

Using approximation to relate computational classes over the reals

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Outline

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- 2 **Framework**
- 3 **Results**
 - Real Recursive Functions
 - Polynomial differential equations
- 4 **Conclusion**

Motivation

Is $f : \mathbb{R} \rightarrow \mathbb{R}$ computable?

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Several notions of computability for real functions:

- Turing machine approach: Computable Analysis
- Continuous time analog models
- BSS machines
- ...

Motivation

$$\mathbf{C}(\mathbb{R}) = \textit{“Analog”}$$

Analog models considered in this talk:

- Polynomial Differential Equations
- Real Recursive Functions

Motivation

- Church-Turing type thesis for computation on the reals:
 - There are many distinct models of computation on the reals: Computable Analysis, Real recursive Functions, General Purpose Analog Computer, Neural Networks, Dynamic Systems,...
 - How are the models distinct?
 - What kind of modifications make them equal?
- Applications in discrete complexity theory.
 - Can separation questions (e.g. P versus NP) be reduced to relevant questions in Analysis?
 - Can we transfer those questions into relevant questions in Analysis?
 - See work by Costa and Mycka (2006, 2007) in this direction.

Computable Analysis

Definition

- $f(x) \in \mathbf{C}(\mathbb{R})$:

*There is a **computable** function $F^x(n)$ with an oracle for the real number x such that*

$$|f(x) - F^x(n)| \leq 1/n.$$

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- $\mathbf{E}(\mathbb{R})$: like $\mathbf{C}(\mathbb{R})$, replacing **computable** by **elementary computable**.

Approximation and Completion

Goal. $\mathbf{C}(\mathbb{R}) = A(\text{LIM})$, broken into 2 steps:

- (Approximation) $\mathbf{C}(\mathbb{R}) \approx A$.
- (Completion) $\mathbf{C}(\mathbb{R}) = A(\text{LIM})$.

Approximation Relation

Definition

$\mathcal{A} \preceq_+^\varepsilon \mathcal{B}$ iff

For every $f(\bar{x}) \in \mathcal{A}$ and every $\alpha(\bar{x}, \bar{y}) \in \varepsilon$ there is $f^(\bar{x}, \bar{y}) \in \mathcal{B}$ such that $|f(\bar{x}) - f^*(\bar{x}, \bar{y})| \leq \alpha(\bar{x}, \bar{y})$.*

$\mathcal{A} \approx^\varepsilon \mathcal{B}$ iff $\mathcal{A} \preceq_+^\varepsilon \mathcal{B}$ and $\mathcal{B} \preceq_+^\varepsilon \mathcal{A}$.

Lemma (transitivity)

Let ε be an error class. If $\mathcal{A} \preceq_+^\varepsilon \mathcal{B}$ and $\mathcal{B} \preceq_+^\varepsilon \mathcal{C}$ then $\mathcal{A} \preceq_+^\varepsilon \mathcal{C}$.

Completion Operation

Definition

LIM is the operation:

- **Input:** $f(\bar{x}, t)$
- **Output:** $F(\bar{x}) = \lim_{t \rightarrow \infty} f(\bar{x}, t)$, if the limit exists and $F \preceq^{1/t} f$, for positive t

Definition

If OP is an operation and \mathcal{F} a set of functions, then $\mathcal{F}(\text{OP})$ is:

$$\mathcal{F} \cup \{\text{OP}(f) \mid f \in \mathcal{F}\}$$

Thus $\mathcal{F}(\text{LIM})$ is a “completion” of \mathcal{F} .

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Note. LIM is a weak kind of limit operation:

- $\mathbf{C}(\mathbb{R}) = \mathbf{C}(\mathbb{R})(\text{LIM});$
- $\mathbf{E}(\mathbb{R}) = \mathbf{E}(\mathbb{R})(\text{LIM}).$

Function Algebras

Definition

Suppose \mathcal{B} is a set of functions (i.e. the basic functions) and \mathcal{O} is a set of operations. Then $\text{FA}[\mathcal{B}; \mathcal{O}]$ is the smallest set of functions containing \mathcal{B} and closed under \mathcal{O} .

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Basic Functions:

- Constant functions: $0, 1, -1, \pi$
- Projection functions “P” (example: $P(x, y) = x$)
- $\theta(x) = \begin{cases} 0, & x < 0; \\ x^3, & x \geq 0. \end{cases}$

The Operations

Definition (COMP)

Input: \vec{f}, \vec{g} ; **Output:** $\vec{h} = \vec{g} \circ \vec{f}$.

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Definition (LI)

- **Input:** Functions: $\vec{g}(\bar{x}), \vec{f}(y, \bar{x})$.
- **Output:** $h_1(y, \bar{x})$ where (h_1, \dots, h_n) is the solution to the IVP:

$$\begin{aligned} \frac{\partial}{\partial y} \vec{h} &= \vec{f}(y, \bar{x}) \vec{h}(y, \bar{x}) \\ \vec{h}(0, \bar{x}) &= \vec{g}(\bar{x}) \quad (\text{initial conditions}) \end{aligned}$$

Examples:

$$\bullet f(x, y) = x + y \quad \begin{array}{l} f(x, 0) = x \\ \partial_y f(x, y) = 1 \end{array} \quad f' = [1 \ 1]$$

$$\bullet f(x, y) = xy \quad \begin{array}{l} f(x, 0) = 0 \\ \partial_y f(x, y) = x \end{array} \quad f' = [y \ x]$$

$$\bullet (\sin y, \cos y) \quad \begin{array}{l} f(0) = (0, 1) \\ \partial_y f(y) = (\cos y, -\sin y) \end{array} \quad \begin{bmatrix} f'_1 \\ f'_2 \end{bmatrix} = \begin{bmatrix} f_2 \\ -f_1 \end{bmatrix}$$

Elementary Computability.

Let \mathcal{L} abbreviate $\text{FA}[0, 1, -1, \pi, \theta, P; \text{comp}, L]$.

Let \mathcal{L}^a abbreviate $\text{FA}[0, 1, -1, P; \text{comp}, L]$.

Elementary Computability.

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Theorem

- (Approximation) $\mathbf{E}(\mathbb{R}) \approx \mathcal{L} \approx \mathcal{L}^a$
- (Completion) $\mathbf{E}(\mathbb{R}) = \mathcal{L}(\text{LIM}) = \mathcal{L}^a(\text{LIM})$

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Theorem

- (Approximation) $\mathbf{E}(\mathbb{R}) \approx \mathcal{L} \approx \mathcal{L}^a$
- (Completion) $\mathbf{E}(\mathbb{R}) = \mathcal{L}(\text{LIM}) = \mathcal{L}^a(\text{LIM})$
- (Alternative Completion) $\mathbf{E}(\mathbb{R}) = \mathcal{L}(\text{dLIM})$
(similar to Bournez and Hainry 2004)

Definition

dLIM is the operation:

- **Input:** $f(t, \bar{x})$
- **Output:** $F(\bar{x}) = \lim_{t \rightarrow \infty} f(t, \bar{x})$, if $|\frac{\partial}{\partial t} f| \leq 1/2^t$ for $t \geq 1$.

Sketch of the proof of $\mathbf{E}(\mathbb{R}) \approx \mathcal{L}$

TM models

 $\mathbf{E}(\mathbb{N})$

=

Function algebras

 $\mathbf{FA}_{\mathbb{N}}$

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TM models

$$\begin{array}{l} \mathbf{E}(\mathbb{N}) \\ \hat{\gamma} \mid \lambda \end{array} =$$

$$\mathbf{E}(\mathbb{Q}) =$$

Function algebras

$$\begin{array}{l} \mathbf{FA}_{\mathbb{N}} \\ \hat{\gamma} \mid \lambda \end{array}$$

$$\mathbf{FA}_{\mathbb{Q}}(\text{disctn})$$

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 \\
 \\
 \\
 \text{if } f \text{ has modulus}
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(Campagnolo and Ojakian, Arch Math Logic, to appear)

Sketch of the proof of $\mathcal{L} \approx \mathcal{L}^a$

Recall that $\mathcal{L} = \text{FA}[0, 1, -1, \pi, \theta, P; \text{comp}, \text{LI}]$
and $\mathcal{L}^a = \text{FA}[0, 1, -1, P; \text{comp}, \text{LI}]$.

Goal: eliminate the non-analytic function θ

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Goal: eliminate the non-analytic function θ

Show:

- $\theta, \pi \preceq \mathcal{L}^a$
- $\text{comp}, \text{LI} \preceq \mathcal{L}^a$

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Show:

- $\theta, \pi \preceq \mathcal{L}^a$
- $\text{comp}, \text{LI} \preceq \mathcal{L}^a$

General idea: using approximation and transitivity we can break down the proof of $\mathbf{E}(\mathbb{R}) \approx \mathcal{L}^a$ into simpler pieces.

Computability.

Theorem (similar to Bournez and Hainry, 2005, 2006)

- (Approximation) $\mathbf{C}(\mathbb{R}) \approx FA[0, 1, \theta, P; comp, CLI, UMU]$
- (Completion)

$$\begin{aligned}\mathbf{C}(\mathbb{R}) &= FA[0, 1, \theta, P; comp, CLI, UMU](LIM) \\ &= FA[0, 1, \theta, P; comp, CLI, UMU](dLIM)\end{aligned}$$

Definition

Note: The solutions of $\vec{y}' = \vec{p}(\vec{y}, t)$ with initial condition $\vec{y}(0) = \vec{y}_0$ are exactly the functions generated by Shannon's General Purpose Analog Computer (Graça and Costa, 2003).

Definition

Let PI be the operation:

- **Input:** $n - 1$ polynomials: $\vec{p}(y, t)$, a polynomial $q(x)$, and numbers $\alpha_1, \dots, \alpha_{n-1} \in \mathbb{R}$.
- **Output:** $y_1(t, x)$ where (y_1, \dots, y_n) is the solution of IVP:

$$\frac{\partial}{\partial t} \vec{y} = \vec{p}(\vec{y}, t) \quad \vec{y}(0) = (\alpha_1, \dots, \alpha_{n-1}, q(x))$$

Definition

For $X \subseteq \mathbb{R}$, let GPAC_X be the set of functions generated by PI using polynomials with coefficients from X and initial conditions from X .

Result

Let \mathcal{CR} be the set of computable reals.

Theorem (Bournez, Campagnolo, Graça and Hainry, 2007)

- (Approximation) $\mathbf{C}(\mathbb{R}) \approx \text{GPAC}_{\mathcal{CR}}$
- (Completion) $\mathbf{C}(\mathbb{R}) = \text{GPAC}_{\mathcal{CR}}(\varepsilon - \text{LIM})$

Question. Is this true for $\text{GPAC}_{\mathbb{Q}}$ or even $\text{GPAC}_{\{0,1,-1\}}$?

Summary

- Computable Analysis can be characterized with analog models.
- The connections can be organized using approximation and completion.
- New useful techniques: transitivity, eliminating non-analytic functions, lifting.

Directions for research

- Find simpler characterizations.
- Use the same techniques to characterize complexity classes lower than the elementary.
- Explore other kinds of “completion”.
- Are there characterizations of Computable Analysis, which naturally capture all of its functions, *without* a completion operation?

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Thanks!