FPT results through potential maximal cliques

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in collaboration with
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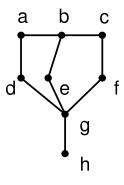
Univ. Orléans, INSA Centre Val de Loire, LIFO EA 4022, Orléans , France

JGA 2015, Orléans, France November 4, 2015





Minimal separators



Definition

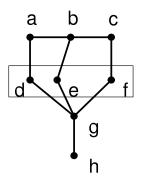
 $S \subseteq V$ is a minimal a, b-separator if S separates a

and b and it is inclusion-minimal for this property.

Definition

S is a minimal separator of G there exist vertices a, b s.t. S is a minimal a, b-separator.

Minimal separators



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S is a minimal separator of G there exist vertices a, b s.t. S is a minimal a, b-separator.

Potential maximal cliques

Definition

A set of vertices Ω is a potential maximal clique of G if is a maximal clique in some minimal triangulation of G.

Proposition (Bouchitté, Todinca 2001)

The number of potential maximal cliques is polynomial in the number of minimal separators.

Minimal separators and \mathcal{G}_{poly}

Definition

For a polynomial poly, let \mathcal{G}_{poly} be the class of graphs such that $G \in \mathcal{G}_{poly}$ if G has at most poly(n) minimal separators.

Class	minimal separators	potential maximal cliques
Weakly chordal	$\mathcal{O}(n^2)$	$\mathcal{O}(n^2)$
Chordal	$\mathcal{O}(n)$	$\mathcal{O}(n)$
Polygon-circle	$\mathcal{O}(n^2)$	$\mathcal{O}(n^3)$
Circle	$\mathcal{O}(n^2)$	$\mathcal{O}(n^3)$
Circular arc	$\mathcal{O}(n^2)$	$\mathcal{O}(n^3)$
<i>d</i> -trapezoid	$\mathcal{O}(n^d)$	$\mathcal{O}(n^{d+2})$

When the input graph belongs to \mathcal{G}_{poly} we can find in polynomial time a MAXIMUM INDUCED:

- Independent Set, Forest, Path, Matching
- Subgraph With no cycles $\geq I$, Outerplanar
- SUBGRAPH WITH NO CYCLES OF LENGTH 0 mod /

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- Subgraph With no cycles of Length 0 mod /

For $t \ge 0$ and \mathcal{P} a CMSO property:

Optimal Induced Subgraph for ${\mathcal P}$ and t

Input: A graph G = (V, E)

Output A largest induced subgraph G[F] s.t.

- $tw(G[F]) \leq t$,
- G[F] satisfies \mathcal{P} .

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Theorem (Fomin, Todinca, Villanger, 2015)

Optimal Induced Subgraph for \mathcal{P} and t on \mathcal{G}_{poly} is solvable in polynomial time.

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Theorem (Fomin, Todinca, Villanger, 2015)

OPTIMAL INDUCED SUBGRAPH FOR \mathcal{P} AND t is solvable time $\mathcal{O}(\#\text{POTENTIAL MAXIMAL CLIQUES} \cdot n^{t+cst} \cdot f(\mathcal{P}, t))$.

In this talk, two extensions:

- 1) Theorem (Fomin, Liedloff, M., Todinca. SWAT 2014) OPTIMAL INDUCED SUBGRAPH FOR \mathcal{P} AND t can be solved in time $\mathcal{O}^*(4^{vc})$ and $\mathcal{O}^*(1.7347^{mw})$.
- 2) Definition $(\mathcal{G}_{poly} + kv)$ $G \in \mathcal{G}_{poly} + kv$ if there exists a set $M \subset V$ called modulator, |M| < k s.t. $G - M \in \mathcal{G}_{poly}$.

Theorem (Liedloff, M. and Todinca. WG 2015)

OPTIMAL INDUCED SUBGRAPH FOR \mathcal{P} AND t ON $\mathcal{G}_{poly} + kv$ with parameter k is fixed-parameter tractable, when the modulat

with parameter k is fixed-parameter tractable, when the modulator is also part of the input.

First result

Theorem (Fomin, Todinca, Villanger, 2015)

Optimal Induced Subgraph for \mathcal{P} and t is solvable time $\mathcal{O}(\#\text{Potential maximal cliques} \cdot n^{t+cst} \cdot f(\mathcal{P},t)).$

Our result:

Theorem

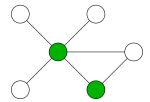
The number of potential maximal cliques is bounded by

- O*(4^{vc})
- $\mathcal{O}^*(1.7347^{\text{mw}})$

Vertex cover

Definition

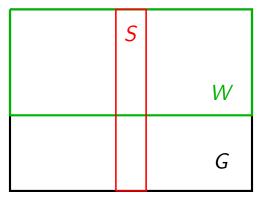
The vertex cover of a graph G, denoted by vc(G), is the minimum number of vertices that cover all edges of the graph.

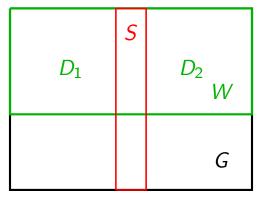


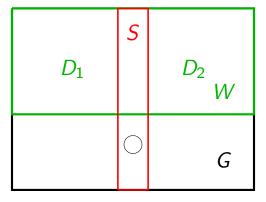
- The number of minimal separators is bounded by 3^{vc}
- The number of potential maximal cliques is bounded by $\mathcal{O}^*(4^{vc})$

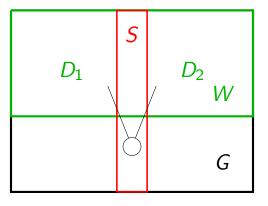


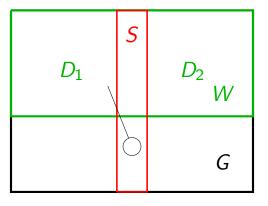


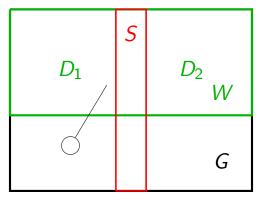


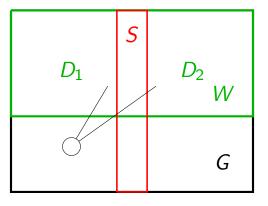


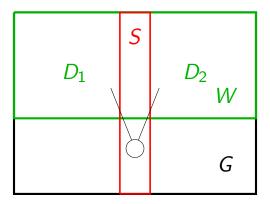












For any vertex cover W

$$S \rightarrow (S^W, D_1, D_2) = W$$

$$S = S^W \cup \{x \in V \setminus W \mid N(x) \text{ intersects both } D_1 \text{ and } D_2\}$$

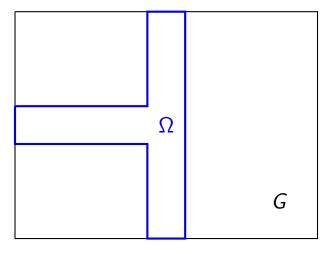
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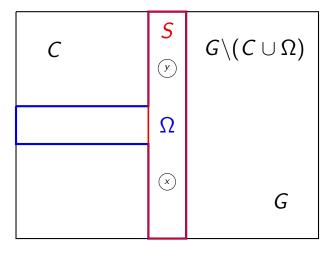
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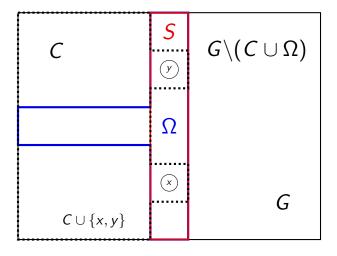
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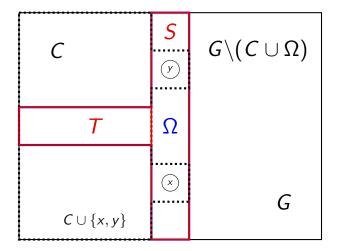
Theorem

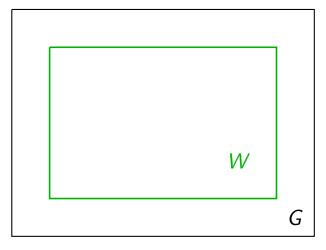
- Number of minimal separators is $\mathcal{O}(3^{\text{vc}})$
- They can be listed in time O*(3^{vc})

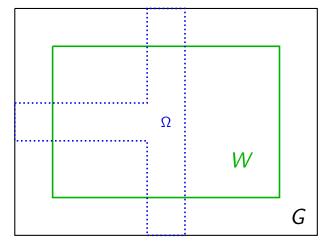


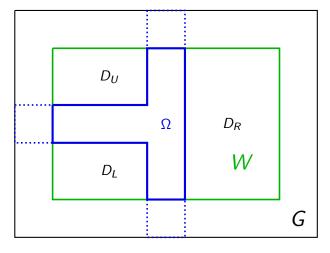


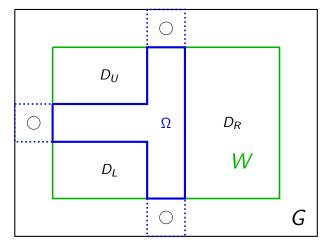


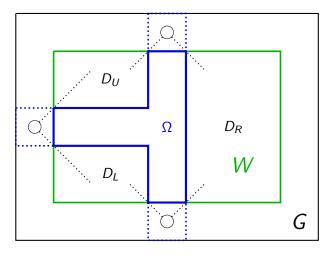












Vertex cover and pmc

For any vertex cover W

$$\Omega \to (\Omega^W, D_R, D_U, D_L) = W$$

$$\Omega = \Omega^{W}$$

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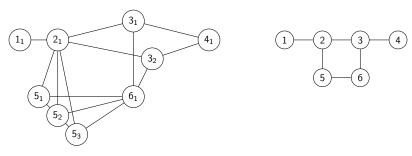
Theorem

- Number of potential maximal cliques is $\mathcal{O}^*(4^{\text{vc}})$
- They can be listed in time $\mathcal{O}^*(4^{\text{vc}})$

Modular width

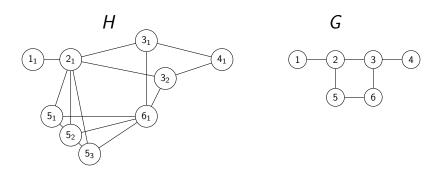
Definition

The modular width mw(G) can be defined as the maximum degree of a prime node in the modular decomposition tree of G

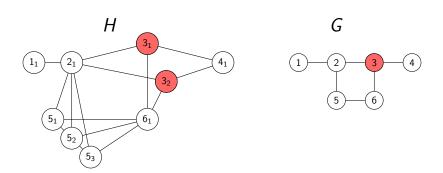


- The number of minimal separators is bounded by $\mathcal{O}^*(1.6181^{\text{mw}})$,
- The number of potential maximal cliques is bounded by $\mathcal{O}^*(1.7347^{\mathrm{mw}})$.

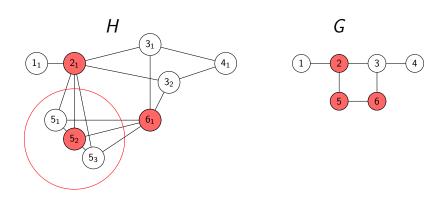
Modular width and minimal separators



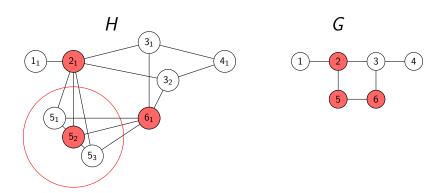
Modular width and minimal separators



Modular width and minimal separators



Modular width and minimal separators



Theorem (Fomin, Villanger (2010))

Every n-vertex graph has $\mathcal{O}(1.6181^n)$ minimal separators and $\mathcal{O}(1.7347^n)$ potential maximal cliques.

Conclusion

Theorem

Optimal Induced Subgraph for $\mathcal P$ and t can be solved in time $\mathcal O^*(4^{vc})$ and $\mathcal O^*(1.7347^{mw})$

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Also..

- (Weighted) TREEWIDTH,
- (Weighted) MINIMUM FILL IN,
- Treelength.

Are solvable in time $\mathcal{O}^*(\# pmc)$ ([Gysel], [Lokshtanov],..)

Conclusion

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Are solvable in time \mathcal{O}^*(\# \, \text{pmc}) ([Gysel], [Lokshtanov],..) (then in time \mathcal{O}^*(4^{\text{vc}}) and \mathcal{O}^*(1.7347^{\text{mw}})).
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Theorem

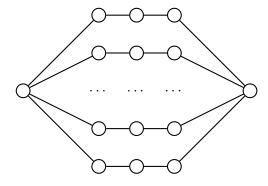
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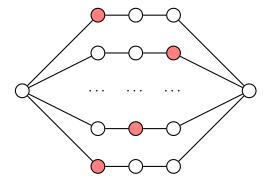
Also..

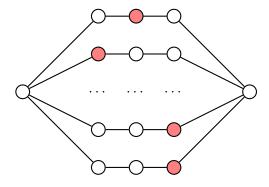
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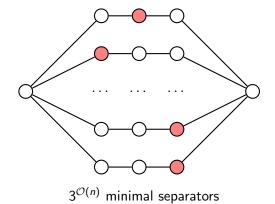
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- Running times that are single exponential in the parameter.
- This result covers both sparse and dense families of graphs.

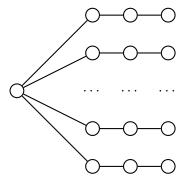


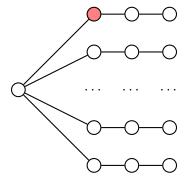


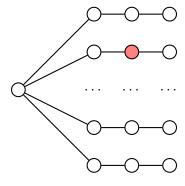


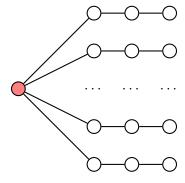


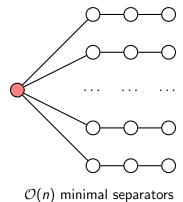
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Second result

Definition $(\mathcal{G}_{poly} + kv)$

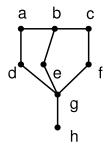
 $G \in \mathcal{G}_{poly} + kv$ if there exists a set $M \subset V$ called modulator, $|M| \leq k$ s.t. $G - M \in \mathcal{G}_{poly}$.

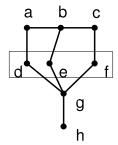
Theorem (Liedloff, M. and Todinca. WG 2015)

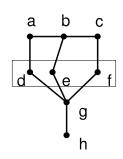
Optimal Induced Subgraph for \mathcal{P} and t on $\mathcal{G}_{poly}+kv$ with parameter k is fixed-parameter tractable, when the modulator is also part of the input.

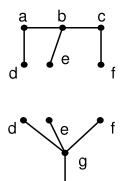
The tools

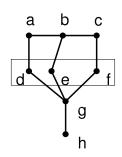
- Tools from [Fomin, Villanger, 2010] and [Fomin, Todinca, Villanger, 2015] for computing a MAXIMUM INDUCED SUBGRAPH OF TREEWIDTH t:
 - Decompositions with minimal separators.
 - Potential maximal cliques
 - Dynamic programming over all minimal tree decompositions of the input graphs, using potential maximal cliques.
- Results [Bodlaender, Kloks, 1996]
 - Given a graph G and a tree decomposition of width at most k+t, determine if G has treewidth t in time $\mathcal{O}(f(t+k)n)$, with $f(x) = 2^{\mathcal{O}(x^3 \log(x))}$.

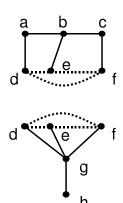


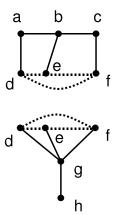


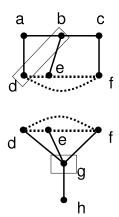


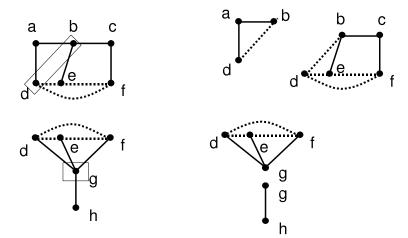


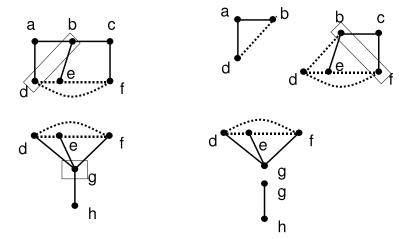


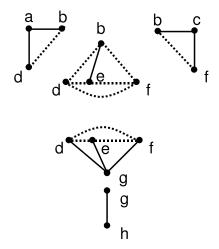


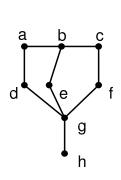


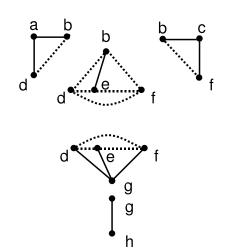


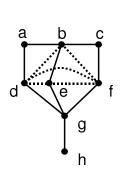


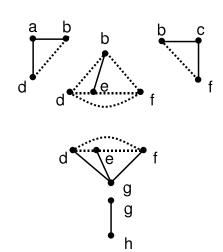




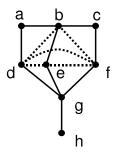






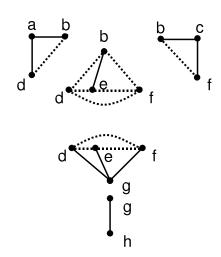


Decomposing with minimal separators



Theorem (Parra, Schaeffler 97)

Decomposing through minimal separators \rightarrow minimal tree decompositions.



Potential maximal cliques

Definition

A set of vertices Ω is a potential maximal clique of G if is a maximal clique in some minimal triangulation of G.

Definition

A set of vertices Ω is a potential maximal clique of G if there is a minimal tree decomposition TG of G such that Ω is a bag in TG.

Proposition (Bouchitté, Todinca 2001)

The number of potential maximal cliques is polynomial in the number of minimal separators.

Dynamic programming over minimal separators...

Maximum induced subgraph of treewidth t on \mathcal{G}_{polv}

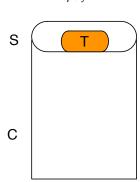
S: minimal separator of G

C: component of G - S

T: a subset of S of size < t + 1

OPT(S, C, T) the size of the largest partial solution G[F] s.t.

- $F \subset S \cup C$
- $T = F \cap S$



Dynamic programming over minimal separators...

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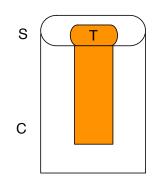
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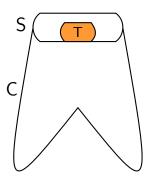
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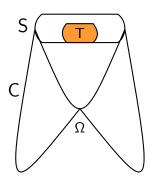
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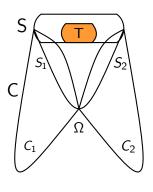






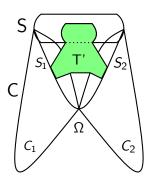
OPT(S, C, T):

• guess the potential maximal clique Ω splitting $S \cup C$

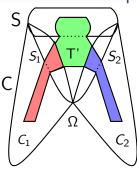


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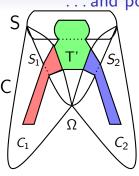


- guess the potential maximal clique Ω splitting $S \cup C$
- and $T \subseteq T'$ the bag of F that intersects Ω , $|T'| \le t + 1$.



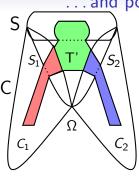
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$$OPT(S_1, C_1, T' \cap S_1) + OPT(S_2, C_2, T' \cap S_2) + |T' \setminus \{S_1 \cup S_2\}|$$



- guess the potential maximal clique Ω splitting $S \cup C$
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$$OPT(S, C, T) = \max_{S \subset \Omega \subset C \cup S, T \subset T' \subset \Omega} (OPT(S_1, C_1, T' \cap S_1) + OPT(S_2, C_2, T' \cap S_2) + |T' \setminus \{S_1 \cup S_2\}|)$$



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Running time: $O(n^{t+cst} \cdot \# \text{potential maximal cliques})$ Key lemma [Fomin, Villanger 2010]: we don't miss solutions. Maximum induced subgraph of treewidth t on $\mathcal{G}_{polv} + kv$

 F^{M} : A subset of the modulator of size k'.

S: minimal separator of G'

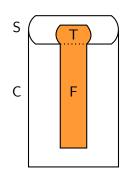
C: component of G' - S

T: a subset of S of size < t + 1

OPT(S, C, T) the size of the largest partial solution G[F] s.t.

- $F^M = F \cap M$
- F\M ⊆ S ∪ C
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Dynamic programming over minimal separators...

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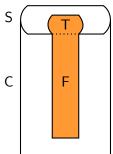
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This way we build a tree decomposition of G[F] of width $\leq t + k'$

[Bodlaender, Kloks, 1996]:

• Algorithm that takes as input a graph with a tree decomposition of width at most t+k and decides if this graph has treewidth t in time $\mathcal{O}(f(t+k)n)$, with $f(x)=2^{\mathcal{O}(x^3\log(x))}$

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- if two partial solutions are glued, then the characteristic of the resulting graph can be computed from the characteristics of each part.

Dynamic programming over minimal separators...

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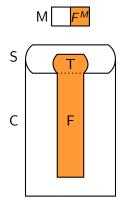
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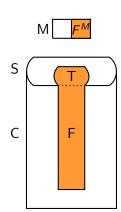
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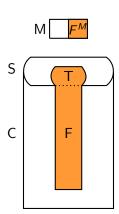
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To sum up

Theorem

Optimal Induced Subgraph for \mathcal{P} and t on $\mathcal{G}_{poly} + kv$ is solvable in time $\mathcal{O}(n^t \cdot poly'(n) \cdot f(t+k,\mathcal{P}))$ when the modulator is also part of the input.

t	\mathcal{P}	f
any	any	tower of exponentials
any	none	$2^{\mathcal{O}((t+k)^3\log(t+k))}$
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roduction First result Conclusion 1 Second result Conclusion 2

Discussion

What if the modulator is not a part of the input?

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Deletion to \mathcal{G}_{poly}

Input: A graph G = (V, E) and a constant k

Parameter: k

Output: A set $M \subseteq V$ of size at most k s.t. G - M belongs to

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