# Computational Power of Observed Quantum Turing Machines 

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## PARIS <br> DIDEROT



## Quantum Computing Basics

## State space

in a classical world of computation: countable $A$.
in a quantum world:
Hilbert space $\mathbb{C}^{A}$
ket map

$$
\text { |.) : } A \rightarrow \mathbb{C}^{A}
$$

s.t. $\{|x\rangle, x \in A\}$ is an orthonormal basis of $\mathbb{C}^{A}$

## Arbitrary states

$$
\mathbf{\Phi}=\sum_{x \in A} \alpha_{x}|x\rangle
$$

s.t. $\sum_{x \in A}\left|\alpha_{x}\right|^{2}=1$

## Quantum Computing Basics

## bra map

$$
\langle.|: A \rightarrow \mathbf{L}\left(\mathbb{C}^{A}, \mathbb{C}\right)
$$

s.t. $\forall x, y \in A$,

$$
\langle y||x\rangle=\left\{\begin{array}{ll}
1 & \text { if } x=y \\
0 & \text { otherwise }
\end{array} \quad\right. \text { "Kronecker" }
$$

$\forall v, t \in A,|v\rangle\langle t|: \mathbb{C}^{A} \rightarrow \mathbb{C}^{A}:$

$$
(|v\rangle\langle t|)|x\rangle=|v\rangle(\langle t||x\rangle)= \begin{cases}|v\rangle & \text { if } t=x \\ \mathbf{0} & \text { otherwise } \quad "|v\rangle\langle t| \approx t \mapsto v "\end{cases}
$$

Evolution of isolated systems: Linear map $U \in \mathbf{L}\left(\mathbb{C}^{A}, \mathbb{C}^{A}\right)$

$$
U=\sum_{x, y \in A} u_{x, y}|y\rangle\langle x|
$$

which is an isometry $\left(U^{\dagger} U=I\right)$.

## Observation

$$
\text { Let } \mathbf{\Phi}=\sum_{x \in A} \alpha_{x}|x\rangle
$$

(Full) measurement in standard basis:
The probability to observe $a \in A$ is $\left|\alpha_{a}\right|^{2}$.
If $a \in A$ is observed, the state becomes $\boldsymbol{\Phi}_{a}=|a\rangle$.

Partial measurement in standard basis: Let $K=\left\{K_{\lambda}, \lambda \in \Lambda\right\}$ be a partition of $A$.

The probability to observe $\lambda \in \Lambda$ is $p_{\lambda}=\sum_{a \in K_{\lambda}}\left|\alpha_{a}\right|^{2}$
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$$
\mathbf{\Phi}_{\lambda}=\frac{1}{\sqrt{p_{\lambda}}} P_{\lambda} \boldsymbol{\Phi}=\frac{1}{\sqrt{p_{\lambda}}} \sum_{a \in K_{\lambda}} \alpha_{a}|a\rangle
$$

where $P_{\lambda}=\sum_{a \in K_{\lambda}}|a\rangle\langle a|$.

## Deterministic Turing Machine (DTM)

Classical Turing machine $(Q, \Sigma, \delta)$ :

$$
\delta: Q \times \Sigma \rightarrow Q \times \Sigma \times\{-1,0,1\}
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$(q, T, x) \in Q \times \Sigma^{*} \times \mathbb{Z}$ is a classical configuration.

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## Quantum Turing Machine (QTM)

Quantum Turing machine $M=(Q, \Sigma, \delta)$ :

$$
\delta: Q \times \Sigma \times Q \times \Sigma \times\{-1,0,1\} \rightarrow \mathbb{C}
$$



A quantum configuration is a superposition of classical configurations

$$
\sum_{q \in Q, T \in \Sigma^{*}, x \in \mathbb{Z}} \alpha_{q, T, x}|q, T, x\rangle \in \mathbb{C}^{Q \times \Sigma^{*} \times \mathbb{Z}}
$$

## Evolution operator

$$
U_{M}=\sum_{\substack{ \\p \in O, \sigma \in \Sigma, d \in\{-1.0 .1\}, T \in \Sigma^{*}, x \in \mathbb{Z}}} \delta\left(p, T_{x}, q, \sigma, d\right)\left|q, T_{x}^{\sigma}, x+d\right\rangle\langle p, T, x|
$$

A QTM $(Q, \Sigma, \delta)$ has to satisfy some well-formedness conditions...

## Well-formedness conditions

Definition: A QTM $M$ is well-formed iff $U_{M}$ is an isometry, i.e. $U_{M}^{\dagger} U_{M}=I$

- The evolution of the machine does not violate the postulates of quantum mechanics.
- During the computation, the machine is isolated from the rest of the universe.


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## Halting of QTM



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If the halting state is not reached, the computation is useless.

## Halting of QTM



Halting qubit (Ad hoc)

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## ‘Un-isolated' QTM

Isolation assumption is probably too strong

- technical issues like the halting of QTM,
- models of QC (one-way model, measurement-only model) based on measurements.
- PTM and DTM are not well-formed QTM (reversible DTM does)
- quest of a universal QTM: a classical control is required.


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## Modelling Environment: Observed QTM

Environment is modelled as a partial measurement of the configuration, characterised by a partition $K=\left\{K_{\lambda}\right\}_{\lambda \in \Lambda}$ of $Q \times \Sigma^{*} \times \mathbb{Z}$.

Definition: For a given QTM $M=(Q, \Sigma, \delta)$ and a given partition $K=\left\{K_{\lambda}\right\}_{\lambda \in \Lambda}$ of $Q \times \Sigma^{*} \times \mathbb{Z},[M]_{K}$ is an Observed Quantum Turing Machine (OQTM).

## Evolution of OQTM

One transition of $[M]_{K}$ is composed of:

1. partial measurement $K$ of the quantum configuration;
2. transition of $M$;
3. partial measurement $K$ of the quantum configuration.

Definition: An OQTM $[M]_{K}$ is well-observed iff

$$
\sum_{\lambda \in \Lambda} P_{\lambda} U_{M}^{\dagger} U_{M} P_{\lambda}=I
$$

where $P_{\lambda}=\sum_{(p, T, x) \in K_{\lambda}}|p, T, x\rangle\langle p, T, x|$.

## a weaker condition

Lemma: If a QTM $M$ is well-formed then $[M]_{K}$ is a well-observed OQTM for any $K$.


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Proof:

$$
\begin{aligned}
\sum_{\lambda \in \Lambda} P_{\lambda} U_{M}^{\dagger} U_{M} P_{\lambda} & =\sum_{\lambda \in \Lambda} P_{\lambda} P_{\lambda} \\
& =\sum_{\lambda \in \Lambda} P_{\lambda} \\
& =\sum_{\lambda \in \Lambda} \sum_{p, T, x \in K_{\lambda}}|p, T, x\rangle\langle p, T, x| \\
& =\sum_{p, T, x \in Q \times \Sigma^{*} \times \mathbb{Z}}|p, T, x\rangle\langle p, T, x| \\
& =I
\end{aligned}
$$

## Example: halting of QTM

For a given QTM $M=(Q, \Sigma, \delta)$ s.t. $q_{h} \in Q$ is the unique halting state.

$$
\begin{aligned}
& K_{h}=\left\{q_{h}\right\} \times \Sigma^{*} \times \mathbb{Z} \\
& K_{\bar{h}}=K \backslash K_{h}
\end{aligned}
$$

$[M]_{\left\{K_{h}, K_{\bar{h}}\right\}}$ evolves as follows:


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## OQTM more expressive than QTM

Lemma: For any DTM $M=(Q, \Sigma, \delta),[M]_{\left\{\{c\}, c \in Q \times \Sigma^{*} \times \mathbb{Z}\right\}}$ is a well-observed OQTM.

## OQTM, a too powerful model ?!?

Theorem: There is a well-observed OQTM $\left[M_{h}\right]_{K_{h}}$ for deciding (with high probability), for any DTM $M$ and any input $u$, whether $M$ halts on input $u$.

## (Proof) Hadamard QTM

Let $M_{h}=\left(\left\{q_{0}, q_{1}, q_{2}, q_{h}, q_{\bar{h}}\right\}, \Sigma, \delta_{h}\right)$ be a well-formed QTM, s.t. $q_{h}$ and $q_{\bar{h}}$ are the halting states and for $\sigma \in \Sigma$

$$
\begin{aligned}
\delta_{h}\left(q_{0}, \sigma, q_{1}, \sigma, 0\right) & =1 / \sqrt{2} \\
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\delta_{h}\left(q_{1}, \sigma, q_{\bar{h}}, \sigma, 0\right) & =1 / \sqrt{2} \\
\delta_{h}\left(q_{2}, \sigma, q_{h}, \sigma, 0\right) & =1 / \sqrt{2} \\
\delta_{h}\left(q_{2}, \sigma, q_{\bar{h}}, \sigma, 0\right) & =-1 / \sqrt{2}
\end{aligned}
$$

$\forall w \in \Sigma^{*}$,

$$
\begin{aligned}
U_{M_{h}}^{2}\left|q_{0}, w\right\rangle & =U_{M_{h}}\left(\frac{1}{\sqrt{2}}\left(\left|q_{1}, w\right\rangle+\left|q_{2}, w\right\rangle\right)\right) \\
& =\frac{1}{2}\left(\left|q_{h}, w\right\rangle+\left|q_{\bar{h}}, w\right\rangle+\left|q_{h}, w\right\rangle-\left|q_{\bar{h}}, w\right\rangle\right) \\
& =\left|q_{h}, w\right\rangle
\end{aligned}
$$

For any DTM $M$ and any input $u$, let $w_{M, u} \in \Sigma^{*}$ be an 'encoding' of $M$ and $u$.

$$
\begin{aligned}
& K_{0}=\left\{\left(q_{1}, w_{M, u}\right) \text { s.t. } M(u) \text { does not halt }\right\} \cup\left\{\left(q_{\bar{h}}, w\right)\right\} \\
& K_{1}=\left\{(q, w) \text { s.t. }(q, w) \notin K_{1}\right\}
\end{aligned}
$$

What is the evolution of $\left[M_{h}\right]_{\left\{K_{0}, K_{1}\right\}}$ if the initial configuration is $\left(q_{0}, w_{M, u}\right)$ ?

## - If $M(u)$ halts, then $\left(q_{1}, w_{M, u}\right),\left(q_{2}, w_{M, u}\right) \in K_{1}$, thus the evolution $\left.q_{0}, w_{M, u}\right\rangle \rightarrow^{*}\left|q_{h}, w_{M, u}\right\rangle$ <br> - If $M(u)$ does not halt, then $\left(q_{1}, w_{M, u}\right) \in K_{0}$, and $\left(q_{2}, w_{M, u}\right) \in K_{1}$ moreover $\left(q_{\bar{h}}, w_{M, u}\right) \in K_{0}$ and $\left(q_{h}, w_{M, u}\right) \in K_{1}$, thus:



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$$
\left|q_{0}, w_{M, u}\right\rangle \rightarrow^{*} \begin{cases}\left|q_{h}, w_{M, u}\right\rangle & \text { with probability } 1 / 2 \\ \left|q_{\bar{h}}, w_{M, u}\right\rangle & \text { with probability } 1 / 2\end{cases}
$$

## Towards a new definition of OQTM

- Initial proposition: $K$ is a partition of $Q \times \Sigma^{*} \times \mathbb{Z}$.
- Focus on the (classical) control: $K$ is a partition of $Q \times \mathbb{Z}$.
> $\left[M_{h}\right]_{K}$ is well observed and decides (with high probability), for any DTM $M$ and any input $u$, whether $M$ halts on input $u$.
- Finite partition: $K$ is a partition of $Q \times \Sigma$. ( $Q$ : internal states; $\Sigma$ : symbol pointed out by the head.)


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## Simulation

Theorem: For any well-observed OQTM $[M]_{K}$ there exists a well-formed QTM $M^{\prime}$ which simulates $[M]_{K}$ within a quadratic slowdown.

## Step one

If $M=(Q, \Sigma, \delta)$ and $K=\left\{K_{\lambda}\right\}_{\lambda \in \Lambda}$, let $\tilde{M}=(Q, \Sigma, \Lambda, \tilde{\delta})$ be a 2-tape QTM s.t.

$$
\tilde{\delta}(p, \tau,\lrcorner, q, \sigma, \lambda, d,+1)=\left\{\begin{array}{ll|l|l|l|l|l|l|l}
\delta(p, \tau, q, \sigma, d) & \text { if }(p, \tau) \in K_{\lambda} \\
0 & & & \text { otherwise }
\end{array}\right\}
$$

Lemma: $\tilde{M}$ is well formed.

## Step two

Lemma: $[\tilde{M}]_{\tilde{K}}$ simulates $[M]_{K}$, where $\tilde{K}=\{Q \times \Sigma \times\{\lambda\}\}_{\lambda \in \Lambda}$


## Step three

Since they act on distinct systems (the second head always moves to the right), the measurements can be postponed to the end of the computation:

Lemma: $\tilde{M}$ simulates $[\tilde{M}]_{\tilde{K}}$.
Lemma: There exists a well-formed 1 -tape QTM $M^{\prime}$ which simulates $\tilde{M}$ within a quadratic slowdown.

## Conclusion

- OQTM: extension of QTM with measurements;
- a more expressive (but not overpowerfull) machine: QTM, DTM, halting QTM.


## Perspectives:

- Universal quantum Turing machine;
- what is the minimal $k$ for which any OQTM $[M]_{K}$ can be efficiently simulated by an OQTM $\left[M^{\prime}\right]_{K^{\prime}}$ where all regions of $K^{\prime}$ have a size less than $k$ ?

