions over the rewrite system are needed to get regular descendants, which are not suitable in the framework of protocol or program verification.

2. Preliminaries

Consider a *finite ranked alphabet* $\Sigma = \{a, b, f, g, h, ...\}$ and a set of variables $Var = \{x, y, z, ...\}$. Each symbol $f \in \Sigma$ has a unique arity, denoted by ar(f). The notions of *first-order term*, *position* and *substitution* are defined as usual. Given σ and σ' two substitutions, $\sigma \circ \sigma'$ denotes the substitution such that for any variable $x, \sigma \circ \sigma'(x) = \sigma(\sigma'(x))$. T_{Σ} denotes the set of

² Clause heads are assumed to be linear.

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ground terms (without variables) over Σ . For a unary functional symbol f, $f(f(\dots, f(t)))$ is denoted by $f^n(t)$. For a term t, Var(t) is the set of variables of t, Pos(t) is the set of positions of t. For $p \in Pos(t)$, t(p) is the symbol of $\Sigma \cup Var$ occurring at position p in t, and $t|_p$ is the subterm of t at position p. The term t is *linear* if each variable of t occurs only once in t. The term $t[t']_p$ is obtained from t by replacing the subterm at position p by t'. $PosVar(t) = \{p \in Pos(t) | t(p) \notin Var\}$. Note that if $p \in PosNonVar(t)$, $t|_p = f(t_1, \dots, t_n)$, and $i \in \{1, \dots, n\}$, then p.i is the position of t_i in t. For $p, p' \in Pos(t)$, p < p' means that p occurs in t strictly above p'. Let t, t' be terms, t is more general than σ' (denoted $\sigma \leq \sigma'$) if there exists a substitution ρ s.t. $\rho \circ \sigma = \sigma'$.

A rewrite rule is an oriented pair of terms, written $l \to r$. We always assume that l is not a variable, and $Var(r) \subseteq Var(l)$. A rewrite system R is a finite set of rewrite rules. Ihs stands for left-hand-side, rhs for right-hand-side. The rewrite relation \to_R is defined as follows: $t \to_R t'$ if there exist a position $p \in PosNonVar(t)$, a rule $l \to r \in R$, and a substitution θ s.t. $t|_p = \theta(l)$ and $t' = t[\theta(r)]_p$. \to_R^* denotes the reflexive-transitive closure of \to_R . t' is a descendant of t if $t \to_R^* t'$. If E is a set of ground terms, $R^*(E)$ denotes the set of descendants of elements of E. The rewrite rule $l \to r$ is left (resp. right) linear if l (resp. r) is linear. R is left (resp. right) linear if all its rewrite rules are left (resp. right) linear. R is both left and right linear.

In the following, we consider the framework of *pure logic programming*, and the class of synchronized-context-free treetuple³ languages [10,11], which is presented as an extension of the class of synchronized tree-tuple languages defined by CS-clauses [9,23]. Given a set *Pred* of *predicate* symbols; *atoms*, *goals*, *bodies* and *Horn-clauses* are defined as usual. Note that both *goals* and *bodies* are sequences of atoms. We will use letters *G* or *B* for sequences of atoms, and *A* for atoms. Given a goal $G = A_1, \ldots, A_k$ and positive integers *i*, *j*, we define $G|_i = A_i$ and $G|_{i,j} = (A_i)|_j = t_j$ where $A_i = P(t_1, \ldots, t_n)$. Let *G* be a sequence of atoms, *A* an atom occurring in *G* and *B* a new atom. We denote by $G[A \leftarrow B]$ the replacement of the atom *A* by *B* in *G*.

Definition 1. The tuple of terms (t_1, \ldots, t_n) is flat if t_1, \ldots, t_n are variables. The sequence of atoms *B* is flat if for each atom $P(t_1, \ldots, t_n)$ of *B*, (t_1, \ldots, t_n) is flat. *B* is *linear* if each variable occurring in *B* (possibly at subterm position) occurs only once in *B*. Note that the empty sequence of atoms (denoted by \emptyset) is flat and linear.

A Horn clause $P(t_1, \ldots, t_n) \leftarrow B$ is:

- *empty* if $P(t_1, \ldots, t_n)$ is flat, i.e. $\forall i \in \{1, \ldots, n\}$, t_i is a variable.
- normalized if $\forall i \in \{1, ..., n\}$, t_i is a variable or contains only one occurrence of function-symbol. A program is normalized if all its clauses are normalized.

Example 1. Let *x*, *y*, *z* be variables. The sequence of atoms $P_1(x, y)$, $P_2(z)$ is flat, whereas $P_1(x, f(y))$, $P_2(z)$ is not flat. The clause $P(x, y) \leftarrow Q(x, y)$ is empty and normalized. The clause $P(f(x), y) \leftarrow Q(x, y)$ is normalized whereas $P(f(f(x)), y) \leftarrow Q(x, y)$ is not.

Definition 2. A logic program with modes is a logic program such that a mode-tuple $\vec{m} \in \{I, O\}^n$ is associated to each predicate symbol *P* (*n* is the arity of *P*). In other words, each predicate argument has mode *I* (Input) or *O* (Output).

To distinguish them, output arguments will be covered by a hat.

Notation. Let *P* be a predicate symbol. ArIn(P) is the number of input arguments of *P*, and ArOut(P) is the number of output arguments. Let *B* be a sequence of atoms (possibly containing only one atom). In(B) is the input part of *B*, i.e. the tuple composed of the input arguments of *B*. ArIn(B) is the arity of In(B). $Var^{in}(B)$ is the set of variables that appear in In(B). Out(B), ArOut(B), and $Var^{out}(B)$ are defined in a similar way. We also define $Var(B) = Var^{in}(B) \cup Var^{out}(B)$.

Example 2. Let $B = P(\hat{t_1}, \hat{t_2}, t_3)$, $Q(\hat{t_4}, t_5, t_6)$. Then, $Out(B) = (t_1, t_2, t_4)$ and $In(B) = (t_3, t_5, t_6)$.

Definition 3. Let $B = A_1, ..., A_n$ be a sequence of atoms. We say that $A_j > A_k$ (possibly j = k) if $\exists y \in Var^{in}(A_j) \cap Var^{out}(A_k)$. In other words an input of A_j depends on an output of A_k . We say that B has a *loop* if $A_j > A_j$ for some A_j (>+ is the transitive closure of >).

Example 3. $Q(\hat{x}, s(y)), R(\hat{y}, s(x))$ (where x, y are variables) has a loop because $Q(\hat{x}, s(y)) > R(\hat{y}, s(x)) > Q(\hat{x}, s(y))$.

Definition 4. A Synchronized-Context-Free (S-CF) program Prog is a logic program with modes, whose clauses $H \leftarrow B$ satisfy:

- *In*(*H*).*Out*(*B*) (. is the tuple concatenation) is a linear tuple of variables, i.e. each tuple-component is a variable, and each variable occurs only once,

³ For simplicity, "tree-tuple" is sometimes omitted.

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- and *B* does not have a loop.

A clause of an S-CF program is called S-CF clause.

Example 4. $Prog = \{P(\widehat{x}, y) \leftarrow P(\widehat{s(x)}, y)\}$ is not an S-CF program because In(H).Out(B) = (y, s(x)) is not a tuple of variables. $Prog' = \{P'(\widehat{s(x)}, y) \leftarrow P'(\widehat{x}, s(y))\}$ is an S-CF program because In(H).Out(B) = (y, x) is a linear tuple of variables, and there is no loop in the clause body.

Definition 5. Let *Prog* be an S-CF program. Given a predicate symbol *P* without input arguments, the tree-(tuple) language generated by *P* is $L_{Prog}(P) = \{\vec{t} \in (T_{\Sigma})^{ArOut(P)} | P(\vec{t}) \in Mod(Prog)\}$, where T_{Σ} is the set of ground terms over the signature Σ and Mod(Prog) is the least Herbrand model of *Prog*. $L_{Prog}(P)$ is called *Synchronized-Context-Free language* (*S-CF language*).

Example 5. Let us consider the S-CF program without input arguments $Prog = \{P_1(\widehat{g(x, y)}) \leftarrow P_2(\widehat{x}, \widehat{y}), P_2(\widehat{c(x, y)}), \widehat{c(x', y')}) \leftarrow P_2(\widehat{x}, \widehat{y'}), P_2(\widehat{g}, \widehat{a}) \leftarrow .\}$. The language generated by P_1 is $L_{Prog}(P_1) = \{g(t, t_{sym}) \mid t \in T_{\{c^{\setminus 2}, a^{\setminus 0}\}}\}$, where t_{sym} is the symmetric tree of t (for instance c(c(a, a), a) is the symmetric of c(a, c(a, a))). This language is synchronized, but it is not context-free.

Example 6. $Prog = \{S(\widehat{c(x, y)}) \leftarrow P(\widehat{x}, \widehat{y}, a, b). P(\widehat{f(x)}, \widehat{g(y)}, x', y') \leftarrow P(\widehat{x}, \widehat{y}, h(x'), i(y')). P(\widehat{x}, \widehat{y}, x, y) \leftarrow \}$ is an S-CF program. The language generated by S is $L_{Prog}(S) = \{c(f^n(h^n(a)), g^n(i^n(b))) \mid n \in \mathbb{N}\}$, which is not synchronized (there are vertical dependencies) nor context-free.

S-CF languages are closed under union, intersection, and emptiness is decidable [11]. Emptiness is linear in the number of clauses of the S-CF program. On the other hand, consider a S-CF program Prog'' that computes the intersection of a S-CF program Prog with a regular program Prog'. Let Pred, Pred', Pred'' be the set of predicate symbols of Prog, Prog', Prog'' respectively. A bound for the size of Pred'' is $|Pred''| \leq |Pred|.2^{ArMax(Pred).|Pred'|}$, where ArMax(Pred) is the biggest arity of the elements of Pred.

Definition 6. The clause $H \leftarrow B$ is *non-copying* if the tuple Out(H).In(B) is linear. An S-CF program is *non-copying* if all its clauses are non-copying.

Example 7. The clause $P(\overline{d(x, x)}, y) \leftarrow Q(\widehat{x}, p(y))$ is copying. $P(\overline{c(x)}, y) \leftarrow Q(\widehat{x}, p(y))$ is non-copying.

Remark. An S-CF program without input arguments is actually a CS-program (composed of CS-clauses) [9], which generates a synchronized language.⁴ A non-copying normalized CS-program such that every predicate symbol has only one argument is called *regular program*. It is equivalent to a finite tree automaton. Indeed, clauses are of the form $P_0(f(x_1, ..., x_n)) \leftarrow P_1(\hat{x}_1), ..., P_n(\hat{x}_n)$, which is equivalent to the transition $f(P_1, ..., P_n) \rightarrow P_0$ where $P_0, P_1, ..., P_n$ are considered as states. Consequently it generates a regular tree language. Conversely, every regular tree language can be generated by a regular program.

Given an S-CF program, we focus on two kinds of derivations.

Definition 7. Given an S-CF program *Prog* and a sequence of atoms *G*,

- *G* derives into *G'* by a *resolution* step if there exists a clause⁵ $H \leftarrow B$ in *Prog* and an atom $A \in G$ such that *A* and *H* are unifiable by the most general unifier σ (then $\sigma(A) = \sigma(H)$) and $G' = \sigma(G)[\sigma(A) \leftarrow \sigma(B)]$. It is written $G \sim_{\sigma} G'$. We consider the transitive closure \sim^+ and the reflexive-transitive closure \sim^* of \sim . If $G_1 \sim_{\sigma_1} G_2$ and $G_2 \sim_{\sigma_2} G_3$, we write $G_1 \sim_{\sigma_2 \circ \sigma_1}^* G_3$.
- *G* rewrites into G' (possibly in several steps) if $G \sim_{\sigma}^{*} G'$ s.t. σ does not instantiate the variables of *G*. It is written $G \rightarrow_{\sigma}^{*} G'$.

Example 8. $Prog = \{P(\hat{x_1}, \hat{g(x_2)}) \leftarrow P'(\hat{x_1}, \hat{x_2}). P(\hat{f(x_1)}, \hat{x_2}) \leftarrow P''(\hat{x_1}, \hat{x_2}).\}$, and consider G = P(f(x), y). We have $P(f(x), y) \sim_{\sigma_1} P'(f(x), x_2)$ with $\sigma_1 = [x_1/f(x), y/g(x_2)]$ and $P(f(x), y) \rightarrow_{\sigma_2} P''(x, y)$ with $\sigma_2 = [x_1/x, x_2/y].$

⁴ Initially, synchronized languages were presented using constraint systems (sorts of grammars) [24], and later using logic programs. CS stands for "Constraint System".

⁵ We assume that the clause and *G* have distinct variables.

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In the remainder of the paper, given an S-CF program *Prog* and two sequences of atoms G_1 and G_2 , $G_1 \sim^*_{Prog} G_2$ (resp. $G_1 \rightarrow^*_{Prog} G_2$) also denotes that G_2 can be derived (resp. rewritten) from G_1 using clauses of *Prog*. Note that for any atom *A*, if $A \rightarrow B$ then $A \sim B$. On the other hand, $A \sim_{\sigma} B$ implies $\sigma(A) \rightarrow B$. Consequently, if *A* is ground, $A \sim B$ implies $A \rightarrow B$.

It is well known that resolution is complete.

Theorem 1. Let A be a ground atom. $A \in Mod(Prog)$ iff $A \sim *_{Prog} \emptyset$.

3. Technical lemmas

Before describing in Section 4 our technique for computing non-regular approximations, we need some technical lemmas for proving our results.

Lemma 1. Let t and t' be two terms such that $Var(t) \cap Var(t') = \emptyset$. Suppose that t' is linear. Assuming that t and t' are unifiable, let σ be the most general unifier of t and t'. Then, one has: $\forall x, y : (x, y \in Var(t) \land x \neq y) \Rightarrow Var(\sigma(x)) \cap Var(\sigma(y)) = \emptyset$ and $\forall x : x \in Var(t) \Rightarrow \sigma(x)$ is linear.

For the next lemmas, we introduce two notions allowing the extraction of variables occurring once in a sequence of atoms.

Definition 8. Let *G* be a sequence of atoms. $Var_{Lin}^{in}(G)$ is a tuple of variables occurring in In(G) and not in Out(G), and $Var_{Lin}^{out}(G)$ is a tuple of variable occurring in Out(G) and not in In(G). In both cases, tuples of variables are built in such a way that the number of occurrences of variables is preserved for the concerned variables i.e. if a variable occurs *n* times in $Var_{Lin}^{out}(G)$ (resp. $Var_{Lin}^{out}(G)$) then the same variable occurs *n* times in In(G) (resp. Out(G)).

Example 9. Let $G = P(\widehat{g(f(x', z'))}, y'), Q(\widehat{v'}, g(z'))$. Then $Var_{Lin}^{in}(G) = (y')$ and $Var_{Lin}^{out}(G) = (x', v')$.

Note that for a matter of simplicity, we denote by $x \in Var_{Lin}^{in}(G)$ (resp. $x \in Var_{Lin}^{out}(G)$) that x occurs in the tuple $Var_{Lin}^{in}(G)$ (resp. $Var_{Lin}^{out}(G)$). The following lemma focuses on a property of a sequence of atoms obtained after a resolution step.

Lemma 2. Let Prog be a non-copying S-CF program, and G be a sequence of atoms such that Out(G) is linear, In(G) is linear and G does not contain loops. We assume⁶ that variables occurring in Prog are different from those occurring in G. If $G \sim_{\sigma} G'$, then G' is loop free, $\sigma(Var_{Lin}^{in}(G)).Out(G')$ and $\sigma(Var_{Lin}^{out}(G)).In(G')$ are both linear.

Example 10. Let $Prog = \{P(\widehat{g(x)}, y, z) \leftarrow Q(\widehat{x}, f(y), z)\}$ and $G = P(\widehat{g(f(x'))}, y', z'), R(\widehat{z'})$. Then $G \rightsquigarrow_{\sigma} G'$ with $\sigma = (x/f(x'), y/y', z/z'), G' = Q(\widehat{f(x')}, f(y'), z'), R(\widehat{z'})$. Note that G' is loop free, $\sigma(Var_{Lin}^{in}(G)).Out(G') = (y', f(x'), z')$ is linear, $\sigma(Var_{Lin}^{out}(G)).In(G') = (x', f(y'), z')$ is linear.

Proof. First, we show that $\sigma(Var_{Lin}^{in}(G))$. Out(G') and $\sigma(Var_{Lin}^{out}(G))$. In(G') are linear. Thus, in a second time, we show that G' is loop free.

Suppose that $G \sim_{\sigma} G'$. Thus, there exist an atom A_x in $G = A_1, ..., A_x, ..., A_n$, an S-CF-clause $H \leftarrow B \in Prog$ and the mgu σ such that $\sigma(H) = \sigma(A_x)$ and $G' = \sigma(G)[\sigma(A_x) \leftarrow \sigma(B)]$.

Let $Var_{Iin}^{in}(G) = x_1, \ldots, x_k, \ldots, x_{k+n'}, \ldots, x_m$ built as follows:

- x_1, \ldots, x_{k-1} are the variables occurring in $Var^{in}(A_1, \ldots, A_{k-1})$ and not in $Var^{out}(G)$;
- $x_k, \ldots, x_{k+n'}$ are the variables occurring in $Var^{in}(A_x)$ and not in $Var^{out}(G)$;
- $x_{k+n'+1}, \ldots, x_m$ are variables occurring the atoms $Var^{in}(A_{x+1}, \ldots, A_n)$ and not in $Var^{out}(G)$.

Since In(G) and Out(G) are both linear and σ is the mgu of A_x and H, one has $\sigma(Var_{Lin}^{in}(G)) = x_1, \ldots, x_{k+1}, \sigma(x_k), \ldots, \sigma(x_{k+n'}), x_{k+n'+1}, \ldots, x_m$. Note that the linearity of In(G) involves the linearity of $Var_{Lin}^{in}(G)$. And one can deduce that $\sigma(Var_{Lin}^{in}(G))$ is linear iff the tuple $\sigma(x_k), \ldots, \sigma(x_{k+n'})$ is linear.

By hypothesis, Out(H).In(B) and Out(B).In(H) are both linear.

So, a variable occurring in $Var(H) \cap Var(B)$ is either

- a variable that is in Out(H) and Out(B) or
- a variable that is in In(H) and In(B).

⁶ If it is not the case then variables are relabeled.

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(2)



Fig. 1. Possible forms of H.

A variable occurring in Out(H) and in In(H) does not occur in B. Symmetrically, a variable occurring in Out(B) and in In(B) does not occur in H. Moreover, a variable cannot occur twice in either Out(H) or In(H).

Let us focus on A_x . A_x is linear since it does not contain any loop by hypothesis. Let us study the possible forms of H given in Fig. 1.

Each variable *y* occurring in *B* is:

• either a new variable or

 $x_i, i \in \{$

• a variable occurring once in H and preserving its nature (input or output).

The relation \sim_{Prog} ensures the nature stability of variables i.e.

 $Var(Out(\sigma(B))) \cap Var(In(\sigma(H))) = \emptyset \text{ and}$ (1)

$$Var(In(\sigma(B))) \cap Var(Out(\sigma(H))) = \emptyset$$

Moreover, a consequence of Lemma 1 is that $Out(\sigma(B))$ and $In(\sigma(B))$ are both linear.

Let us study the two possible cases:

(a) since the variables of *H* and those of *G* are distinct and $Var_{Lin}^{in}(G)$ is linear, $\sigma(Var_{Lin}^{in}(G)) = x_1, \ldots, x_{k+1}, \sigma(x_k), \ldots, \sigma(x_{k+n'}), x_{k+n'+1}, \ldots, x_m$ is also linear. Moreover, considering *H* as linear and (1) and (2), a consequence is that

$$\bigcup_{k,\ldots,k+n'\}} Var(\sigma(x_i)) \subseteq \{x_k,\ldots,x_{k+n'}\} \cup Var^{in}(A_x).$$

One can also deduce that $Var^{out}(G') \subseteq Var^{out}(G) \cup (Var^{out}(B))$. Consequently, $Var^{out}(G') \cap Var(\sigma(Var_{Lin}^{in}(G))) = \emptyset$ and the tuple $\sigma(Var_{Lin}^{in}(G)).Out(G')$ is linear iff Out(G') is linear.

- (b) A variable can occur at most twice in *H* but an occurrence of such a variable is necessarily an input variable and the other an output variable. Consequently the unification between A_x and *H* leads to a variable α of $\sigma(Var_{Lin}^{in}(G))$ occurring twice in $\sigma(H)$. But according to the form of *H*, these two occurrences of α do not occur in $\sigma(Var_{Lin}^{in}(G))$ since one of the two occurrences is necessarily at an output position. So $\sigma(Var_{Lin}^{in}(G)) = x_1, \ldots, x_{k+1}, \sigma(x_k), \ldots, \sigma(x_{k+n'}), x_{k+n'+1}, \ldots, x_m$ is a linear tuple. Moreover, *Prog* being a non-copying S-CF program, for any variable x_i , with $i = k, \ldots, k + n'$,
 - if $x_i \in Var(\sigma(x))$ with x a variable occurring twice in H then $Var(\sigma(x_i)) \cap Var^{out}(G') = \emptyset$;
 - if there exists $z \in Var^{out}(A_x)$ s.t. $z \in Var(\sigma(x_i))$ and $z \in Var(\sigma(x))$ with x occurring twice in H then $Var(\sigma(x_i)) \cap Var^{out}(G') = \emptyset$;
 - if there exists $z \in Var^{out}(A_x)$ s.t. $x_i \in Var(\sigma(z))$ and $z \in Var(\sigma(x))$ with x occurring twice in H then $Var(\sigma(x_i)) \cap Var^{out}(G') = \emptyset$;
 - if there exists $x \in Var^{in}(H)$ such that $x \notin Var^{out}(H)$ then one has $Var(\sigma(x_i)) \subseteq \{x_k, \ldots, x_{k+n'}\} \cup Var^{in}(A_x)$. Thus $Var(\sigma(x_i)) \cap Var^{out}(G') = \emptyset$.

Consequently, $\sigma(Var_{lin}^{in}(G)).Out(G')$ is linear iff Out(G') is linear.

Let us now study the linearity of Out(G'). First, let us focus on the case $Out(\sigma(G - A_x))$ where $G - A_x$ is the sequence of atoms *G* for which the atom A_x has been removed. Note that $\sigma(G - A_x) = G' - \sigma(B)$.

Suppose that $Out(G - A_x)$ is not linear. So there exist two distinct variables x and y of G such that $Var(\sigma(x)) \cap Var(\sigma(y)) \neq \emptyset$. Since these variables are concerned by the mgu σ , they are also variables of A_x at input positions as illustrated in Fig. 2. Since these variables are distinct and share the same variable by the application of σ , then there exist two subterms (red and green triangles in Fig. 2) at input positions in H sharing the same variable α . That is impossible since, by definition, for each $H \leftarrow B \in Prog$, one has In(H).Out(B) and Out(H).In(B) both linear.

So, the last possible case for breaking the linearity of Out(G') is that there exist two distinct variables x and y such that x occurs in Out(B), y occurs in $Out(G - A_x)$ and $Var(\sigma(x)) \cap Var(\sigma(y)) \neq \emptyset$. A variable α of $Var(\sigma(x)) \cap Var(\sigma(y))$ is

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Fig. 2. $G - A_x$. (For interpretation of the references to color in this figure, the reader is referred to the web version of this article.)

necessarily a variable of *H*. Since a copy of α is done in the variable *y* and *y* necessarily occurs in A_x at an input position, there is a contradiction. Indeed, it means that the variable α must occur both in Out(H) and In(H) but also in Out(B). Thus, $H \leftarrow B$ is not a non-copying S-CF clause. Consequently, Out(G') is linear.

To conclude, $\sigma(Var_{Lin}^{in}(G)).Out(G')$ is linear. Note that showing that $\sigma(Var_{Lin}^{out}(G)).In(G')$ is linear is similar. The last remaining point to show is that G' does not contain any loops. By construction, $G' = \sigma(G)[\sigma(A_x) \leftarrow \sigma(B)]$. There are three cases to study:

- Suppose there exists a loop occurring in $G' \sigma(B)$. By definition, $G' \sigma(B) = \sigma(A_1), \dots, \sigma(A_{x-1}), \sigma(A_{x+1}), \dots, \sigma(A_m)$. Let us reason on the sequence of atoms *G* where $G = A_i, A_x, A_j$. Note that it can be easily generalized to a sequence of atoms of any size, but for a matter of simplicity, we focus on a significant sequence composed of three atoms. In that case, $G' - \sigma(B) = \sigma(A_i), \sigma(A_j)$. If there exists a loop in $G' - \sigma(B)$ but not in *G* then there are two possibilities (actually three but two of them are exactly symmetric):
 - $A_i \not\geq A_j$ and $A_j \not\geq A_i$: Then σ has generated the loop. So, one can deduce that there exist two variables α and β such that $\alpha \in Var^{in}(\sigma(A_i)) \cap Var^{out}(\sigma(A_j))$, $\beta \in Var^{out}(\sigma(A_i)) \cap Var^{in}(\sigma(A_j))$. Thus, there exist $y \in Var^{out}(A_i)$, $y' \in Var^{in}(A_i)$, $z \in Var^{out}(A_j)$ and $z' \in Var^{in}(A_j)$ such that $\alpha \in Var(\sigma(y')) \cap Var(\sigma(z))$ and $\beta \in Var(\sigma(y)) \cap Var(\sigma(z'))$. Since those four variables are concerned by the mgu, one can deduce that they also occur in A_x . More precisely, according to the linearity of In(G) and Out(G), $y' \in Var^{out}(A_x)$, $y \in Var^{in}(A_x)$, $z \in Var^{in}(A_x)$ and $z' \in Var^{out}(A_x)$. In that case, $A_i \succ A_x$ and $A_x \succ A_i$ because $y' \in Var^{out}(A_x) \cap Var^{in}(A_i)$ and $y \in Var^{out}(A_i) \cap Var^{in}(A_x)$. Consequently, a loop occurs in G. Contradiction.
 - $A_i > A_j$ and $A_j \neq A_i$: Consequently, σ has generated the loop. Since $A_i > A_j$, then there exists a variable y such that $y \in Var^{in}(A_i) \cap Var^{out}(A_j)$. If there exists a loop in $G' \sigma(B)$ then there exists a variable α s.t. $\alpha \in Var^{out}(\sigma(A_i)) \cap Var^{in}(\sigma(A_j))$. So there exist two variables y' and z' with $y' \in Var^{out}(A_i)$ and $z' \in Var^{in}(A_j)$ s.t. $\alpha \in Var(\sigma(y')) \cap Var(\sigma(z'))$. Since those two variables are concerned by the mgu, one can deduce that they also occur in A_x . More precisely, according to the linearity of In(G) and Out(G), $y' \in Var^{in}(A_x)$ and $z' \in Var^{out}(A_x)$. In that case, one has $A_x > A_i$ and $A_j > A_x$ because $y' \in Var^{in}(A_x) \cap Var^{out}(A_i)$ and $z' \in Var^{out}(A_x) \cap Var^{in}(A_j)$. Moreover, by hypothesis, $A_i > A_j$. Consequently, a loop occurs in G because $A_j > A_x > A_i > A_j$. Contradiction.
- A loop cannot occur in $\sigma(B)$: This is a direct consequence of Lemma 1. Indeed, σ is the mgu of A_x which is linear and H. B is constructed from the variables occurring once in H and new variables. Moreover, In(B) and Out(B) are linear and the only variables allowed to appear in both In(B) and Out(B) are necessarily new and then not instantiated by σ . To create a loop in these conditions would require that two different variables α and β instantiated by σ would share the same variable i.e. $Var(\sigma(\alpha)) \cap Var(\sigma(\beta)) \neq \emptyset$. Contradicting Lemma 1.
- Suppose that a loop occurs in G' but neither in $G' \sigma(B)$ nor in $\sigma(B)$: Let G be the sequence of atoms such that $G = A_i, A_x$. In that case, $G' = \sigma(A_i), \sigma(B)$ with σ the mgu of A_x and H. One can extend the schema to any kind of sequence of atoms satisfying the hypothesis of this lemma without loss of generality. We consider B as follows: $B = B_1, \ldots, B_k$. If there exists a loop in G' but neither in $G' - \sigma(B)$ nor in $\sigma(B)$ then there exist B_{k_1}, \ldots, B_{k_n} atoms occurring in B such that $\sigma(A_i) \succ \sigma(B_{k_1}) \succ \ldots \succ \sigma(B_{k_n}) \succ \sigma(A_i)$. So, one can deduce that there exists two variables α and β such that $\alpha \in Var^{in}(\sigma(A_i)) \cap Var^{out}(\sigma(B_{k_1}))$ and $\beta \in Var^{out}(\sigma(A_i)) \cap Var^{out}(\sigma(B_{k_n}))$. Consequently, there exists two variables y, z such that $y \in Var^{in}(A_i), z \in Var^{out}(A_i), \alpha \in Var(\sigma(y))$ and $\beta \in Var(\sigma(z))$. Both variables also occur in A_x . Suppose that y does not occur in A_x . Since σ is the mgu of A_x and H and y not in $Var(A_x), \sigma$ does not instantiate y. Consequently, $\alpha = y$. However, $Var(\sigma(B)) \subseteq Var(H) \cup Var(A_x) \cup Var(B)$. Moreover, the sets of variables occurring in Prog and in G are supposed to be disjointed. So, y cannot occur in $\sigma(B)$ and then the loop in G' does not exist. Thus, y occurs in A_x as well as z. Furthermore, since In(G) and Out(G) are linear, $y \in Var^{out}(A_x)$ and $z \in Var^{in}(A_x)$. Consequently, G contains a loop. Contradicting the hypothesis.

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Lemma 2 can be generalized to several steps.

Lemma 3. Let Prog be a non-copying S-CF program, and G be a sequence of atoms such that Out(G) is linear, In(G) is linear and G does not contain loops. We assume⁷ that variables occurring in Prog are different from those occurring in G. If $G \sim_{\sigma}^{*} G'$, then G' is loop free, $\sigma(Var_{lin}^{in}(G))$. Out(G') and $\sigma(Var_{lin}^{out}(G))$. In(G') are both linear.

Proof. Let $G \sim_{\sigma}^{*} G'$ be rewritten as follows: $G_0 \sim_{\sigma_1} G_1 \ldots \sim_{\sigma_k} G_k$ with $G_0 = G$, $G' = G_k$ and $\sigma = \sigma_k \circ \ldots \circ \sigma_1$. Let P_k be the induction hypothesis defined such that: If $G_0 \sim \sigma G_k$ then

- *G_k* does not contain any loop,
- $\sigma(Var_{Lin}^{in}(G_0)).Out(G_k)$ is linear and $\sigma(Var_{Lin}^{out}(G_0)).In(G_k)$ is linear.

Let us proceed by induction.

- P_0 is trivially true. Indeed, $In(G_0)$ and $Out(G_0)$ are linear. Moreover, for any $x \in Var_{Lin}^{in}(G_0)$ (resp. $x \in Var_{Lin}^{out}(G_0)$), one has $x \notin Var(Out(G_0))$ (resp. $x \notin Var(In(G_0))$). Thus, $Var_{Lin}^{in}(G_0).Out(G_0)$ is linear (resp. $Var_{Lin}^{out}(G_0).In(G_0)$).
- Suppose that P_k is true and $G_k \sim_{\sigma_{k+1}} G_{k+1}$. Since $G_k \sim_{\sigma_{k+1}} G_{k+1}$, there exist $H \leftarrow B \in Prog$ and an atom A_x occurring in G_k s.t. σ_{k+1} is the mgu of A_x and H, and $G_{k+1} = \sigma_{k+1}(G_k)[\sigma_{k+1}(H) \leftarrow \sigma_{k+1}(B)]$. By hypothesis, one has $Out(G_k)$ and $In(G_k)$ linear. Consequently, Lemma 2 can be applied and one obtains that
 - $\sigma(Var_{lin}^{in}(G_k)).Out(G_{k+1})$ is linear,
 - $\sigma(Var_{Lin}^{out}(G_k)).In(G_{k+1})$ is linear and
 - G_{k+1} does not contain any loop.

Moreover, for *Prog* a non-copying S-CF program, if $G_i \sim_{\sigma_{i+1}} G_{i+1}$ then one has: For any variable *x*, *y*, if $x \in Var_{lin}^{ln}(G_i)$ and $y \in Var(\sigma_{i+1}(x))$ then $y \in Var_{Lin}^{in}(G_{i+1})$ or $y \notin Var(G_{i+1})$. So, one can conclude that given $\sigma_k \circ \ldots \circ \sigma_1(Var_{Lin}^{in}(G_0))$, for any variable $x \in Var_{Lin}^{in}(G_0)$, for any $y \in Var(\sigma_k \circ \ldots \circ \sigma_1(x))$, either $y \in Var_{Lin}^{in}(G_k)$ or $y \notin Var(G_k)$. Let us study the variables of $\bigcup_{y \in Var_{lin}^{in}(G_0)} (Var(\sigma_k \circ \ldots \circ \sigma_1(y)))$.

- For any variable x s.t. $x \in \bigcup_{y \in Var_{in}^{in}(G_0)} (Var(\sigma_k \circ \ldots \circ \sigma_1(y))) \setminus Var(G_k), x \notin Var(G_{k+1})$. Indeed, an already-used variable cannot be reused for relabeling variables of Prog while the reduction process. Moreover such variables are not instantiated by σ_{k+1} since the mgu σ_{k+1} of A_x and H only concerns variables of $Var(H) \cup Var(A_x)$. So, for any variable y in $Var(\sigma_k \circ \ldots \circ \sigma_1(y)) \setminus Var(G_k)$, one has $\sigma_{k+1}(y) = y$ and $y \notin Var(G_{k+1})$. Consequently, for any variable y in $Var(\sigma_{k+1} \circ \sigma_k \circ \ldots \circ \sigma_1(y))) \setminus Var(G_k), y \notin Var(G_{k+1}).$
- For any variable x s.t. $x \in \bigcup_{y \in Var_{Lin}^{in}(G_0)} (Var(\sigma_k \circ \ldots \circ \sigma_1(y))) \cap Var(G_k)$, one can deduce that $x \in Var_{Lin}^{in}(G_k)$.

Since $\sigma_{k+1}(Var_{Lin}^{in}(G_k))$. $Out(G_{k+1})$ is linear, therefore one can deduce that for any $y \in \bigcup_{v \in Var_{Lin}^{in}(G_0)}(Var(\sigma_k \circ \ldots \circ (\sigma_k \circ (\sigma_k \circ \ldots \circ (\sigma_k \circ (\sigma_k$ $\sigma_1(y))) \cap Var(G_k), Var(\sigma_{k+1} \circ \sigma_k \circ \ldots \circ \sigma_1(y)) \cap Var(Out(G_{k+1})) = \emptyset.$

So, one has $\sigma_{k+1} \circ \sigma_k \circ \ldots \circ \sigma_1(Var_{Lin}^{in}(G_k))$. $Out(G_{k+1})$ is linear. The proof of $\sigma(Var_{Lin}^{out}(G_k))$. $In(G_{k+1})$ is in some sense symmetric. To conclude, considering the hypothesis of Lemma 2, one has: If $G \sim_{\sigma}^{*} G'$, then

- G' is loop free;
- $\sigma(Var_{Lin}^{in}(G)).Out(G')$ is linear; $\sigma(Var_{Lin}^{out}(G)).In(G')$ is linear.

4. Computing descendants

Let us first present the main ideas.

Example 11. Let $R = \{f(x) \rightarrow g(h(x))\}$ and $I = \{p^n(f(s^n(a))) \mid n \in \mathbb{N}\}$ generated by Predicate P_0 in the S-CF program Prog = Program Prog = Program Prog = Program $\{Q(\widehat{a}) \leftarrow P_0(\widehat{x}) \leftarrow P_1(\widehat{x}, y), Q(\widehat{y}), P_1(\widehat{p}(\widehat{x}), y) \leftarrow P_1(\widehat{x}, s(y)), P_1(\widehat{f}(\widehat{x}), x) \leftarrow \}. \text{ Note that } \mathbb{R}^*(I) = I \cup \{p^n(g(h(s^n(a)))) \mid n \in \mathbb{N}\}.$

To simulate the rewrite step $f(s^n(a)) \rightarrow g(h(s^n(a)))$, we consider the rewrite-rule left-hand-side f(x). We can see that: $P_1(\widehat{f(x)}, y) \sim_{[Prog, \theta = (x/y)]} \emptyset$ and $\theta(P_1(\widehat{f(x)}, y)) = P_1(\widehat{f(y)}, y) \rightarrow_R P_1(\widehat{g(h(y))}, y)$. Then the clause $P_1(\widehat{g(h(y))}, y) \leftarrow$ is called *critical pair*.⁸ This critical pair is not *convergent* (in *Prog*) because $P_1(\widehat{g(h(y))}, y) \not\rightarrow_{Prog}^* \emptyset$. To get the descendants, the critical pairs should be convergent. Let $Prog' = Prog \cup \{P_1(g(h(y)), y) \leftarrow\}$. Now the critical pair is convergent in Prog', and note that the predicate P_0 of Prog' generates $R^*(I)$. Adding critical pairs into the S-CF program is called *completion*.

If it is not the case then variables are relabeled.

⁸ In former work, a critical pair was a pair. Here it is a clause since we use logic programs.

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For technical reasons,⁹ we consider only normalized S-CF programs, and *Prog'* is not normalized. However, the critical pair can be normalized using a new predicate symbol, and replaced by the following normalized clauses $P_1(\widehat{g(x)}, y) \leftarrow P_2(\widehat{x}, y)$. $P_2(\widehat{h(y)}, y) \leftarrow$. This is the role of Function norm in the completion algorithm below.

In general, adding a critical pair (after normalizing it) into the S-CF program may create new critical pairs, and the completion process may not terminate. To force termination, two bounds *predicate-limit* and *arity-limit* are fixed. If *predicate-limit* is reached, Function norm should re-use existing predicates instead of creating new ones. If a new predicate symbol is created whose arity¹⁰ is greater than *arity-limit*, then this predicate has to be cut by Function norm into several predicates whose arities do not exceed *arity-limit*. On the other hand, for a fixed¹¹ S-CF program, the number of critical pairs may be infinite. Function removeCycles modifies some clauses so that the number of critical pairs is finite. *Strong coherence* is technical and will be defined later. It is used to prove the results. However, if the initial program *Prog* is regular or is a CS-program, i.e. *Prog* does not have input arguments, then the strong coherence property is automatically satisfied.

Definition 9 (*comp*). Let *arity-limit* and *predicate-limit* be positive integers. Let *R* be a linear rewrite system, and *Prog* be a finite, normalized and non-copying S-CF program strongly coherent with *R*. The completion process is defined by:

```
Function \operatorname{comp}_R(\operatorname{Prog})

\operatorname{Prog} = \operatorname{removeCycles}(\operatorname{Prog})

while there exists a non-convergent critical pair H \leftarrow B in \operatorname{Prog} do

\operatorname{Prog} = \operatorname{removeCycles}(\operatorname{Prog} \cup \operatorname{norm}_{\operatorname{Prog}}(H \leftarrow B))

end while

return \operatorname{Prog}
```

Critical pairs and strong coherence are defined in Section 4.1, and Theorem 2 shows closure under rewriting when all critical pairs are convergent. Theoretical notions and results are presented in Section 4.2 in order to define Function removeCycles. Section 4.3 speaks about normalization, and the final result, i.e. we get an over-approximation of the descendants, is given in Section 4.4.

4.1. Critical pairs

The notion of critical pair is the heart of our technique. Indeed, it allows us to add S-CF clauses into the current S-CF program in order to cover rewriting steps.

Definition 10. Let *Prog* be a non-copying S-CF program and $l \rightarrow r$ be a left-linear rewrite rule. Consider distinct variables x_1, \ldots, x_n such that $Var(l) \cap \{x_1, \ldots, x_n\} = \emptyset$. If there are *P* and *k* s.t. the k^{th} argument of *P* is an output, and $P(x_1, \ldots, x_{k-1}, l, x_{k+1}, \ldots, x_n) \sim_{\theta}^{+} G$ where¹²

- 1. resolution steps are applied only on atoms whose output is not flat,
- 2. Out(G) is flat and
- 3. the clause $P(t_1, \ldots, t_n) \leftarrow B$ used in the first step of this derivation satisfies t_k is not a variable¹³

then the clause $\theta(P(x_1, \ldots, x_{k-1}, r, x_{k+1}, \ldots, x_n)) \leftarrow G$ is called *critical pair*. if θ does not instantiate the variables of $In(P(x_1, \ldots, x_{k-1}, l, x_{k+1}, \ldots, x_n))$ then the critical pair is said *strict*.

Example 12. Let *Prog* be the S-CF program defined by:

 $Prog = \{P(\widehat{s(x)}) \leftarrow Q(\widehat{x}, a). \quad Q(\widehat{f(x)}, y) \leftarrow Q(\widehat{x}, g(y)). \quad Q(\widehat{x}, x) \leftarrow .\} \text{ and consider } R = \{f(f(x)) \rightarrow h(x)\}.$ Note that $L(P) = \{s(f^n(g^n(a))) \mid n \in \mathbb{N}\}.$

We have $Q(\widehat{f(f(x))}, y) \rightsquigarrow Q(\widehat{f(x)}, g(y)) \rightsquigarrow Q(\widehat{x}, g(g(y)))$.

Since $Out(Q(\widehat{x}, g(g(y))))$ is flat, this generates the strict critical pair $Q(\widehat{h(x)}, y) \leftarrow Q(\widehat{x}, g(g(y)))$.

The following lemma is very important for completion. It shows that when the completion process adds a strict critical pair into the current S-CF program, the resulting program is still S-CF.

Lemma 4. A strict critical pair is an S-CF clause. In addition, if $l \rightarrow r$ is right-linear, a strict critical pair is a non-copying S-CF clause.

⁹ Critical pairs are computed only at root positions.

¹⁰ The number of arguments.

¹¹ I.e. without adding new clauses in the S-CF program.

 $^{^{12}}$ Here, we do not use a hat to indicate output arguments because they may occur anywhere depending on P.

¹³ In other words, the overlap of *l* on the clause head $P(t_1, \ldots, t_n)$ is done at a non-variable position.

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Proof. Let $G_0 = P(x_1, ..., x_{k-1}, l, x_{k+1}, ..., x_n)$. Since *l* is linear, G_0 is linear and $Var_{Lin}^{in}(G_0) = In(G_0)$. From Lemma 3, $\theta(In(G_0)).Out(G)$ is linear and *G* is loop-free. Note that $In(G_0)$ and Out(G) are tuples of variables. Since the critical pair is strict, we deduce that θ does not instantiate the variables of $In(G_0)$, then $\theta(In(G_0)).Out(G)$ is a linear tuple of variables. Consequently, a strict critical pair is an S-CF clause.

Since G_0 is linear, $Var_{Lin}^{out}(G_0) = Var^{out}(G_0)$. Thus, from Lemma 3, $\theta(Out(G_0)).In(G)$ is linear. And since r is linear, the critical pair is a non-copying clause. \Box

Definition 11. A critical pair $H \leftarrow B$ is said convergent if $H \rightarrow_{Prog}^{*} B$.

The critical pair of Example 12 is not convergent.

Let us recall that the completion procedure is based on adding the non-convergent critical pairs into the program. In order to preserve the nature of the S-CF program, the computed non-convergent critical pairs are expected to be strict. Moreover, since critical pairs are only computed using output arguments, each reducible¹⁴ symbol should not occur in an input argument. So we define a sufficient condition on *R* and *Prog* called *strong coherence*.

Definition 12. Let *R* be a rewrite system. We consider the smallest set of *consuming* symbols, recursively defined by: $f \in \Sigma$ is *consuming* if there exists a rewrite rule $f(t_1, \ldots, t_n) \rightarrow r$ in *R* s.t. some t_i is not a variable, or *r* contains at least one consuming symbol.

The S-CF program *Prog* is strongly coherent with *R* if:

- 1) for all $l \rightarrow r \in R$, the top-symbol of *l* does not occur in input arguments of *Prog*,
- 2) and no consuming symbol occurs in clause-heads having input arguments.

Note that a CS-program (no input arguments) is strongly coherent with any rewrite system.

In $R = \{g(s(y)) \rightarrow h(y)\}$, g is consuming. Thus $Prog = \{P(\overline{g(x)}, x) \leftarrow .\}$ is not strongly coherent with R because item 2 is not satisfied. We have $P(\overline{g(s(y))}, z) \sim_{[x/s(y), z/s(y)]} \emptyset$, which generates the critical pair $P(h(y), s(y)) \leftarrow$. This critical pair is not a S-CF clause.

Lemma 5. If Prog is a normalized S-CF program strongly coherent with R, then every critical pair cp is strict, and $Prog \cup \{cp\}$ is strongly coherent with R.

Proof. Consider $f(\vec{s}) \rightarrow r \in R$ (\vec{s} is a tuple of terms), and assume that

$$P(\widehat{\vec{x_1}}, \widehat{f(\vec{s})}, \widehat{\vec{x_2}}, \vec{z}) \sim_{[P(\widehat{t_1}, \widehat{f(\vec{u})}, \widehat{t_2}, \vec{v}) \leftarrow B, \theta]} G \sim_{\sigma}^* G'$$

such that Out(G') is flat, $\vec{x_1}, \vec{x_2}, \vec{z}, \vec{u}, \vec{v}$ are tuples of distinct variables and $\vec{t_1}, \vec{t_2}$ are tuples of terms (however \vec{v} may share some variables with $\vec{t_1}.\vec{u}.\vec{t_2}$). This derivation generates the critical pair $(\sigma \circ \theta)(P(\vec{x_1}, \hat{r}, \vec{x_2}, \vec{z})) \leftarrow G'$.

If $l \to r$ is consuming then *P* has no input arguments, i.e. \vec{z} and \vec{v} do not exist. Therefore $\sigma \circ \theta$ cannot instantiate the input variables of *P*, hence the critical pair is strict.

Otherwise \vec{s} is a linear tuple of variables, and $(x/t \text{ means that the variable } x \text{ is replaced by } t) \theta = (\vec{v}/\vec{z}) \circ (\vec{x_1}/\vec{t_1}, \vec{s}/\vec{u}, \vec{x_2}/\vec{t_2})$, which does not instantiate \vec{z} nor the output variables of B. Moreover Out(B) is flat, then $Out(G) = Out(\theta B)$ is flat. Thus G' = G and the critical pair is $P(\theta \vec{x_1}, \theta \vec{r}, \theta \vec{x_2}, \vec{z}) \leftarrow G$, which is strict.

About strong coherence, the function symbols occurring in the input arguments of the critical pair come from the input arguments of *Prog*. Therefore condition 1 of Definition 12 is satisfied.

On the other hand, suppose that *P* has input arguments. So *f* is not consuming, then \vec{s} is a linear tuple of variables. Consequently the derivation contains only one step, i.e. G' = G. Then \vec{s} is instantiated by variables, and $\theta(\vec{x_1}) = \vec{t_1}, \theta(\vec{x_2}) = \vec{t_2}$, where $\vec{t_1}$ and $\vec{t_2}$ do not contain consuming symbols. Moreover *r* does not contain consuming symbols (otherwise *f* would be consuming). Therefore condition 2 of Definition 12 is satisfied. \Box

So, we come to our main result that ensures to get the rewriting closure when every computable critical pair is convergent.

Theorem 2. Let *R* be a linear rewrite system, and Prog be a non-copying normalized S-CF program strongly coherent with *R*. If all strict critical pairs are convergent, then for every predicate symbol *P* without input arguments, L(P) is closed under rewriting by *R*, i.e. $(\vec{t} \in L(P) \land \vec{t} \rightarrow R^*, \vec{t'}) \implies \vec{t'} \in L(P)$.

¹⁴ I.e. the top symbol of the left-hand-side of some rewrite rule.

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The proof is very technical. To illustrate the proof, consider Example 12 again, except that the critical pair $Q(h(x), y) \leftarrow Q(\hat{x}, g^2(y))$ is added into the S-CF program. Now

$$Prog = \{ P(\widehat{s(x)}) \leftarrow Q(\widehat{x}, a). \ Q(\widehat{f(x)}, y) \leftarrow Q(\widehat{x}, g(y)). \ Q(\widehat{x}, x) \leftarrow . \ Q(\widehat{h(x)}, y) \leftarrow Q(\widehat{x}, g^2(y)) \}$$

and $R = \{f^2(x) \rightarrow h(x)\}$. So there is only one critical pair, which is convergent thanks to the last clause of *Prog*.

 $s(f^2(g^2(a))) \in L(P)$ because the atom $A = P(s(f^2(g^2(a)))) \in Mod(Prog)$, moreover $A = P(s(f^2(g^2(a)))) \rightarrow_R A' = P(s(h(g^2(a))))$. Since $A \in Mod(Prog)$, we have $A \sim \emptyset$.

More precisely:

$$A = P(s(f^2(g^2(a)))) \rightsquigarrow A'' = Q(\widehat{f^2(g^2(a))}, a) \rightsquigarrow Q(\widehat{f(g^2(a))}, g(a)) \rightsquigarrow Q(\widehat{g^2(a)}, g^2(a)) \rightsquigarrow \emptyset$$

Using the notations of the proof, we have C = s, $l = f^2(x)$, r = h(x), $\sigma = (x/g^2(a))$, $\sigma' = (x/g^2(a), y/a)$. Thus $A'' = Q(\widehat{\sigma(l)}, a) = \sigma'(Q(\widehat{l}, y))$.

On the other hand, since Prog is non-copying, we have

$$A' = P(s(h(g^2(a)))) \rightsquigarrow Q(h(g^2(a)), a) = Q(\sigma(r), a) = \sigma'(Q(h(x), y))$$

where $Q(\widehat{h(x)}, y)$ is the head of the critical pair. Since the critical pair is convergent, we have

$$A' \sim \sigma'(Q(\widehat{h(x)}, y)) \sim \sigma'(Q(\widehat{x}, g^2(y))) = Q(\widehat{g^2(a)}, g^2(a)) \sim \emptyset$$

Therefore $A' \in Mod(Prog)$, hence $s(h(g^2(a))) \in L(P)$.

Proof of Theorem 2. Let $A \in Mod(Prog)$ s.t. $A \to_{l \to r} A'$. Then $A|_i = C[\sigma(l)]$ for some $i \in \mathbb{N}$ and $A' = A[i \leftarrow C[\sigma(r)]$.

Since resolution is complete, $A \sim^* \emptyset$. Since *Prog* is normalized, resolution consumes symbols of *C* one by one. Since *Prog* is coherent with *R*, the top symbol of *l* cannot be generated as an input: it is either consumed in an output argument, or the whole $\sigma(l)$ disappears thanks to an output argument. Consequently $G_0 = A \sim^* G_k \sim^* \emptyset$ and there exists an atom $A'' = P(t_1, \ldots, t_n)$ in G_k and an output argument *j* s.t. $t_j = \sigma(l)$, i.e. $A \sim^* G_k[A'' = P(t_1, \ldots, \sigma(l), \ldots, t_n)]$, and along the step $G_k \sim G_{k+1}$ the top symbol of $\sigma(l)$ is consumed or $\sigma(l)$ disappears entirely. On the other hand, $A' \sim^* G_k[A'' \leftarrow P(t_1, \ldots, \sigma(r), \ldots, t_n)]$ since *Prog* is non-copying.

If $t_j = \sigma(l)$ disappears entirely, it can be replaced by any term, then $A' \sim^* G_k[A'' \leftarrow P(t_1, ..., \sigma(r), ..., t_n)] \sim^* \emptyset$, hence $A' \in Mod(Prog)$. Otherwise the top symbol of $\sigma(l)$ is consumed along $G_k \sim G_{k+1}$. Consider new variables $x_1, ..., x_n$ such that $\{x_1, ..., x_n\} \cap Var(l) = \emptyset$, and let us define the substitution σ' by $\forall i \in \{1, ..., n\}$, $\sigma'(x_i) = t_i$ and $\forall x \in Var(l), \sigma'(x) = \sigma(x)$. Then $\sigma'(P(x_1, ..., x_{j-1}, l, x_{j+1}, ..., x_n)) = A''$, and according to resolution properties $P(x_1, ..., l, ..., x_n) \sim^*_{\theta} \emptyset$ and $\theta \leq \sigma'$. This derivation can be decomposed into: $P(x_1, ..., l, ..., x_n) \sim^*_{\theta_1} G' \sim_{\theta_2} G \sim^*_{\theta_3} \emptyset$ where $\theta = \theta_3 \circ \theta_2 \circ \theta_1$, and s.t. Out(G') is not flat and Out(G) is flat.¹⁵

The derivation $P(x_1, \ldots, l, \ldots, x_n) \sim_{\theta_1}^* G' \sim_{\theta_2} G$ can be commuted into: $P(x_1, \ldots, l, \ldots, x_n) \sim_{\gamma_1}^* B' \sim_{\gamma_2} B \sim_{\gamma_3}^* G$ s.t. Out(B) is flat, Out(B') is not flat, and within $P(x_1, \ldots, l, \ldots, x_n) \sim_{\gamma_1}^* B' \sim_{\gamma_2} B$ resolution is applied only on atoms whose output is not flat, and we have $\gamma_3 \circ \gamma_2 \circ \gamma_1 = \theta_2 \circ \theta_1$. Then $\gamma_2 \circ \gamma_1(P(x_1, \ldots, r, \ldots, x_n)) \leftarrow B$ is a critical pair. By hypothesis, it is convergent, then $\gamma_2 \circ \gamma_1(P(x_1, \ldots, r, \ldots, x_n)) \rightarrow^* B$. Note that $\gamma_3(B) \rightarrow^* G$ and recall that $\theta_3 \circ \gamma_3 \circ \gamma_2 \circ \gamma_1 = \theta_3 \circ \theta_2 \circ \theta_1 = \theta$. Then $\theta(P(x_1, \ldots, r, \ldots, x_n)) \rightarrow^* \theta_3(G) \rightarrow^* \emptyset$, and since $\theta \leq \sigma'$ we get $P(t_1, \ldots, \sigma(r), \ldots, t_n) = \sigma'(P(x_1, \ldots, r, \ldots, x_n)) \rightarrow^* \emptyset$. Thus $A' \sim^* G_k[A'' \leftarrow P(t_1, \ldots, \sigma(r), \ldots, t_n)] \sim^* \emptyset$, hence $A' \in Mod(Prog)$.

By trivial induction, the proof can be extended to the case of several rewrite steps. \Box

4.2. Ensuring finitely many critical pairs

The following example illustrates a situation where the number of critical pairs is infinite for a given S-CF program.

Example 13. Let $f(c(x), y) \to d(y)$ be a rewrite rule, and $\{P_0(\widehat{f(x, y)}) \leftarrow P_1(\widehat{x}, \widehat{y}), P_1(\widehat{c(x)}, \widehat{y}) \leftarrow P_1(\widehat{x}, \widehat{y}), P_1(\widehat{c(x)}, \widehat{y}) \leftarrow P_2(\widehat{x}, \widehat{y}), P_2(\widehat{a}, \widehat{a}) \leftarrow .\}$ be an S-CF program¹⁶ Then $P_0(\widehat{f(c(x), y)}) \to P_1(\widehat{c(x)}, \widehat{y}) \to y_{/s(y)}, P_1(\widehat{c(x)}, \widehat{y}) \to y_{/s(y)}, \dots, P_1(\widehat{c(x)}, \widehat{y}) \to P_2(\widehat{x}, \widehat{y})$. Resolution is applied only on non-flat atoms and the last atom obtained by this derivation is flat. The composition of substitutions along this derivation gives $y/s^n(y)$ for some $n \in \mathbb{N}$. There are infinitely many such derivations, which generates infinitely many critical pairs of the form $P_0(\widehat{d(s^n(y))}) \leftarrow P_2(\widehat{x}, \widehat{y})$.

This is annoying since the completion process introduced in Definition 9 needs to compute all critical pairs. This is why we define sufficient conditions to ensure that a given finite S-CF program has finitely many critical pairs.

¹⁵ Since \emptyset is flat, a goal having a flat output can always be reached, i.e. in some cases $G = \emptyset$.

¹⁶ Note that $L(P_0) = \{f(c(a), s^n(a)) \mid n \in \mathbb{N}\}$ is a regular language, whereas the S-CF program (which is also a CS-program) is not regular. If it were regular, there would be finitely many critical pairs.

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Definition 13. Prog is *empty-recursive* if there exist a predicate symbol P and two tuples $\vec{x} = (x_1, \dots, x_n), \ \vec{y} = (y_1, \dots, y_k)$ composed of distinct variables s.t. $P(\hat{\vec{x}}, \vec{y}) \sim_{\sigma}^{+} A_1, \dots, P(\hat{\vec{x'}}, \vec{t'}), \dots, A_k$ where $\vec{x'} = (x'_1, \dots, x'_n)$ is a tuple of variables and there exist *i*, *j* s.t. $x'_i = \sigma(x_i)$ and $\sigma(x_j)$ is not a variable and $x'_j \in Var(\sigma(x_j))$.

Example 14. Let *Prog* be the S-CF program defined as follows: $Prog = \{P(\widehat{a}, \widehat{b}) \leftarrow P(\widehat{x'}, \widehat{s(y')}) \leftarrow P(\widehat{x'}, \widehat{y'})\}$. From $P(\widehat{x}, \widehat{y})$, one can obtain the following derivation: $P(\hat{x}, \hat{y}) \sim_{[x/x', y/s(y')]} P(\hat{x'}, \hat{y'})$. Consequently, Prog is empty-recursive since $\sigma =$ $[x/x', y/s(y')], x' = \sigma(x)$ and y' is a variable of $\sigma(y) = s(y')$.

The following lemma shows that the nonempty-recursiveness of an S-CF program is sufficient to ensure the finiteness of the number of critical pairs.

Lemma 6. Let Prog be a normalized S-CF program. If Prog is not empty-recursive, then the number of critical pairs is finite.

Remark. Note that the S-CF program of Example 13 is normalized and has infinitely many critical pairs.

However it is empty-recursive because $P_1(\widehat{x}, \widehat{y}) \sim_{[x/x', y/s(y')]} P_1(\widehat{x'}, \widehat{y'})$.

Proof. By contrapositive. Let us suppose there exist infinitely many critical pairs. So there exist P_1 and infinitely many derivations of the form

- (i): $P_1(x_1, \ldots, x_{k-1}, l, x_{k+1}, \ldots, x_n) \sim_{\alpha}^* G' \sim_{\theta} G$ (the number of steps is not bounded). As the number of predicates is finite and every predicate has a fixed arity, there exists a predicate P_2 and a derivation of the form
- (ii): $P_2(t_1, \ldots, t_p) \sim_{\sigma}^{k} G_1'', P_2(t_1', \ldots, t_p'), G_2''$ (with k > 0) included in some derivation of (i), strictly before the last step, such that:
 - 1. $Out(G''_1)$ and $Out(G''_2)$ are flat and the derivation from $P_2(t_1, \ldots, t_p)$ can be applied on $P_2(t'_1, \ldots, t'_p)$ again, which gives rise to an infinite derivation.
 - 2. σ is not empty and there exists a variable x in $P_2(t_1, \ldots, t_p)$ such that $\sigma(x) = t$ and t is not a variable and contains a variable y that occurs in $P_2(t'_1, \ldots, t'_p)$. Otherwise $\sigma \circ \ldots \circ \sigma$ would always be a variable renaming and there would be finitely many critical pairs.
 - 3. There is at least one non-variable term (let t_i) in output arguments of $P_2(t_1, \ldots, t_p)$ (due to the definition of critical pairs) such that $t'_i = t_j$.¹⁷ As we use an S-CF clause in each derivation step, the output argument t'_i matches a variable (output argument) in the body of the last clause used in (ii). As $t'_i = t_j$, the output argument t_j matches a variable (output argument) in head of the first clause used in (ii). So, for each variable x occurring in the nonvariable output terms of P_2 , we have $\sigma(x) = x$.
 - 4. From the previous item, we deduce that the variable x found in item 2 is one of the terms t_1, \ldots, t_p , say t_k . We can assume that y is t'_k . t_k is an output argument of P_2 because it matches a non-variable and only output arguments are non-variable in the head of S-CF clause.

If in derivation (*ii*) we replace all non-variable output terms by new variables, we obtain a new derivation¹⁸ (*iii*): $P_2(x_1, \ldots, x_n, t_{n+1}, \ldots, t_p) \sim_{\sigma'}^k G_1''', P_2(x_1', \ldots, x_n', t_{n+1}', \ldots, t_p'), G_2'''$ and there exists *i*, *k* (in {1,...n}) such that $\sigma'(x_i) = x'_i$ (at least one non-variable term (in output arguments) in the (ii) derivation), and $\sigma'(x_k) = t_k$, x'_k is a variable of t_k . We conclude that Prog is empty-recursive. \Box

Deciding the empty-recursiveness of an S-CF program seems to be a difficult problem (undecidable?). Nevertheless, we propose a sufficient syntactic condition to ensure that an S-CF program is not empty-recursive.

Definition 14. The S-CF clause $P(\hat{t}_1,\ldots,\hat{t}_n,x_1,\ldots,x_k) \leftarrow A_1,\ldots,Q(\ldots),\ldots,A_m$ is pseudo-empty over Q if there exist i, j such that

- *t_i* is a variable,
- and t_i is not a variable,
- and $\exists x \in Var(t_i), x \neq t_i \land \{x, t_i\} \subseteq VarOut(Q(\ldots)).$

Roughly speaking, when making a resolution step issued from the following flat atom $P(\hat{y}_1, \ldots, \hat{y}_n, z_1, \ldots, z_k)$, the variable y_i is not instantiated, and y_i is instantiated by something that is synchronized with y_i (in Q(...)).

 $^{1^7}$ This property does not necessarily hold as soon as P_2 is reached within (*ii*). We may have to consider further occurrences of P_2 so that each required term occurs in the required argument, which will necessarily happen because there are only finitely many permutations.

¹⁸ Without loss of generality, we can consider that the output arguments (at least two) are the first arguments of P_2 .

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The S-CF clause $H \leftarrow B$ is pseudo-empty if there exists some Q s.t. $H \leftarrow B$ is pseudo-empty over Q. The S-CF clause: $P(\hat{t_1}, \dots, \hat{t_n}, x_1, \dots, x_{n'}) \leftarrow A_1, \dots, Q(\hat{y_1}, \dots, \hat{y_k}, s_1, \dots, s_{k'}), \dots, A_m$ is empty over Q if for all y_i , there exists j such that $t_j = y_i$ or $y_i \notin Var(P(\hat{t_1}, \dots, \hat{t_n}, x_1, \dots, x_{n'}))$.

Example 15. The S-CF clause $P(\hat{x}, f(\hat{x}), \hat{z}) \leftarrow Q(\hat{x}, \hat{z})$ is both pseudo-empty (thanks to the second and the third argument of *P*) and empty over *Q* (thanks to the first and the third argument of *P*).

Definition 15. Using Definition 14, let us define two relations over predicate symbols.

- $P_1 \succeq_{Prog} P_2$ if there exists in *Prog* a clause empty over P_2 of the form $P_1(...) \leftarrow A_1, ..., P_2(...), ..., A_n$. The reflexive-transitive closure of \succeq_{Prog} is denoted by \succeq_{Prog}^* .
- transitive closure of \geq_{Prog} is denoted by \geq_{Prog}^* . • $P_1 >_{Prog} P_2$ if there exist in *Prog* predicates P'_1 , P'_2 s.t. $P_1 \geq_{Prog}^* P'_1$ and $P'_2 \geq_{Prog}^* P_2$, and a clause pseudo-empty over P'_2 of the form $P'_1(...) \leftarrow A_1, ..., P'_2(...), ..., A_n$. The transitive closure of $>_{Prog}$ is denoted by $>_{Prog}^+$.

Prog is *cyclic* if there exists a predicate *P* s.t. $P >_{Prog}^{+} P$.

Example 16. Let $\Sigma = \{f^{\setminus 1}, h^{\setminus 1}, a^{\setminus 0}\}$. Let Prog be the S-CF program such that $Prog = \{P(\widehat{x}, \widehat{h(y)}, \widehat{f(z)}) \leftarrow Q(\widehat{x}, \widehat{z}), R(\widehat{y})$. $Q(\widehat{x}, \widehat{g(y, z)}) \leftarrow P(\widehat{x}, \widehat{y}, \widehat{z}). Q(\widehat{a}, \widehat{a}) \leftarrow . R(\widehat{a}) \leftarrow .\}$. One has $P >_{Prog} Q$ and $Q >_{Prog} P$. Thus, Prog is cyclic.

The lack of cycles is the key point of our technique since it ensures the finiteness of the number of critical pairs.

Lemma 7. If Prog is not cyclic, then Prog is not empty-recursive, consequently the number of critical pairs is finite.

Proof. By contrapositive. Suppose that *Prog* is empty recursive. It exists *P* s.t. $P(\widehat{x_1}, ..., \widehat{x_n}, y_1, ..., y_n) \rightsquigarrow_{\sigma}^+ A_1, ..., P(\widehat{x'_1}, ..., \widehat{x'_n}, t'_1, ..., t'_{n'}), ..., A_k$ where $x'_1, ..., x'_n$ are variables and there exist *i*, *j* s.t. $x'_i = \sigma(x_i)$ and $\sigma(x_j)$ is not a variable and $x'_j \in Var(\sigma(x_j))$. We can extract from the previous derivation the following derivation which has *p* steps ($p \ge 1$):

$$P(\widehat{x_{1}}, \dots, \widehat{x_{n}}, y_{1}, \dots, y_{n'}) = Q^{0}(\widehat{x_{1}}, \dots, \widehat{x_{n}}, y_{1}, \dots, y_{n'}) \sim_{\alpha_{1}} B^{1}_{1} \dots Q^{1}(\widehat{x_{1}^{1}}, \dots, \widehat{x_{n_{1}}^{1}}, t^{1}_{1}, \dots, t^{1}_{n'_{1}}) \dots B^{1}_{k_{1}} \sim_{\alpha_{2}} B^{1}_{1} \dots B^{2}_{1} \dots Q^{2}(\widehat{x_{1}^{2}}, \dots, \widehat{x_{n_{2}}^{2}}, t^{2}_{1}, \dots, t^{2}_{n'_{2}}) \dots B^{2}_{k_{2}} \dots B^{1}_{k_{1}} \sim_{\alpha_{3}} \dots \sim_{\alpha_{p}} B^{1}_{1} \dots B^{p}_{1} \dots Q^{p}(\widehat{x_{1}^{p}}, \dots, \widehat{x_{n_{p}}^{p}}, t^{p}_{1}, \dots, t^{p}_{n'_{p}}) \dots B^{p}_{k_{p}} \dots B^{1}_{k_{1}}$$

where $Q^p(\widehat{x_1^p},\ldots,\widehat{x_{n_p}^p},t_1^p,\ldots,t_{n_p'}^p) = P(\widehat{x_1'},\ldots,\widehat{x_n'},t_1',\ldots,t_{n'}').$

For each *k* (after *k* steps in the previous derivation), $\alpha_k \circ \alpha_{k-1} \dots \circ \alpha_1(x_i)$ is a variable of $Out(Q^k(\widehat{x_1^k}, \dots, \widehat{x_{n_k}^k}, t_1^k, \dots, t_{n_k'}^k))$ and $\alpha_k \circ \alpha_{k-1} \dots \circ \alpha_1(x_j)$ is either a variable of $Out(Q^k(\widehat{x_1^k}, \dots, \widehat{x_{n_k}^k}, t_1^k, \dots, t_{n_k'}^k))$ or a non-variable term containing a variable of $Out(Q^k(\widehat{x_1^k}, \dots, \widehat{x_{n_k}^k}, t_1^k, \dots, t_{n_k'}^k))$.

Each derivation step issued from Q^k uses either a clause pseudo-empty over Q^{k+1} and we deduce $Q^k >_{Prog} Q^{k+1}$, or an empty clause over Q^{k+1} and we deduce $Q^k \succeq_{Prog} Q^{k+1}$. At least one step uses a pseudo-empty clause otherwise no variable from x_1, \ldots, x_n would be instantiated by a non-variable term containing at least one variable in x'_1, \ldots, x'_n .

We conclude that $P = Q^0 op_1 Q^1 op_2 Q^2 \dots Q^{p-1} op_p Q^p = P$ with each op_i is $>_{Prog}$ or \succeq_{Prog} and there exists k such that op_k is $>_{Prog}$. Therefore $P >^+_{Prog} P$, so Prog is cyclic. \Box

Thus, if *Prog* is not cyclic, all is fine. Otherwise, we need to transform *Prog* into *Prog'* such as *Prog'* is not cyclic and $Mod(Prog) \subseteq Mod(Prog')$.

The transformation is based on the following observation. If *Prog* is cyclic, there is at least one pseudo-empty clause that participates in a cycle. In Example 16, $P(\hat{x}, h(y), f(z)) \leftarrow Q(\hat{x}, \hat{z}), R(\hat{y})$ is a pseudo-empty clause over Q involved in the cycle. To remove the cycle, we transform it into $P(\hat{x}, h(y), f(z)) \leftarrow Q(\hat{x}, \hat{x}_2), R(\hat{x}_1), Q(\hat{x}_3, \hat{z}), R(\hat{y})$ (x_1, x_2, x_3 are new variables), which is not pseudo-empty anymore. The main process is described in Definition 19. Definitions 16, 17 and 18 are preliminary definitions used in Definition 19. Example 17 illustrates the definitions. If there are input arguments then some variables occurring in the input arguments of the body should also be renamed in order to get a non-copying S-CF clause.

Definition 16. Given a S-CF program *Prog*, the set *S* of *productive* predicate symbols is recursively defined as being the smallest set such that

- for each fact $(P(\cdots) \leftarrow)$ of *Prog*, $P \in S$,

- and for each clause $P(\dots) \leftarrow P_1(\dots), \dots, P_n(\dots)$ of *Prog*, if $P_1, \dots, P_n \in S$, then $P \in S$.

P is unproductive iff $P \notin S$.

Definition 17 (*simplify*). Let $H \leftarrow A_1, \ldots, A_n$ be an S-CF clause, and for each *i*, let us write $A_i = P_i(\ldots)$.

If there exists P_i such that P_i is unproductive then simplify $(H \leftarrow A_1, \ldots, A_n)$ is the empty set, otherwise it is the set that contains only the S-CF clause $H \leftarrow B_1, \ldots, B_m$ such that

• $\{B_i \mid 0 \le i \le m\} \subseteq \{A_i \mid 0 \le i \le n\}$ and

• $\forall i \in \{1, \dots, n\}, (\neg (\exists j, B_j = A_i) \Leftrightarrow (Var(A_i) \cap Var(H) = \emptyset \land \forall k \neq i, Var(A_i) \cap Var(A_k) = \emptyset)).$

In other words, simplify deletes unproductive clauses, or it removes the atoms of the body that contain only free variables.

Let $H \leftarrow B$ be a non-copying S-CF clause. Note that if the variable x occurs several times in B then $x \notin Var(H)$.

Definition 18 (*unSync*). Let $H \leftarrow B$ be a non-copying S-CF clause.

Let us write $Out(H) = (t_1, ..., t_n)$ and $In(B) = (s_1, ..., s_k)$. unSync $(H \leftarrow B) = simplify(H \leftarrow \sigma_0(B), \sigma_1(B))$ where σ_0, σ_1 are substitutions built as follows. $\forall x \in Var(B)$:

 $\sigma_{0}(x) = \begin{cases} x \text{ if } x \in VarOut(B) \land \exists i, t_{i} = x \\ x \text{ if } x \in VarIn(B) \cap VarIn(H) \land \exists j, (s_{j} = x) \\ a \text{ fresh variable otherwise} \end{cases}$ $\sigma_{1}(x) = \begin{cases} x \text{ if } x \in VarOut(B) \land \exists i, (t_{i} \notin Var \land x \in Var(t_{i})) \\ x \text{ if } x \in VarIn(B) \cap VarIn(H) \land \exists j, (s_{j} \notin Var \land x \in Var(s_{j})) \\ a \text{ fresh variable otherwise} \end{cases}$

Definition 19 (*removeCycles*). Let *Prog* be an S-CF program. If *Prog* is not cyclic then removeCycles(*Prog*) = *Prog*. Otherwise removeCycles(*Prog*) = removeCycles({unSync}($H \leftarrow B$)} \cup *Prog*') where $H \leftarrow B$ is a pseudo-empty clause involved in a cycle and $Prog' = Prog \setminus \{H \leftarrow B\}$.

Example 17. Let *Prog* be the S-CF program of Example 16. Since *Prog* is cyclic, let us compute removeCycles(*Prog*). The pseudo-empty S-CF clause

 $P(\hat{x}, \hat{h}(y), \hat{f}(z)) \leftarrow Q(\hat{x}, \hat{z}), R(\hat{y})$ is involved in the cycle. Consequently, unSync is applied on it. According to Definition 18, one obtains σ_0 and σ_1 where $\sigma_0 = [x/x, y/x_1, z/x_2]$ and $\sigma_1 = [x/x_3, y/y, z/z]$. Thus, one gets the S-CF clause $P(\hat{x}, \hat{h}(y), \hat{f}(z)) \leftarrow Q(\hat{x}, \hat{x}_2), R(\hat{x}_1), Q(\hat{x}_3, \hat{z}), R(\hat{y})$. Note that according to Definition 18, simplify is applied and removes $R(\hat{x}_1)$ from the body. Following Definitions 17 and 19, $P(\hat{x}, \hat{h}(y), \hat{f}(z)) \leftarrow Q(\hat{x}, \hat{z}), R(\hat{y})$ is removed from *Prog* and $P(\hat{x}, \hat{h}(y), \hat{f}(z)) \leftarrow Q(\hat{x}, \hat{x}_2), Q(\hat{x}_3, \hat{z}), R(\hat{y})$ is added instead. Note that the atom $R(\hat{x}_1)$ has been removed using simplify. Note also that there is no cycle anymore.

removeCycles may enlarge the least Herbrand Model.

Lemma 8. Let Prog and Prog' be two S-CF programs such that Prog is non-copying and Prog' = removeCycles(Prog). Then Prog' is a non-copying and non-cyclic S-CF program, and $Mod(Prog) \subseteq Mod(Prog')$. Moreover:

- if Prog is normalized, then so is Prog',
- if Prog is strongly coherent with R, then so is Prog'.

Consequently, there are finitely many critical pairs in *Prog'*.

Proof. removeCycles applies unSync until the program is not cyclic. When applying unSync, one pseudo-empty clause is removed and replaced by a non-pseudo-empty one. Thus, the number of pseudo-empty clauses decreases, and when there are no more pseudo-empty clauses, the program is not cyclic. Then removeCycles terminates and returns *Prog'*, which is not cyclic.

simplify does not change *Mod*(*Prog*). On the other hand, unSync may enlarge *Mod*(*Prog*), because of the introduction of free variables in the clause body.

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simplify and unSync do not change the clause head. Then if the clause is normalized, the resulting clause also is. Moreover, the fresh variables introduced into input arguments by σ_0 are distinct from those introduced by σ_1 . Then if the clause is non-copying, the resulting clause also is.

The definition of strong coherence (Definition 12) includes two conditions. Recall that for a S-CF clause, function symbols in input arguments necessarily occur in the body. Therefore condition 1 is preserved by removeCycles because removeCycles does not add new function symbols in clause bodies (just new variables are added). Condition 2 is preserved by removeCycles because removeCycles does not change clause heads. \Box

4.3. Normalizing critical pairs – norm_{Prog}

If a critical pair is not convergent, we add it into *Prog*, and the critical pair becomes convergent. However, a critical pair is not necessarily normalized, whereas all clauses in *Prog* should be normalized. In the case of CS-clauses (i.e. without input arguments), a procedure that transforms a non-normalized clause into normalized ones has been presented [2]. For example, $P(\widehat{f(g(x))}, \widehat{b}) \leftarrow Q(\widehat{x})$ can be normalized into $\{P(\widehat{f(x)}, \widehat{b}) \leftarrow P_1(\widehat{x}), P_1(\widehat{g(x)}) \leftarrow Q(\widehat{x})\}$ (*P*₁ is a new predicate symbol). Since only output arguments should be normalized, this procedure still works even if there are also input arguments.

As new predicate symbols are introduced, possibly with bigger arities, completion may not terminate. To make it terminate in every case, two positive integers are used: *predicate-limit* and *arity-limit*. If the number of predicate symbols having the same arity as P_1 (including P_1) exceeds *predicate-limit*, an existing predicate symbol (for example Q) must be used instead of the new predicate P_1 . This may enlarge Mod(Prog) in general and may lead to a strict over-approximation. If the arity of P_1 exceeds *arity-limit*, P_1 must be replaced in the clause body by several predicate symbols¹⁹ whose arities are less than or equal to *arity-limit*. This may also enlarge Mod(Prog). See [2] for more details. In other words norm_{Prog}($H \leftarrow B$) builds a set of normalized S-CF clauses N such that $Mod(Prog \cup \{H \leftarrow B\}) \subseteq Mod(Prog \cup N)$.

However, when starting from a CS-program (i.e. without input arguments), it could be interesting to normalize by introducing input arguments, in order to profit from the bigger expressiveness of S-CF programs, and consequently to get a better approximation of the set of descendants, or even an exact computation, like in Examples 18 and 19 presented in Section 5. The quality of the approximation depends on the way the normalization is achieved. Some heuristics will be developed in further work. Moreover, they should preserve strong coherence when introducing new input arguments. A rule to preserve it could be as follows. For each function symbol f occurring in the head of a critical pair:

- if f is consuming, f should be generated as output in a predicate symbol having no input arguments,

- if f is reducible, i.e. f occurs as the root of a left-hand-side, and f is not consuming, f should be generated as output.

This rule is applied in Examples 18 and 19.

4.4. Completion

At the beginning of Section 4, we have presented in Definition 9 the completion algorithm i.e. $comp_R$. In Sections 4.1 and 4.3, we have described how to detect non-convergent critical pairs and how to convert them into normalized clauses using norm_{Prog}.

Theorem 3 illustrates that our technique leads to a finite S-CF program whose language over-approximates the descendants obtained by a linear rewrite system R.

Theorem 3. Function comp always terminates, and all critical pairs are convergent in $\text{comp}_R(\text{Prog})$. Moreover, for each predicate symbol *P* without input arguments, $R^*(L_{\text{Prog}}(P)) \subseteq L_{\text{comp}_R(\text{Prog})}(P)$.

Proof. The proof is straightforward. \Box

5. Examples

In this section, completion is applied on several examples. *I* is the initial set of terms and *R* is the rewrite system. Initially, we define an S-CF program *Prog* that generates *I* and that satisfies the assumptions of Definition 9. To make the procedure terminate shortly, we suppose that *predicate-limit* = 1, which means that for all *i*, there is at most one predicate symbol having *i* arguments, except for i = 1 we allow two predicate symbols having one argument.

When the following example is dealt with synchronized languages, i.e. with CS-programs [2, Example 42], we get a strict over-approximation of the descendants. Now, thanks to the bigger expressivity of S-CF programs, we compute the descendants in an exact way.

¹⁹ For instance, if P_1 is binary and *arity-limit* = 1, then $P_1(t_1, t_2)$ should be replaced by the sequence of atoms $P_2(t_1)$, $P_3(t_2)$. Note that the dependency between t_1 and t_2 is lost, which may enlarge *Mod*(*Prog*). Symbols P_2 and P_3 are new if it is compatible with *predicate-limit*. Otherwise former predicate symbols should be used instead of P_2 and P_3 .

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| Detected non-convergent critical pairs | New clauses obtained by $norm_{Prog}$ |
|----------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| | Starting S-CF program $P_f(\widehat{f(x,y)}) \leftarrow P_a(\widehat{x}), P_a(\widehat{y}).$ $P_a(\widehat{a}) \leftarrow .$ |
| $P_f(u(f(v(\widehat{x}), w(y)))) \leftarrow P_a(\widehat{x}), P_a(\widehat{y}).$ | $P_f(\widehat{z}) \leftarrow P_1(\widehat{z}, x, y), P_a(\widehat{x}), P_a(\widehat{y}).$ $P_1(u(\widehat{z}), x, y) \leftarrow P_1(\widehat{z}, v(x), w(y)).$ $P_1(f(x, y), x, y) \leftarrow .$ |
| Ø | |

Fig. 3. Run of $comp_R$ on Example 18.

Example 18. Let $I = \{f(a, a)\}$ and $R = \{f(x, y) \rightarrow u(f(v(x), w(y)))\}$. The exact set of descendants is $R^*(I) = \{u^n(f(v^n(a), w^n(a))) \mid n \in \mathbb{N}\}$. We define $Prog = \{P_f(\widehat{f(x, y)}) \leftarrow P_a(\widehat{x}), P_a(\widehat{y}).$ (1), $P_a(\widehat{a}) \leftarrow .$ (2)}. Note that $L_{Prog}(P_f) = I$.

Using clause (1) we have $P_f(\widehat{f(x, y)}) \rightarrow_{(1)} P_a(\widehat{x}), P_a(\widehat{y})$ generating the critical pair: $P_f(u(f(v(x), w(y)))) \leftarrow P_a(\widehat{x}), P_a(\widehat{y})$. In order to normalize this critical pair, we choose to generate symbols u, f as output, v, w as input. Moreover only one predicate symbol of arity 3 is allowed. It produces three new S-CF clauses:

$$P_f(\widehat{z}) \leftarrow P_1(\widehat{z}, x, y), P_a(\widehat{x}), P_a(\widehat{y}).$$
 (3), $P_1(\widehat{u(z)}, x, y) \leftarrow P_1(\widehat{z}, v(x), w(y)).$ (4) and $P_1(\widehat{f(x, y)}, x, y) \leftarrow .$ (5).

Now $P_f(\widehat{f(x', y')}) \rightarrow_{(3)} P_1(\widehat{f(x', y')}, x, y), P_a(\widehat{x}), P_a(\widehat{y}) \sim_{(5),\sigma} P_a(\widehat{x}), P_a(\widehat{y})$ where $\sigma = (x'/x, y'/y)$. Consequently, it generates the convergent critical pair $P_f(u(\widehat{f(v(x), w(y))})) \leftarrow P_a(\widehat{x}), P_a(\widehat{y})$ again. On the other hand, since $P_1(\widehat{f(x', y')}, x, y) \sim_{(5),(x'/x, y'/y)} \emptyset$, the critical pair $P_1(u(\widehat{f(v(x), w(y))}), x, y) \leftarrow$ is detected, but it is already convergent.

No other critical pair is detected. Then, we get the S-CF program Prog' composed of clauses (1) to (5), and note that $L_{Prog'}(P_f) = R^*(I)$ indeed.

The run of the completion is summarized in Fig. 3. The left-most column reports the detected non-convergent critical pairs and the right-most column describes how they are normalized.

The previous example could probably be dealt in an exact way using the technique of [1] as well, since $R^*(I)$ is a context-free language. It is not the case for the following example, whose language of descendants $R^*(I)$ is not context-free (and not synchronized). It can be handled by S-CF programs in an exact way thanks to their bigger expressivity.

Example 19. Let $I = \{d_1(a, a, a)\}$ and

$$R = \left\{ \begin{array}{c} d_1(x, y, z) \stackrel{1}{\to} d_1(h(x), i(y), s(z)), & d_1(x, y, z) \stackrel{2}{\to} d_2(x, y, z) \\ d_2(x, y, s(z)) \stackrel{3}{\to} d_2(f(x), g(y), z), & d_2(x, y, a) \stackrel{4}{\to} c(x, y) \end{array} \right\}$$

 $R^*(I)$ is composed of all terms appearing in the following derivation:

Note that the last rewrite step by rule 4 is possible only when k = n.

Let $Prog = \{P_d(\widehat{d_1(x, y, z)}) \leftarrow P_a(\widehat{x}), P_a(\widehat{y}), P_a(\widehat{z}).$ (1), $P_a(\widehat{a}) \leftarrow .$ (2)}. Thus $L_{Prog}(P_d) = I$.

By applying clause (1) and using rule 1, we get the critical pair:

 $P_d(d_1(h(x), i(y), s(z))) \leftarrow P_a(\hat{x}), P_a(\hat{y}), P_a(\hat{z})$. To normalize it, we choose to generate all symbols as output. Then the following clauses (3) and (4) are added into $Prog: P_d(d_1(x, y, z)) \leftarrow P_1(\hat{x}, \hat{y}, \hat{z})$. (3) and $P_1(h(x), i(y), \hat{s(z)}) \leftarrow P_a(\hat{x}), P_a(\hat{y}), P_a(\hat{z})$. (4). By applying clause (1) and using rule 2, we obtain the critical pair $P_d(d_2(x, y, z)) \leftarrow P_a(\hat{x}), P_a(\hat{y}), P_a(\hat{z})$. (5). This critical pair being already normalized, it is directly added into *Prog*.

We obtain the critical pair $P_d(d_1(h(x), i(y), s(z))) \leftarrow P_1(\widehat{x}, \widehat{y}, \widehat{z})$ by applying clause (3) and rule 1. To normalize it, we generate all symbols as output. It produces clause (3) again, and $P_1(\widehat{h(x)}, \widehat{i(y)}, \widehat{s(z)}) \leftarrow P_1(\widehat{x}, \widehat{y}, \widehat{z})$. (6).

Applying clause (3) and using rule 2, we get the critical pair:

 $P_d(d_2(x, y, z)) \leftarrow P_1(\hat{x}, \hat{y}, \hat{z})$. (7) which is already normalized. Thus, it is directly added into *Prog.* Applying clause (5) and using rule 4, we get the critical pair $P_d(c(x, y)) \leftarrow P_a(\hat{x}), P_a(\hat{y})$. (8) which is already normalized. Consequently, it is directly added into *Prog.*

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| Detected non-convergent critical pairs | New clauses obtained by $norm_{Prog}$ |
|--------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| | Starting S-CF program |
| | $\begin{array}{l} P_d(d_1(\overline{x,y},z)) \leftarrow P_a(\widehat{x}), P_a(\widehat{y}), P_a(\widehat{z}). \\ P_a(\widehat{a}) \leftarrow . \end{array}$ |
| $P_d(d_1(h(x), \widehat{i(u)}, s(z))) \leftarrow P_a(\widehat{x}), P_a(\widehat{y}), P_a(\widehat{z})$ | $P_d(\widehat{d_1(x,y,z)}) \leftarrow P_1(\widehat{x},\widehat{y},\widehat{z}).$ |
| $= u(-1)(-(-))(\partial f) - (-f) f = u(-f) - u(\partial f) - u(-f)$ | $P_1(\widehat{h(x)}, \widehat{i(y)}, \widehat{s(z)}) \leftarrow P_a(\widehat{x}), P_a(\widehat{y}), P_a(\widehat{z}).$ |
| $P_d(d_2(\widehat{x,y},z)) \leftarrow P_a(\widehat{x}), P_a(\widehat{y}), P_a(\widehat{z}).$ | |
| $P_d(d_1(h(x), \widehat{i(y)}, s(z))) \leftarrow P_1(\widehat{x}, \widehat{y}, \widehat{z})$ | $P_1(\widehat{h(x)}, \widehat{i(y)}, \widehat{s(z)}) \leftarrow P_1(\widehat{x}, \widehat{y}, \widehat{z}).$ |
| $P_d(d_2(\widehat{x,y},z)) \leftarrow P_1(\widehat{x},\widehat{y},\widehat{z}).$ | |
| $P_d(\widehat{c(x,y)}) \leftarrow P_a(\widehat{x}), P_a(\widehat{y}).$ | |
| $P_d(d_2(f(h(\widehat{x})), q(i(y)), z)) \leftarrow P_c(\widehat{x}), P_c(\widehat{y}), P_c(\widehat{z})$ | $P_d(d_2(\widehat{x,y},z)) \leftarrow P_2(\widehat{x},\widehat{y},\widehat{z},x',y',z'), P_a(\widehat{x'}), P_a(\widehat{y'}), P_a(\widehat{z'}).$ |
| | $P_2(\widehat{f(x)}, \widehat{g(y)}, \widehat{z}, x', y', z') \leftarrow P_2(\ \widehat{x}, \widehat{y}, \widehat{z}, h(x'), i(y'), z')$ |
| | $P_2(\widehat{x}, \widehat{y}, \widehat{z}, x, y, z) \leftarrow .$ |
| A cycle is detected – $removeCycles$ replaces the | $P_2(\widehat{f(x)},\widehat{g(y)},\widehat{z},x',y',z') \leftarrow P_2(\widehat{x},\widehat{y},\widehat{z_1},h(x'),i(y'),z_1'),$ |
| blue clause by the red one. | $P_2(\widehat{x_1}, \widehat{y_1}, \widehat{z}, h(x_1'), i(y_1'), z')$ |
| $P_d(d_2(f(h(x)), g(i(y)), z)) \leftarrow P_1(\widehat{x}, \widehat{y}, \widehat{z})$ | $P_d(d_2(\widehat{x,y},z)) \leftarrow P_2(\widehat{x},\widehat{y},\widehat{z},x',y',z'), P_1(\widehat{x'},\widehat{y'},\widehat{z'}).$ |
| $P_d(c(\widehat{f(x),g(y))}) \leftarrow P_2(\widehat{x},\widehat{y},\widehat{z},h(x'),\overline{i(y')},z'),$ | $P_3(\widehat{f(x)}, \widehat{g(y)}) \leftarrow P_2(\widehat{x}, \widehat{y}, \widehat{z}, h(x'), i(y'), z'), \ \overline{P_a(\widehat{x'})}, P_a(\widehat{y'}).$ |
| $P_a(\widehat{x'}), P_a(\widehat{y'}).$ | $P_d(\widehat{c(x,y)}) \leftarrow P_3(\widehat{x},\widehat{y}).$ |

Fig. 4. Run of $comp_R$ on Example 19.

By applying clauses (7) and (4), and using rule 3, we get the critical pair: $P_d(d_2(f(h(x)), g(i(y)), z)) \leftarrow P_a(\hat{x}), P_a(\hat{y}), P_a(\hat{z})$. To normalize it, we choose to generate d_2 , f, g as output, and h, i as input. It produces:

 $P_{d}(\widehat{d_{2}(x, y, z)}) \leftarrow P_{2}(\widehat{x}, \widehat{y}, \widehat{z}, x', y', z'), P_{a}(\widehat{x'}), P_{a}(\widehat{y'}), P_{a}(\widehat{z'}).$ (9) $P_{2}(\widehat{f(x)}, \widehat{g(y)}, \widehat{z}, x', y', z') \leftarrow P_{2}(\widehat{x}, \widehat{y}, \widehat{z}, h(x'), i(y'), z').$ (10') $P_{2}(\widehat{x}, \widehat{y}, \widehat{z}, x, y, z) \leftarrow .$ (11)

Now, clause (10') may provide an infinite number of critical pairs. Applying removeCycles makes clause (10') be substituted by the clause $P_2(\widehat{f(x)}, \widehat{g(y)}, \widehat{z}, x', y', z') \leftarrow P_2(\widehat{x}, \widehat{y}, \widehat{z_1}, h(x'), i(y'), z'_1), P_2(\widehat{x_1}, \widehat{y_1}, \widehat{z}, h(x'_1), i(y'_1), z')$ (10).

By applying clauses (7) and (6), and using rule 3, we get the critical pair: $P_d(d_2(f(h(x)), g(i(y)), z)) \leftarrow P_1(\widehat{x}, \widehat{y}, \widehat{z})$. We normalize it as previously. We get $P_d(d_2(x, y, z)) \leftarrow P_2(\widehat{x}, \widehat{y}, \widehat{z}, x', y', z')$, $P_1(\widehat{x'}, \widehat{y'}, \widehat{z'})$. (12) as well as (10), (11) again.

With clauses (9 or 12), (10), and rule 3, we get the convergent critical pairs $P_d(d_2(f(\widehat{f(x)}), \widehat{g(g(y))}, z)) \leftarrow P_2(\widehat{x}, \widehat{y}, \widehat{z_1}, h(h(x')), i(i(y')), z'_1), P_a(\widehat{x'}), P_a(\widehat{x})$ and $P_d(d_2(f(\widehat{f(x)}), \widehat{g(g(y))}, z)) \leftarrow P_2(\widehat{x}, \widehat{y}, \widehat{z_1}, h(h(x')), i(i(y')), z'_1), P_1(\widehat{x'}, \widehat{y'}, \widehat{z}).$

By applying clauses (9 or 12) and (11), and using rule 3, we get the convergent critical pairs $P_d(d_2(f(h(x)), g(i(y)), z)) \leftarrow P_a(\hat{x}), P_a(\hat{y}), P_a(\hat{z})$ and $P_d(d_2(f(h(x)), g(i(y)), z)) \leftarrow P_1(\hat{x}, \hat{y}, \hat{z})$. By applying clauses (9) and (11), and using rule 4, we get the convergent critical pair $P_d(c(x, y)) \leftarrow P_a(\hat{x}), P_a(\hat{y})$. Applying clauses (9) and (10), and using rule 4, we obtain the critical pair: $P_d(c(f(x), g(y))) \leftarrow P_2(\hat{x}, \hat{y}, \hat{z}, h(x'), i(y'), z'), P_a(\hat{x'}), P_a(\hat{x'}), P_a(\hat{y'})$. Its normalization gives the clauses: $P_3(f(x), \hat{g(y)}) \leftarrow P_2(\hat{x}, \hat{y}, \hat{z}, h(x'), i(y'), z'), P_a(\hat{x'}), P_a(\hat{y'})$. (13) and $P_d(c(x, y)) \leftarrow P_3(\hat{x}, \hat{y})$. (14). Note that the symbols c, f and g have been considered as output parameters.

No more critical pairs are detected and the procedure stops. The resulting program Prog' is composed of clauses (1) to (14). Note that the subset of descendants $d_2(f^k(h^n(a)), g^k(i^n(a)), s^{n-k}(a))$ can be seen (with p = n - k) as $d_2(f^k(h^{k+p}(a)), g^k(i^{k+p}(a)), s^p(a))$. The reader can check by himself that $L_{Prog'}(P_d)$ is exactly $R^*(I)$.

The run of the completion on this example is also summarized in Fig. 4. Black arrows means that the non-convergent critical pair is directly added to *Prog* since it is already normalized.

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6. Further work

Computing approximations more precise than regular ones is a first attempt towards a verification technique. However, there are at least two steps before considering our technique as a verification technique: 1) automatically handling the choices done during the normalization process and 2) extending to work with any rewrite system.

Concerning item 1, the quality of the approximation highly depends on the choice of the predicate symbol to be reused when *predicate-limit* is reached. On the other hand, the choice of generating function-symbols as output or as input is also crucial. Some automated heuristics will have to be designed in order to obtain well-customized approximations, for instance by extending the ideas of [25].

Ongoing work tends to show that the linear restriction concerning the rewrite system can be tackled. A nonright-linear rewrite system makes the computed S-CF program copying. Consequently, Theorem 2 does not hold anymore. To get rid of the right-linearity restriction, we are studying the transformation of a copying S-CF clause into non-copying ones that will generate an over-approximation. On the other hand, to get rid of the left-linearity restriction, we are studying a technique based on that of [9]. However, their method does not always terminate. We want to force termination thanks to an additional over-approximation.

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