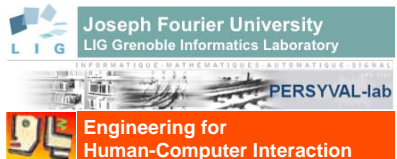


**Laurence Nigay**

---

**Interaction modality and multimodality**




*JIRC Journées Informatique de la Région Centre*

**EHCI group**

---

- “EHCI” for Engineering for Human-Computer Interaction
  - Created in 1990
  - 9 professors and assistant professors
  - 1 CNRS researcher
  - 1 CNRS research engineer part time
  - 14 PhD students
  - 5 project engineers
  - 1 visiting researcher
  - 10 master students



**EHCI group**


---

- EHCI group belongs to LIG (Computer Science Laboratory of Grenoble)
  - 188 academic researchers
  - 367 doctoral / post-doctoral students, visitors, engineers
  - 45 technical and administrative staff
- 23 autonomous research teams
- 4 principal themes
  - Infrastructure (networks and data)
  - Software (foundations and design models)
  - **Interaction (perception, action and dialog)**
  - Knowledge (learning, agent models and web-ontologies)

**EHCI group: Research thematic**

---

- Software Engineering for HCI



- Understanding the human-computer phenomena
- Establishing links between psychology-ergonomics and software engineering
- Designing, developing and evaluating interaction techniques
- Developing conceptual and technical tools based on HCI principles: Utility, Usability, Context

**EHCI group: Research axes**

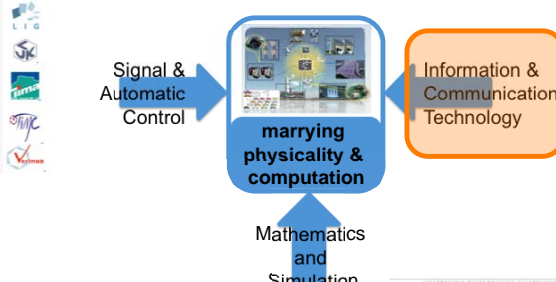
---

- 5 complementary research axes
- Multimodal interaction
- Interaction with small handheld devices
- **Mixed reality interaction**
- User interface plasticity
- New interaction techniques

**Laboratory of excellence Persyval-lab**

---

- Pervasive Systems & Algorithms at the convergence of the physical and digital worlds



### Outline

- Research framework
  - Scientific themes
  - Research approach
  - HCI & Ubiquitous computing
  - Three research axes
- Foundations of my work
  - Interaction modality
  - Multimodality
- Combining the real and virtual worlds

### Scientific themes: Design trade-offs

Designers face a fundamental challenge:  
How to balance the trade-off between power of expression and simplicity of interaction?

*simple things should be simple  
complex things should be possible*

© W. Mackay

### Scientific themes: Design trade-offs

Research challenge?  
Move the curve!

© W. Mackay

### Scientific approach: deduction and induction

© W. Mackay

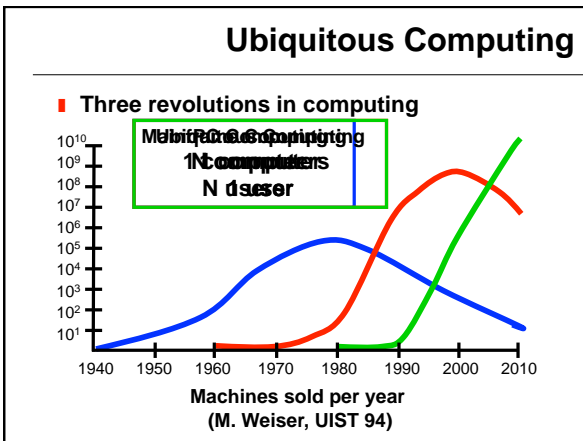
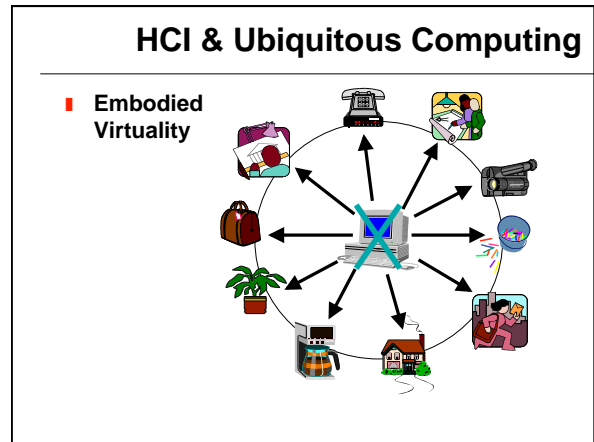
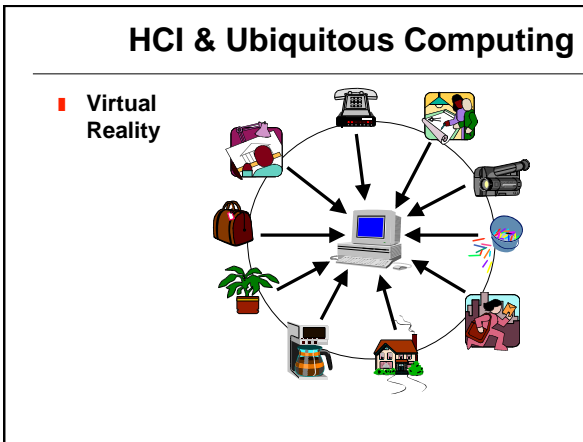
### Scientific approach: deduction and induction

© W. Mackay

### HCI & Ubiquitous Computing

- Ubiquitous computing 1991  
*M. Weiser Scientific American*
- Calm technology

- Invisible technology
- Technology available at any place
- Symbiosis of the real and digital worlds



### HCI & Ubiquitous Computing

- HCI in the context of "Ubiquitous computing"
  - a seamless interactive environment
  - unobtrusive, everywhere
  - often invisible and yet in our consciousness

### HCI & Ubiquitous Computing



- HCI in the context of "Ubiquitous computing"
  - "Our surrounding is the interface" to a universe of integrated services. This will enable citizens to access IST services wherever they are, whenever they want, and in the form that is most "natural" for them

### HCI & Ubiquitous Computing

- HCI in the context of "Ubiquitous computing"
  - Unprecedented challenges for interaction design
    - Combining the real and virtual worlds
    - Multiple interaction devices/modalities
      - Small and large interaction surfaces
    - Dynamic contexts of use

### HCI & Ubiquitous Computing

- HCI in the context of “Ubiquitous computing”
- Unprecedented challenges for interaction design
- ... while defining an opportunity for the users’ acceptance of innovative interaction techniques going beyond the desktop paradigm

The Xerox Star has reached its limits

### HCI & Ubiquitous Computing

- My scientific goals:
  1. Design and realisation of interaction techniques for large information spaces (*interactive visualisation*)
  2. Design and realisation of interaction techniques on mobile devices (*mobile techniques*)
  3. Design and realisation of interaction techniques for combining the real and virtual worlds (*combining real and virtual worlds*)

### HCI & Ubiquitous Computing

- My scientific goals:
  1. Design and realisation of interaction techniques for large information spaces (*visualisation*)
  2. Design and realisation of interaction techniques on mobile devices (*mobile techniques*)
  3. Design and realisation of interaction techniques for combining the real and virtual worlds (*combining real and virtual worlds*)

From the point of view of  
**Interaction modality and Multimodality**

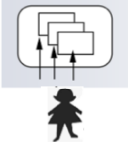
### Outline

- Research framework
  - Scientific themes
  - Research approach
  - Ubiquitous computing
  - Three research axes
- Foundations of my work
  - Interaction modality
  - Multimodality
- Combining the real and virtual worlds

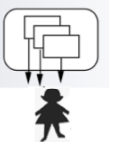
### Interaction modality

- Modality = (device, interaction language)
  - A set of sensors (input devices) or effectors (output devices)
  - A processing facility based on a language

Input modality

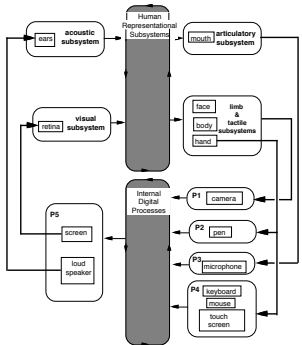


Output modality



### Interaction modality


- Theory ICS
  - APU Cambridge
- ICS as predicting cognitive resources involved in using and choosing modalities

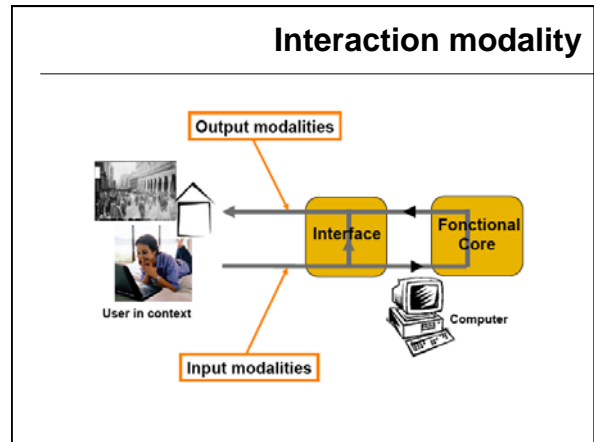


### Interaction modality

- Modality = (device, interaction language)
- Recent interaction paradigms such as perceptual UI, tangible UI and embodied UI open a vast world of possibilities


- M1 = (microphone, natural language)
- M2 = (keyboard, command language)
- M3 = (mouse, direct manipulation)
- M4 = (PDA, 3D gesture) *embodied UI*
- M5 = (HMD, 3D graphics) *AR*
- M6 = (bottle-sensor, 3D gesture) *tangible UI*
- M7 = (GPS, localization) *perceptual UI*
- M8 = (Tongue display, 2D shape)






### Interaction modality

- INPUT Modality = <d, l>

Modality = < , natural language >


Flights from Pittsburgh to Boston




*MATIS project*

### Interaction modality


- INPUT Modality = <d, l>




M = <camera-finger, gesture>



M = <micro, NL>



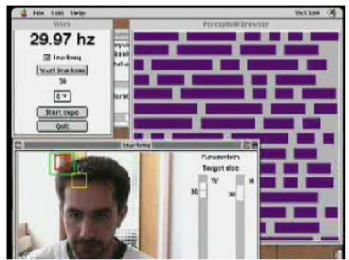
M = <PDA, gesture>  
*Embodied UI*



M = <stylus, direct manipulation>

### Interaction modality


- Input M = <camera-head, gesture>



*Perceptual browser project*

### Interaction modality

- Input M = <devices, gesture>
- Devices: wiimote, iPhone, trackIR, Shake ...

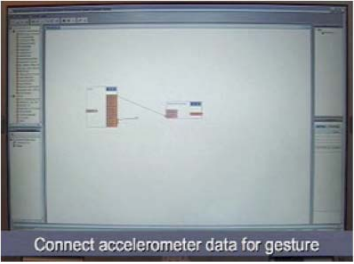


**Gesture Recognition**

*SHAKE*  
triple axis accelerometer,  
two capacitive sensors  
and a vibrotactile actuator


### Interaction modality

- Input M = <devices, gesture>
- Examples: wiimote and trackIR



### Definition of a modality

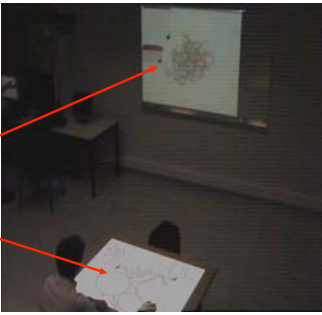
- Input M = <camera-token, direct manipulation>



Tokens

The position of tokens are tracked by a vision based mechanism. A tracking video camera is fixed on the top of the table. NAVRNA: A system to visualize, explore and edit RNA.

### Definition of a modality

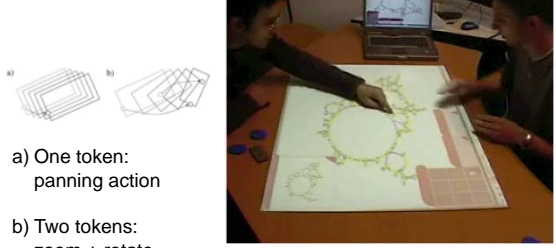


Tertiary structure

Secondary structure

### Definition of a modality

- Input M = <camera-token, direct manipulation>



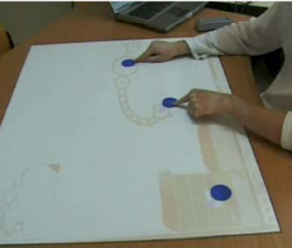
a) One token: panning action

b) Two tokens: zoom + rotate

### Definition of a modality

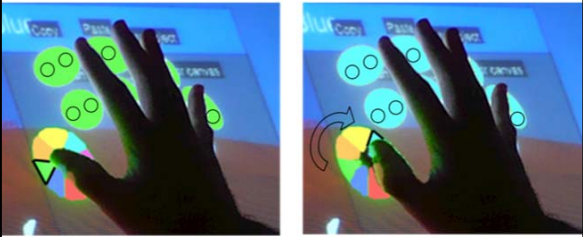
- Input M = <camera-token, direct manipulation>

Two-handed interaction:  
Bending one branch of RNA




### Definition of a modality

- Input M = <multi-touch table, direct manipulation>
- Multitouch menu: MTM




### Definition of a modality

- Input M = <multi-touch table, direct manipulation>
- Multitouch menu: MTM




← extension



flexion →

← abduction




adduction →

15 degrees of freedom  
Thumb: 5 degrees of freedom

Bulchholz, B., Armstrong, T. J., (1992) A Kinematic model of the human hand to evaluate its prehensile capabilities, J. Biomechanics.

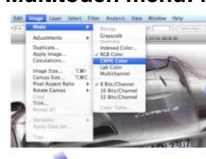
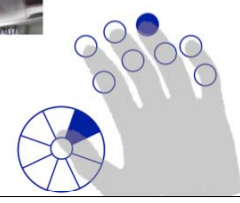
### Definition of a modality

- Input M = <multi-touch table, direct manipulation>
- Multitouch menu: MTM



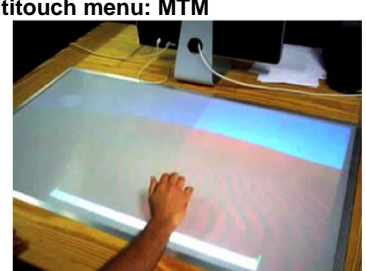
### Definition of a modality

- Input M = <multi-touch table, direct manipulation>
- Multitouch menu: MTM



### Definition of a modality

- Input M = <multi-touch table, direct manipulation>
- Multitouch menu: MTM



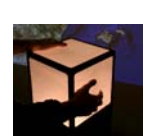

### Definition of a modality

- Input M = <multi-touch surfaces, interaction langage>
- Device: cubtile
  - Immersion [www.immersion.fr](http://www.immersion.fr)
  - First 3D multitouch interface
  - 5 multi-touch surfaces
  - Rear Diffused Illumination
  - Multiuser

### Definition of a modality

- Input M = <multi-touch surfaces, interaction langage>
- Device: cubtile
- One interaction langage per surface
- Two-handed interaction

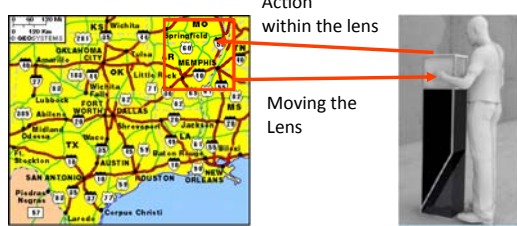


### Definition of a modality

- **Input M =**  
<multi-touch surfaces, interaction language>
- **Two handed-interaction**
  - **Psychological Theory -Kinematic chain – Y. Guiard**
    - Right-to-left reference: The right hand performs its motion relative to the frame of reference set by the left hand
    - Asymmetric scales: Different temporal-spatial scales of motion
    - Left hand precedence: The left hand precedes the right: for example, the left hand first positions the paper, then the right hand begins to write
    - Right hand preference: Is the one finishing the action, touching the world

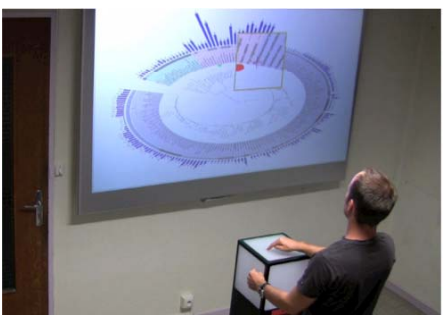
### Definition of a modality

- **Input M =**  
<multi-touch surfaces, interaction language>
- **Two handed-interaction**




### Definition of a modality

- **Two handed-interaction**



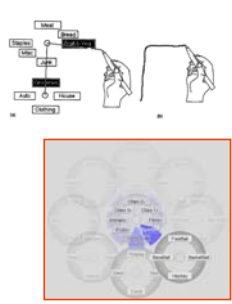
### Definition of a modality

- **Input M =**  
<small interactive surface, direct manipulation>
- **Wavelet menu on iPhone**
  - Space on screen
  - No keyboard for shortcuts (novice mode)
  - The best way to interact is to use only one-hand
  - Eye-free interaction



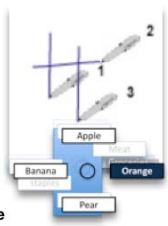
### Input modalities on small devices

- **Marking menus**
- Advantages
  - Circular design
  - Fluid transition
  - Scale independance
- Limitations
  - Screen space requirement
  - Number of commands
    - Error rate in expert mode
    - Ambiguous marks in expert mode



### Input modalities on small devices

- **Marking menus**
- **Multi-stroke marking menus**
- Instead of considering a spatial compound stroke,
- Multi-Stroke menus introduce a serie of simple strokes
- **Require less physical input space in novice & expert modes**
  - A submenu is displayed on top of its parent menu
  - Overlapped marks
- **Increase accuracy in expert mode**
- **Increase the number of items**
  - No ambiguous gestures in expert mode

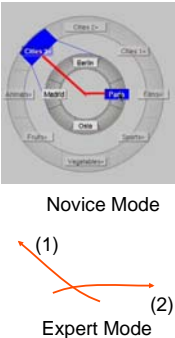




### Input modalities on small devices

**Wave menus**

- Few physical input space
- A submenu is displayed at the center of the menu system. In order to remain visible, its parent menu is then enlarged to surround this submenu
- In expert mode, Wave Menus work exactly the same way as Multi-Stroke Menus




Novice Mode

(1) (2)

Expert Mode

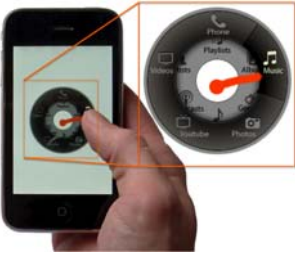
### Input modalities on small devices

**Wave menus**




### Input modalities on small devices

**Wavelet menus: extension on Iphone**



### Input modalities on small devices


**Wavelet menus: extension on Iphone**



- The Wavelet menu appears centered around the contact point.
- By drawing a stroke towards the desired item, the first level is enlarged permitting progressive appearance of the submenu.
- A second stroke selects an item in the submenu.

### Input modalities on small devices

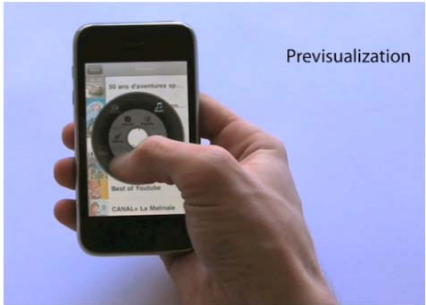
**Wavelet menus: extension on Iphone**



Long lists management: the linear list appears in the center of the Wavelet menu and is surrounded by its parent menus.

### Input modalities on small devices

**Wavelet menus:**



Previsualization

### Input modalities on small devices

- LeafMenu: extension of linear menus

### Input modalities on small devices

- LeafMenu: extension of linear menus

### Definition of a modality

- Input M = <bottle-sensor, gesture>

- Input M = <Object-sensor, manipulation>

### Definition of a modality

- Input M = <Object-sensor, manipulation>
- Object-Sensor = Mixed objects
  - MIM: Model of Mixed Interaction  
A conceptual model for designing augmented objects
  - OP (Object Prototyping): A toolkit based on the conceptual model MIM for prototyping mixed objects

### Definition of a modality

- Input M = <Object-sensor, manipulation>
- MIM: Model of Mixed Interaction

### Definition of a modality

- Input M = <Object-sensor, manipulation>
- OP: Object prototyping
  - Toolkit developed in Qt
  - Toolkit that includes ARToolkit, Phidgets, Interface-Z sensors

OP - Prototyping mixed objects: Combined development of form and interaction.

Scott E. Hudson HCI CMU

### Definition of a modality

### Definition of a modality

- Input M = <Object-sensor, manipulation>
- OP: Object prototyping

```

1 int main(int argc, char* argv[])
2 {
3     // Initialize ROS
4     ros::init(argc, argv, "light_sensor", ros::init_options::AnonymousName);
5     ros::NodeHandle nh;
6     // Create a publisher
7     std::string topic = "light_exposed";
8     ros::Publisher pub = nh.advertise<bool>(topic, 10);
9     // Create a subscriber
10    bool is_exposed = false;
11    ros::Subscriber sub = nh.subscribe<bool>(topic, 10, &callback);
12    // Callback function
13    void callback(const bool& msg)
14    {
15        is_exposed = msg;
16        pub.publish(is_exposed);
17    }
18    // Main loop
19    while (nh.ok())
20    {
21        // Wait for a message
22        ros::spinOnce();
23    }
24    return 0;
25 }
    
```

### Definition of a modality

- Input Modalities (*sensing modalities*)
- M1 = <GPS, localization>
- M2 = <magnetometer, orientation>

*TROC project*

### Definition of a modality

- Input Modalities

Get

- M1 = (micro, command)
- M2 = (trackpad, 2D gesture)
- M3 = (camera, 3D gesture)

### Definition of a modality

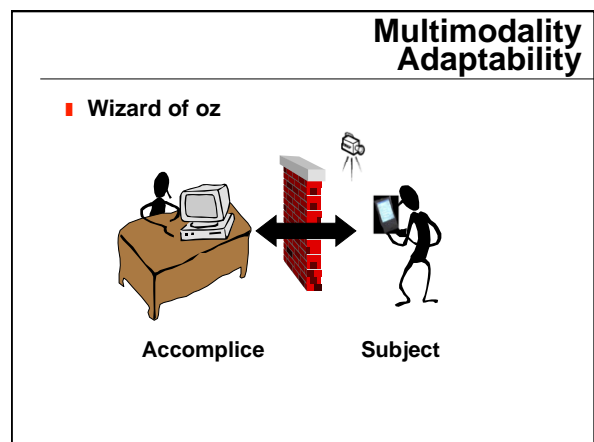
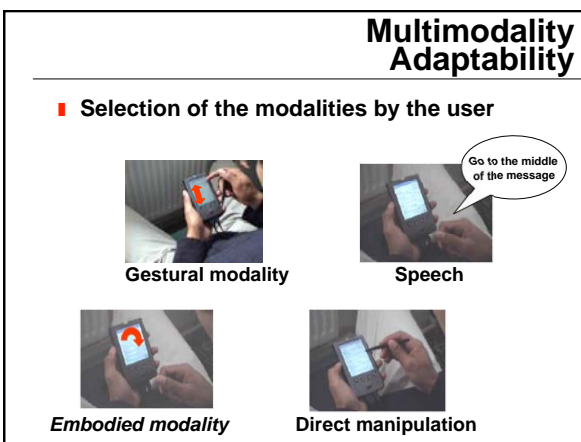
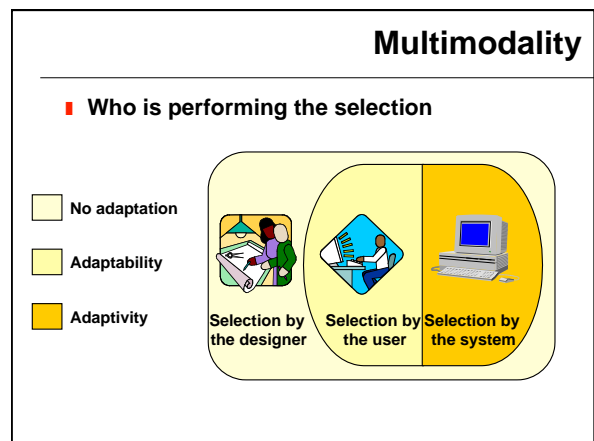
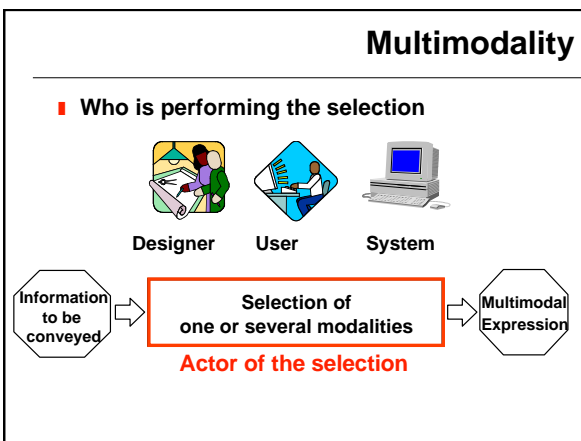
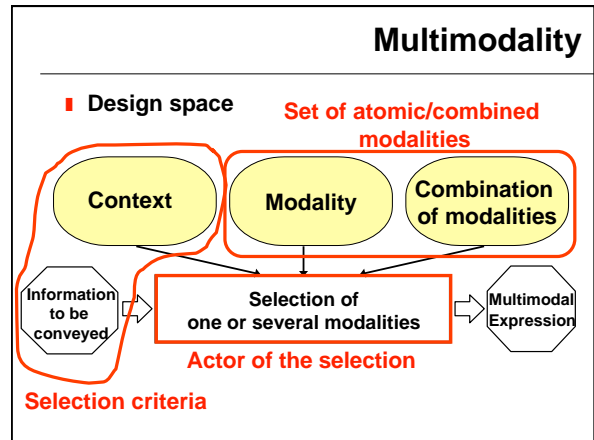
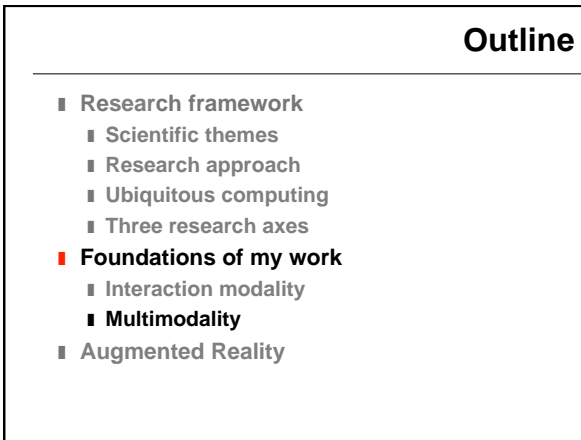
- OUTPUT Modality = <d, l>
- M = <HMD, 3D graphics>

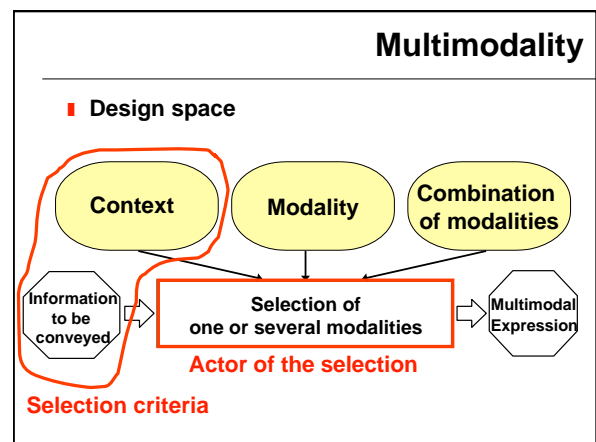
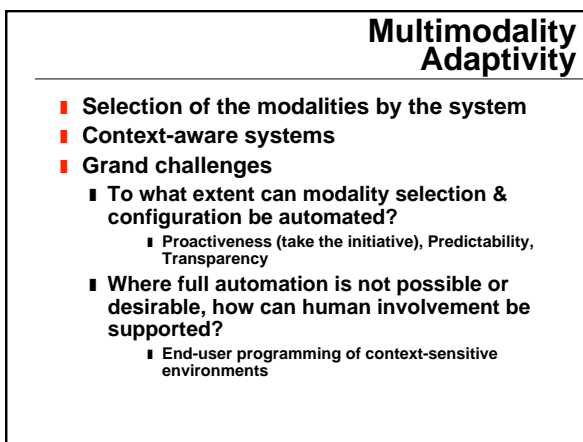
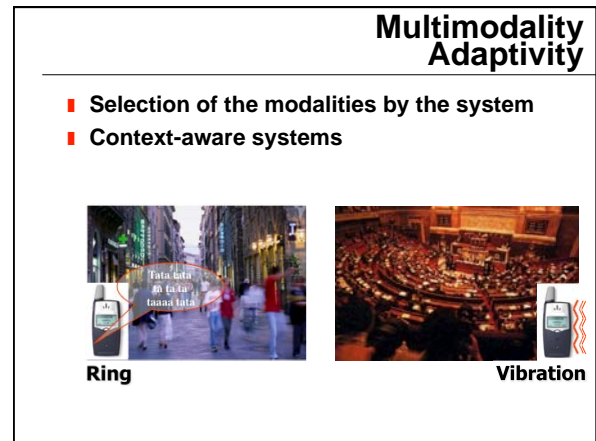
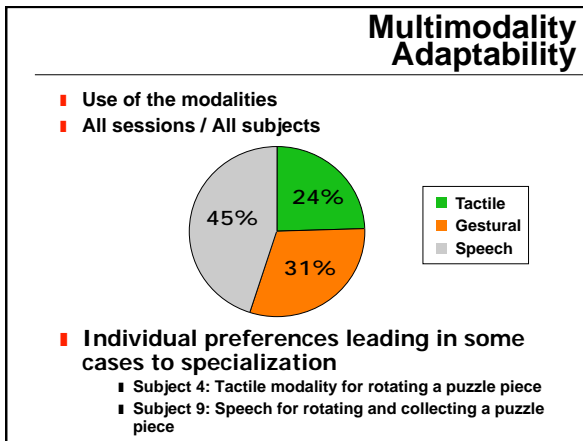
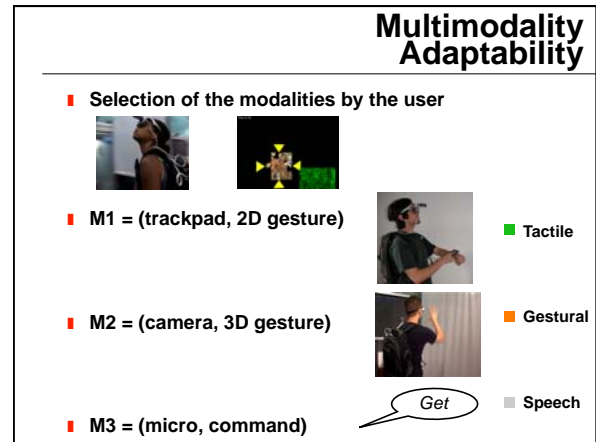
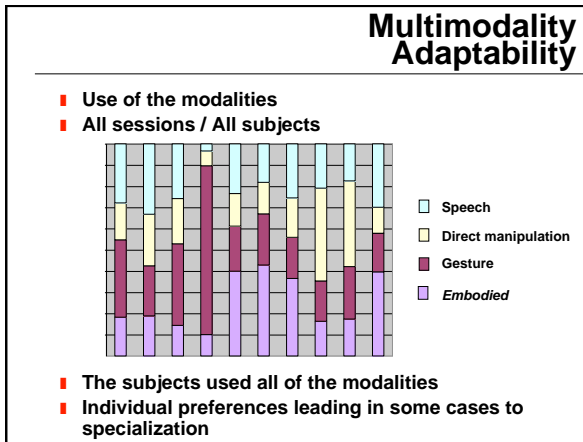
*CASPER project*

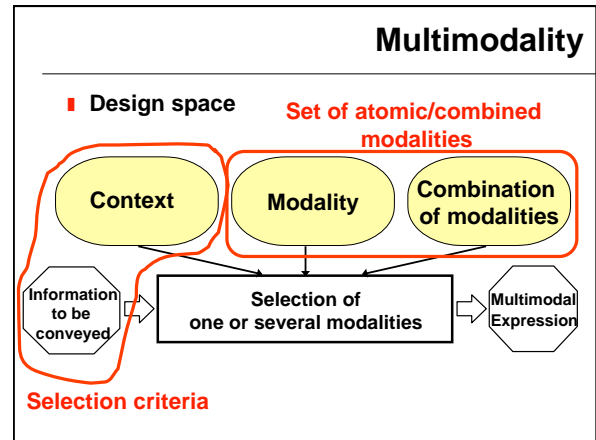
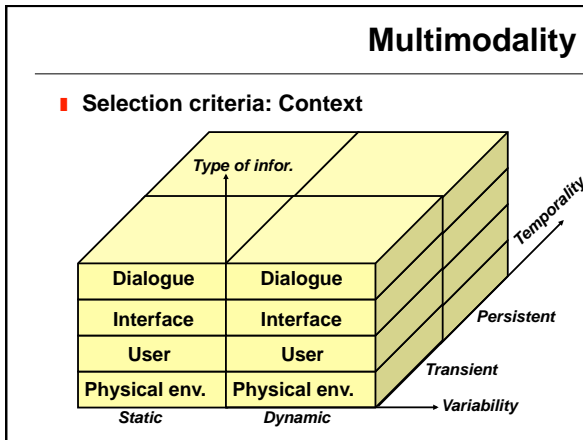
### Definition of a modality

- OUTPUT Modality = <d, l>


M = <screen, table>    M = <screen, deformed table>







### Atomic and combined modalities

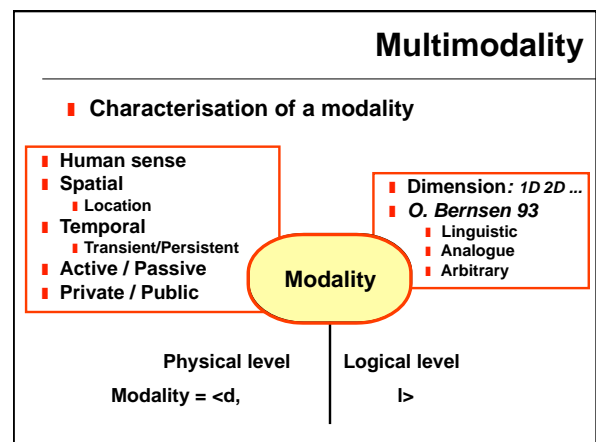
- Interaction modelling at the modality level
  - Rich enough to express differences
    - 
  - Abstract enough to enable reasoning
    - among modalities (vast world of modalities)
      - any physical object can be involved in interaction
    - between modality and task/system/service/context issues

### Atomic and combined modalities

- A vast world of atomic and combined modalities
  - any physical object can be involved in interaction as a device
  - We can no longer expect to model each input and output modality in all their diversity at the concrete level
  - We need to reason about modalities at a higher level of abstraction

### Multimodality

- Characterisation of a modality
- Active modalities
  - For inputs, active modalities are used by the user to issue a command to the computer such as a pedal to move a laparoscope in a CAS system
- Passive - Implicit modalities
  - Passive modalities are used to capture relevant information for enhancing the realization of the task, information that is not explicitly expressed by the user to the computer (PUI). For example tracking position

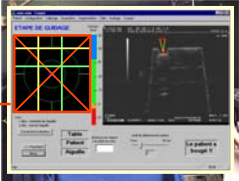




### Multimodality

- **Characterisation of a modality**


- **Physical level**
  - Human sense: Sight
  - Spatial: Location = screen
  - Temporal: Persistent
  - Public
- **Logical level**
  - 2D
  - Non Analogue
  - Arbitrary



### Multimodality

- **Characterisation of a modality**

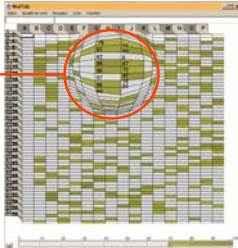
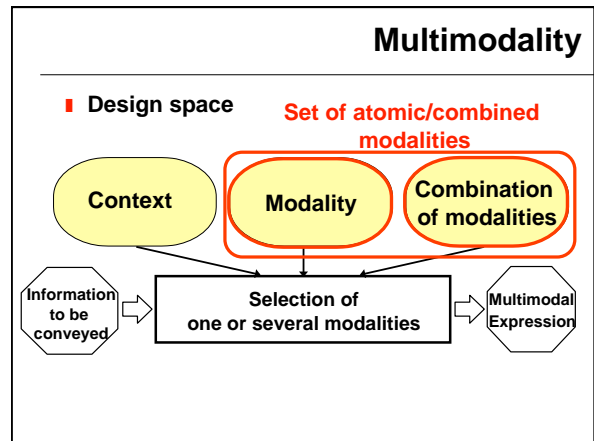
- **Physical level**
  - Human sense: Sight
  - Spatial: Location = operating field
  - Temporal: Persistent
  - Private
- **Logical level**
  - 3D
  - Analogue
  - Non arbitrary



### Multimodality

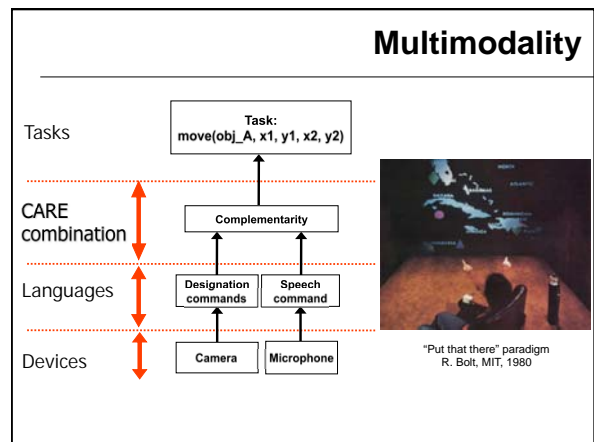
- **Characterisation of a modality**

- **Physical level**
  - Human sense: Sight
  - Spatial: Location = screen
  - Temporal: Persistent
  - Public
- **Logical level**
  - 3D
  - Analogue
  - Non arbitrary

### Multimodality


- **Combination of modalities**
- **Several studies**
  - UOM 94 / TYCOON 95 / CARE 95
- **CARE properties**
  - Relationships between Devices, Interaction languages and Tasks
  - C : Complementarity
  - A : Assignment
  - R : Redundancy
  - E : Equivalence

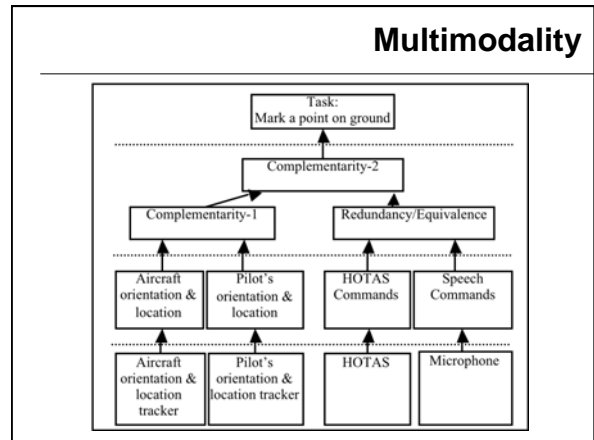


### Multimodality

- Flight simulator of a military fighter, used for studying future interaction techniques in the cockpit



**Modalities:**  
 M1: Aircraft location  
 M2: Pilot's orientation  
 M3: HOTAS commands  
 M4: Speech commands

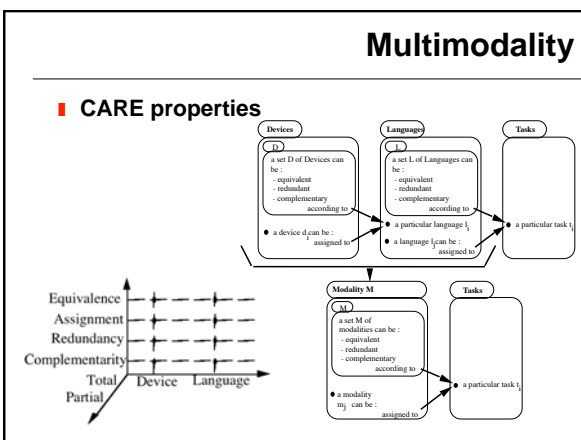
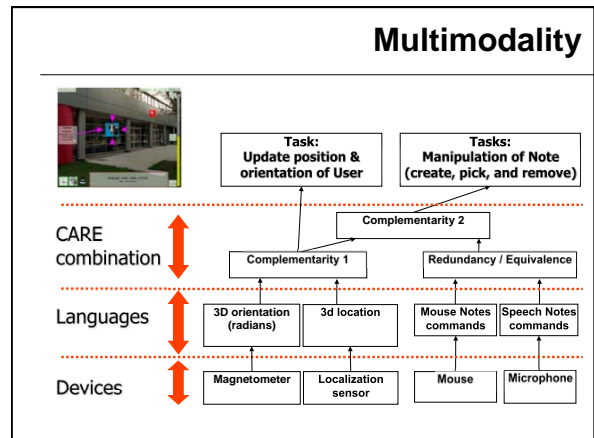




### Multimodality

- TROC: a game based on the technique of barter
- M1 = (Magnetometer, orientation)
- M2 = (GPS, location)
- Complementarity of M1 and M2 for selecting an object



### Multimodality

- Combination of modalities
- CARE properties
- New combination space
  - Different schemas and aspects of combinations
  - 5 aspects: temporal, spatial, articulatory syntactic and semantic
  - 5 schemas: [Allen 83]


### Multimodality

■ **Combination of modalities**

		Combination schemas				
		[ ]	[ ]	[ ]	[ ]	[ ]
Combination aspects	<b>Temporal</b>	Anachronism	Sequence	Concomitance	Coincidence	Parallelism
	<b>Spatial</b>	Separation	Adjacency	Intersection	Overlaid	Collocation
	<b>Articulatory</b>	Independence	Fission	Fission Duplication	Partial Duplication	Total Duplication
	<b>Syntactic</b>	Difference	Completion	Divergence	Extension	Twin
	<b>Semantic</b>	Concurrency	Complementarity	Complementarity & Redundancy	Partial Redundancy	Total Redundancy

### Multimodality

■ **AR Puzzle**

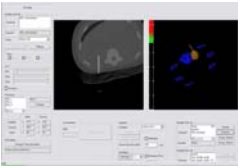
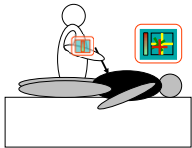


Turn 48° to the left

✖

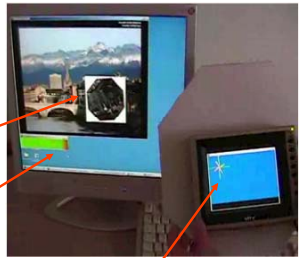
### Multimodality

■ **PERM system: a CAS system for kidney puncture**

### Multimodality

■ **Puzzle**

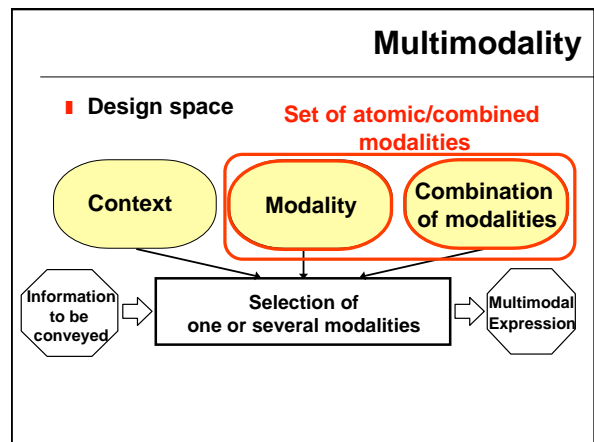


M1 = <screen, 2D image>  
 M2 = <screen, color>  
 M3 = <mini-screen, crosses>

### Multimodality

■ **Combination of M2 = <screen, color> and M3 = <mini-screen, crosses>**

		Combination schemas				
		[ ]	[ ]	[ ]	[ ]	[ ]
Combination aspects	<b>Temporal</b>	Anachronism	Sequence	Concomitance	Coincidence	Parallelism
	<b>Spatial</b>	Separation	Adjacency	Intersection	Overlaid	Collocation
	<b>Articulatory</b>	Independence	Fission	Fission Duplication	Partial Duplication	Total Duplication
	<b>Syntactic</b>	Difference	Completion	Divergence	Extension	Twin
	<b>Semantic</b>	Concurrency	Complementarity	Complementarity & Redundancy	Partial Redundancy	Total Redundancy



### Outline

- Research framework
  - Scientific themes
  - Research approach
  - Ubiquitous computing
  - Three research axes
- Foundations of my work
  - Interaction modality
  - Multimodality
- **Combining the real and virtual worlds**

### Combining the real and virtual worlds

### Combining the real and virtual worlds

### Combining the real and virtual worlds

- Profusion of terms
  - Virtual reality
  - Bit / Atom
  - Computer Augmented Environment
  - Augmented Video
  - Augmented Interaction
  - Augmented Virtuality
  - Augmented Reality
  - ...

### Combining the real and virtual worlds

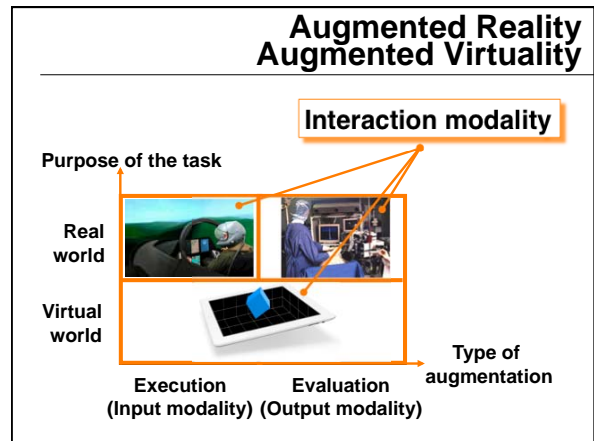
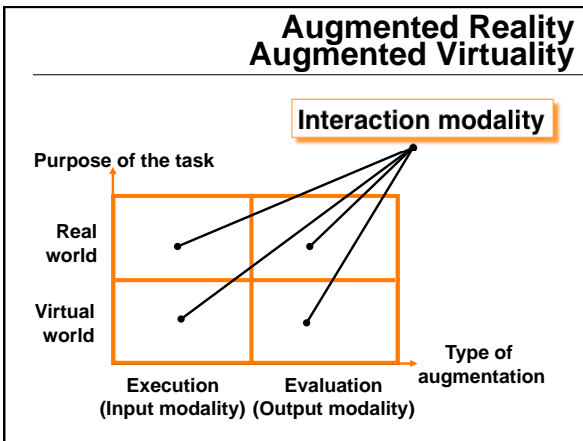
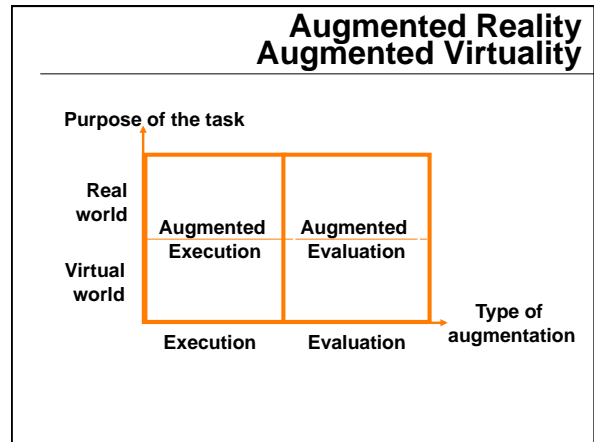
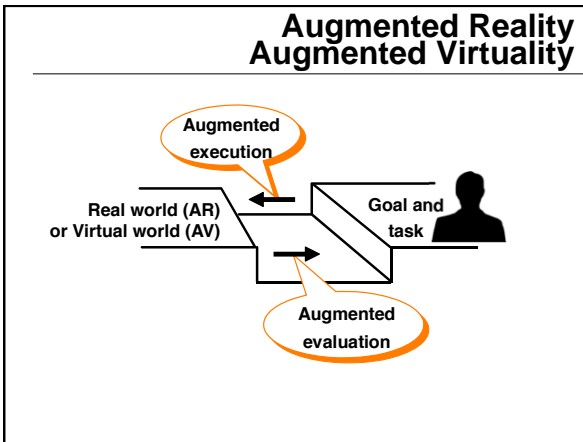
- **Common objective**

### Augmented Reality Augmented Virtuality

Purpose of the task = real world

Purpose of the task = computer

keyboard UI, graphical UI, gestural UI, tangible UI, embodied UI



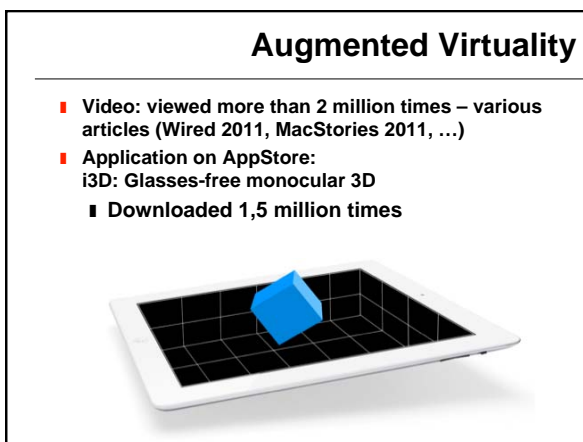
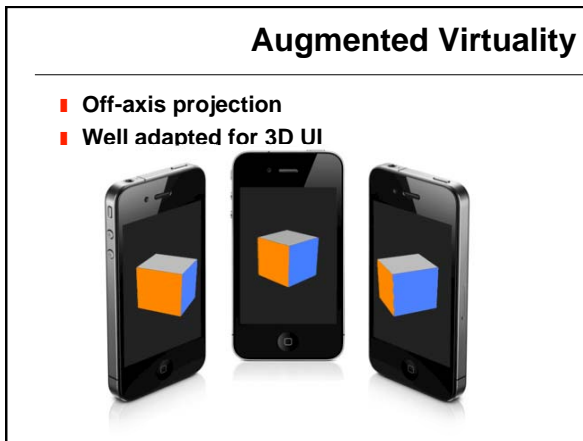
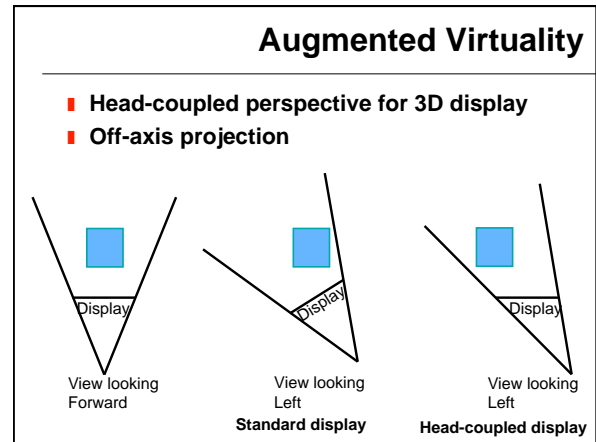
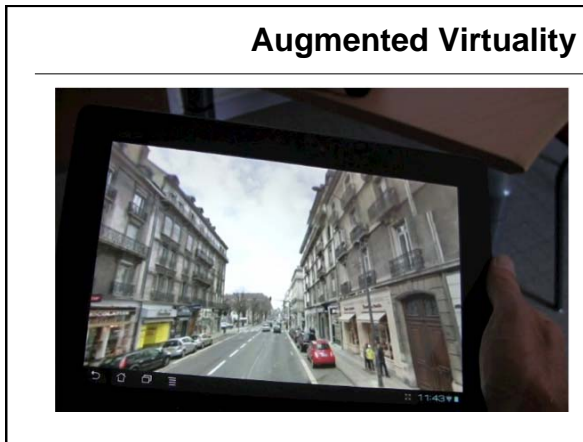
### Augmented Virtuality

- New input modality on mobile devices
  - intuitive
  - Inspired by natural movements

- based on head tracking with the front facing camera

### Augmented Virtuality

- Head tracking improves both input and output capabilities
- Input: Head movements to navigate
- Output: 3D effect




### Outline

- Research framework
  - Scientific themes
  - Research approach
  - Ubiquitous computing
  - Three research axes
- Foundations of my work
  - Interaction modality
  - Multimodality
- Combining the real and virtual worlds
- Conclusion



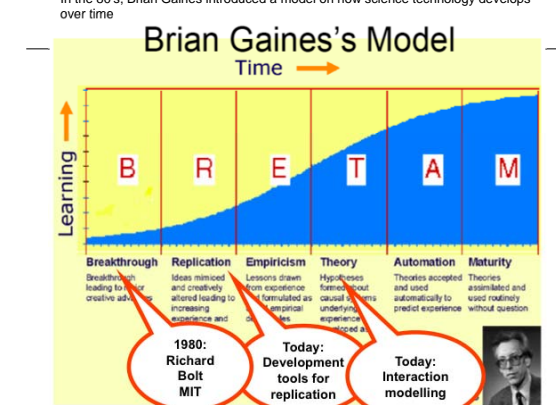
## Conclusion



- **Modality and multimodality:**  
A VAST space of possibilities to be explored
- **Augmented Virtuality / Augmented Reality:**
  - **Multimodality:**
    - Real world (Action/Perception)
    - Digital world (Action/Perception)
- **Multimodality is an integrating vector for several recent interaction paradigms that include:**
  - augmented reality
  - augmented virtuality
  - tangible interfaces

In the 80's, Brian Gaines introduced a model on how science technology develops over time

### Brian Gaines's Model



Breakthrough	Replication	Empiricism	Theory	Automation	Maturity
Breakthrough leading to creative advance	Ideas mimicked and creatively altered leading to increasing experience and	Lessons drawn from experience formulated as empirical	Hypotheses formulated about causal mechanisms underlying experience closed at	Theories accepted and used automatically to predict experience	Theories assimilated and used routinely without question

1980: Richard Bolt MIT

Today: Development tools for replication

Today: Interaction modelling

## Thank you

