

Small semi-weakly universal Turing machines

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Some surprisingly simple processes are computationally powerful

- Aim 1:** To find the border between decidability and undecidability, with respect to the complexity measure of universal program size, e.g. by finding small universal machines or showing that none exist
- Aim 2:** To categorise trade-offs between universal-program size, and time, space and encoding complexity

Standard model & generalisations

Turing machine definition

One bi-infinite tape, one head, deterministic, usual blank symbol

- Most of the published work on the size of universal Turing machines has been for the standard model
 - A good (benchmark) model to compare new techniques
 - A lot of open questions remain
- There have also been results for **restrictions** and **generalisations** of the standard model
- Significant restrictions tend to have much larger programs
- Significant generalisations lead to smaller programs
- E.g. more **tapes**, **dimensions**, **heads**; **couple with a FA**, etc.
- Here we look at a generalisation called **weakness**

Standard, semi-weak, & weak machines

Turing machine Definition

One bi-infinite tape, one head, one-dimensional, deterministic, usual blank symbol

Semi-weak Turing machine definition

One bi-infinite tape, one head, one-dimensional, deterministic, (constant) **blank word** in **one** direction, blank symbol in the other

Weak Turing machine definition

One bi-infinite tape, one head, deterministic, (constant) **blank word** repeated to left and **another blank word** to right

Some known results:

- small (standard) universal Turing machines
 - 2-tag simulators
 - bi-tag simulators
- small semi-weakly universal Turing machines
 - simulate Turing machines directly
- small weakly universal Turing machines
 - rule 110 simulators (new results since proceedings version)

New result:

- new small semi-weakly universal Turing machines
 - cyclic tag system simulators

Some known results:

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New result:

- new small semi-weakly universal Turing machines
 - cyclic tag system simulators

History of weak machines

- Watanabe and Minsky
- Watanabe found smaller machines by generalising the model
- No results for a number of years
- Cook, Wolfram, Eppstein found significantly smaller machines
- Recently improved by Neary, Woods on the size of all weak machines (since proceedings; see arXiv)

Figure

New semi-weakly universal machines

- Here we give two new semi-weak machines
 - (4,5) and (3,7)
- Cyclic tag simulators
- Symmetric with Watanabe's semi-weak machines
 - (5,4) and (7,3)

Figure

Time complexity of small machines

- Until recently, almost all of the smallest universal Turing machines simulated **via 2-tag systems**
 - (modified tag systems, cyclic tag systems, rule 110, etc.)
- The Cocke-Minsky 2-tag universality proof: **exponentially slow**
- Now we know that 2-tag systems, bi-tag systems, cyclic tag systems, rule 110, run in **polynomial time**
- The smallest known universal Turing machines are efficient!
- **Previous belief:** there is an exponential trade-off between UTM program size complexity, and time/space complexity
- **Current belief:** there is little evidence for such a claim, as now *all* of the smallest UTMs are efficient

Time complexity: a plea

- Why are efficient simulations important?
- Universality of physical/biological/other systems that embed simple systems/UTMs
- Simple/small machines may be easier/better to embed in other systems
- Exponentially slow computations are exponentially boring!
- Clearer understanding of computation process
- P. van Emde Boas Class 1/Poly time Church-Turing
- It would be interesting to prove there is a polynomial (or even exponential) trade-off between program size and simulation time!

Time complexity: a plea

- Difficulty of prediction: NC versus P-completeness
- Machine prediction problem: Given an initial configuration and a time bound t in unary, will the machine ever reach a given state/configuration/etc. in time t ?
- Exp slow simulators can not even solve in P problems in poly time
- Prediction problem has finite initial condition; even for weak machines!

Cyclic tag systems were used by M. Cook, S. Wolfram:

Turing machine \mapsto 2-tag system
 \mapsto cyclic tag system \mapsto Rule 110 \mapsto small weak UTM

Cyclic tag system

A list of p binary words (appendants), $C = \alpha_0, \alpha_1, \dots, \alpha_{p-1}$.

Configuration:

$$\alpha_0, \dots, \mathbf{\alpha}_m, \dots, \alpha_{p-1} \quad x_0 x_1 \dots x_\ell$$

Computation step:

- 1 $x_0 = 0 \Rightarrow$ delete x_0 , increment marker to $m + 1 \pmod p$.
- 2 $x_0 = 1 \Rightarrow$ delete x_0 , increment marker to $m + 1 \pmod p$, and append α_m to the right of the dataword.

Cyclic tag systems

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$$\begin{array}{l} \alpha_0, \dots, \alpha_m, \dots, \alpha_{p-1} \quad x_0 x_1 \dots x_\ell \\ \vdash \quad \alpha_0, \dots, \alpha_m, \alpha_{m+1}, \dots, \alpha_{p-1} \quad x_1 \dots x_\ell \end{array}$$

Cyclic tag systems

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$$\begin{array}{l} \alpha_0, \dots, \alpha_m, \dots, \alpha_{p-1} \quad x_0 x_1 \dots x_\ell \\ \vdash \alpha_0, \dots, \alpha_m, \alpha_{m+1}, \dots, \alpha_{p-1} \quad x_1 \dots x_\ell \alpha_m \end{array}$$

Cyclic tag system

Example (Appendants: $C = 00, 010, 11$ Input word: 0010010)

	appendants	dataword
	00, 1010, 10	0010010
┆	00, 1010 , 10	010010
┆	00, 1010, 10	10010
┆	00 , 1010, 10	0010 10
┆	00, 1010 , 10	01010
┆	00, 1010, 10	1010
┆	00 , 1010, 10	010 10
┆	00, 1010 , 10	1010
┆	00, 1010, 10	010 1010
┆	...	

Cyclic tag system

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	00 , 1010, 10	0 010010
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┆	00, 1010, 10	10010
┆	00 , 1010, 10	0010 10
┆	00, 1010 , 10	01010
┆	00, 1010, 10	1010
┆	00 , 1010, 10	010 10
┆	00, 1010 , 10	1010
┆	00, 1010, 10	010 1010
┆	...	

Cyclic tag system

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	00 , 1010, 10	0010010
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┆	00, 1010, 10	10010
┆	00 , 1010, 10	0010 10
┆	00, 1010 , 10	01010
┆	00, 1010, 10	1010
┆	00 , 1010, 10	010 10
┆	00, 1010 , 10	1010
┆	00, 1010, 10	010 1010
┆	...	

Cyclic tag system

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┆	00, 1010, 10	1 0010
┆	00 , 1010, 10	0010 10
┆	00, 1010 , 10	01010
┆	00, 1010, 10	1010
┆	00 , 1010, 10	010 10
┆	00, 1010 , 10	1010
┆	00, 1010, 10	010 1010
┆	...	

Cyclic tag system

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┆	00, 1010, 10	10010
┆	00 , 1010, 10	0010 10
┆	00, 1010 , 10	01010
┆	00, 1010, 10	1010
┆	00 , 1010, 10	010 10
┆	00, 1010 , 10	1010
┆	00, 1010, 10	010 1010
┆	...	

4-state, 5-symbol machine

- Simulates cyclic tag systems where **dataword** and **appendants** are from $\{0, 10\}^*$, i.e. **no consecutive 1 symbols**
- Simulates in polynomial time
- The start state is u_1 and the blank symbol is \emptyset
- Table of behaviour for $U_{4,5}$:

	u_1	u_2	u_3	u_4
0	$\lambda L u_1$	$\lambda L u_2$	$\emptyset R u_3$	$\emptyset R u_4$
1	$\emptyset R u_2$	$1 L u_2$	$1 R u_3$	$1 R u_4$
λ	$0 R u_2$	$0 R u_1$	$0 R u_4$	$0 R u_3$
\emptyset		$0 L u_2$	$0 L u_2$	$1 L u_2$
$\cancel{1}$	$0 L u_2$	$\lambda L u_3$		

Encoding for 4-state, 5-symbol machine

Given a CTS configuration

Example ($C = 00, 010, 11$, input word 011)

00, 1010, 10 0010010

Reverse order of symbols in each appendant

00, 0101, 01 0010010

Reverse order of appendants

01, 0101, **00** 0010010

Dataword requires no special encoding

Encoding for 4-state, 5-symbol machine

Cyclic tag system, with dataword:

01, 0101, **00** 0010010

Encode appendants via

- $\langle 0 \rangle = 0\lambda\cancel{1}0$
- $\langle 1 \rangle = 00\lambda\cancel{1}$

And separate with λ

$\lambda 0\lambda\cancel{1}000\lambda\cancel{1} \lambda 0\lambda\cancel{1}000\lambda\cancel{1}0\lambda\cancel{1}000\lambda\cancel{1} \lambda 0\lambda\cancel{1}00\lambda\cancel{1}0$ 0010010

Appendants repeated on left. Blank symbol \emptyset repeated on right

$\dots \lambda 0\lambda\cancel{1}000\lambda\cancel{1} \lambda 0\lambda\cancel{1}000\lambda\cancel{1}0\lambda\cancel{1}000\lambda\cancel{1} \lambda 0\lambda\cancel{1}00\lambda\cancel{1}0 \lambda 0\lambda\cancel{1}000\lambda\cancel{1} \lambda 0\lambda\cancel{1}000\lambda\cancel{1}0\lambda\cancel{1}000\lambda\cancel{1} \lambda 0\lambda\cancel{1}00\lambda\cancel{1}0$ 0010010 $\emptyset\emptyset\dots$

Encoding for 4-state, 5-symbol machine

Cyclic tag system, with dataword:

01, 0101, 00 0010010

Encode appendants via

- $\langle 0 \rangle = 0\lambda\cancel{1}0$
- $\langle 1 \rangle = 00\lambda\cancel{1}$

And separate with λ

$\lambda 0\lambda\cancel{1}000\lambda\cancel{1} \lambda 0\lambda\cancel{1}000\lambda\cancel{1}0\lambda\cancel{1}000\lambda\cancel{1} \lambda 0\lambda\cancel{1}00\lambda\cancel{1}0$ 0010010

Appendants repeated on left. Blank symbol \emptyset repeated on right

... $\lambda 0\lambda\cancel{1}000\lambda\cancel{1} \lambda 0\lambda\cancel{1}000\lambda\cancel{1}0\lambda\cancel{1}000\lambda\cancel{1} \lambda 0\lambda\cancel{1}00\lambda\cancel{1}0 \lambda 0\lambda\cancel{1}000\lambda\cancel{1} \lambda 0\lambda\cancel{1}000\lambda\cancel{1}0\lambda\cancel{1}000\lambda\cancel{1} \lambda 0\lambda\cancel{1}00\lambda\cancel{1}0$ 0010010 $\emptyset\emptyset\emptyset \dots$

Encoding for 4-state, 5-symbol machine

Cyclic tag system, with dataword:

01, 0101, 00 0010010

Encode appendants via

- $\langle 0 \rangle = 0\lambda\cancel{1}0$
- $\langle 1 \rangle = 00\lambda\cancel{1}$

And separate with λ

$\lambda 0\lambda\cancel{1}000\lambda\cancel{1} \lambda 0\lambda\cancel{1}000\lambda\cancel{1}0\lambda\cancel{1}000\lambda\cancel{1} \lambda 0\lambda\cancel{1}00\lambda\cancel{1}0$ 0010010

Appendants repeated on left. Blank symbol \emptyset repeated on right

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Encoding for 4-state, 5-symbol machine

Cyclic tag system, with dataword:

01, 0101, 00 0010010

Encode appendants via

- $\langle 0 \rangle = 0\lambda\cancel{1}0$
- $\langle 1 \rangle = 00\lambda\cancel{1}$

And separate with λ

$\lambda 0\lambda\cancel{1}000\lambda\cancel{1} \lambda 0\lambda\cancel{1}000\lambda\cancel{1}0\lambda\cancel{1}000\lambda\cancel{1} \lambda 0\lambda\cancel{1}00\lambda\cancel{1}0$ 0010010

Appendants repeated on left. Blank symbol \emptyset repeated on right

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Simulation of reading 0

$00, 1010, 10$ 0010010
⊢ $00, \mathbf{1010}, 10$ 010010

$\lambda \mathbf{0} \lambda \cancel{1} 000 \lambda \cancel{1}$ $\lambda \mathbf{0} \lambda \cancel{1} 000 \lambda \cancel{1} 0 \lambda \cancel{1} 000 \lambda \cancel{1}$ $\lambda \mathbf{0} \lambda \cancel{1} 00 \lambda \cancel{1} 0$ 0010010

If we 'enter' $\langle 0 \rangle = \mathbf{0} \lambda \cancel{1} 0$ or $\langle 1 \rangle = 00 \lambda \cancel{1}$ in state u_1 it gets deleted:

$u_1, \dots 0 \lambda \cancel{1} \underline{0}$

We exit left in state u_1

Simulation of reading 0

00, 1010, 10 0010010
⊢ 00, **1010**, 10 010010

$\lambda 0 \lambda \cancel{1} 0 0 0 \lambda \cancel{1}$ $\lambda 0 \lambda \cancel{1} 0 0 0 \lambda \cancel{1} 0 \lambda \cancel{1} 0 0 0 \lambda \cancel{1}$ $\lambda 0 \lambda \cancel{1} 0 0 \lambda \cancel{1} 0$ 0010010

If we 'enter' $\langle 0 \rangle = 0 \lambda \cancel{1} 0$ or $\langle 1 \rangle = 0 0 \lambda \cancel{1}$ in state u_1 it gets deleted:

$u_1, \dots 0 \lambda \cancel{1} \lambda$

We exit left in state u_1

Simulation of reading 0

$00, 1010, 10$ 0010010
 $\vdash 00, \mathbf{1010}, 10$ 010010

$\lambda 0 \lambda \cancel{1} 0 0 0 \lambda \cancel{1}$ $\lambda 0 \lambda \cancel{1} 0 0 0 \lambda \cancel{1} 0 \lambda \cancel{1} 0 0 0 \lambda \cancel{1}$ $\lambda 0 \lambda \cancel{1} 0 0 \lambda \cancel{1} 0$ 0010010

If we 'enter' $\langle 0 \rangle = 0 \lambda \cancel{1} 0$ or $\langle 1 \rangle = 0 0 \lambda \cancel{1}$ in state u_1 it gets deleted:

$u_2, \dots 0 \underline{\lambda} 0 \lambda$

We exit left in state u_1

Simulation of reading 0

00, 1010, 10 0010010
⊢ 00, **1010**, 10 010010

$\lambda 0 \lambda \cancel{1} 0 0 0 \lambda \cancel{1}$ $\lambda 0 \lambda \cancel{1} 0 0 0 \lambda \cancel{1} 0 \lambda \cancel{1} 0 0 0 \lambda \cancel{1}$ $\lambda 0 \lambda \cancel{1} 0 0 \lambda \cancel{1} 0$ 0010010

If we 'enter' $\langle 0 \rangle = 0 \lambda \cancel{1} 0$ or $\langle 1 \rangle = 0 0 \lambda \cancel{1}$ in state u_1 it gets deleted:

$u_1, \dots 0 0 \underline{0} \lambda$

We exit left in state u_1

Simulation of reading 0

$00, 1010, 10$ 0010010
⊢ $00, \mathbf{1010}, 10$ 010010

$\lambda \mathbf{0} \lambda \cancel{1} 000 \lambda \cancel{1}$ $\lambda \mathbf{0} \lambda \cancel{1} 000 \lambda \cancel{1} 0 \lambda \cancel{1} 000 \lambda \cancel{1}$ $\lambda \mathbf{0} \lambda \cancel{1} 00 \lambda \cancel{1} 0$ 0010010

If we 'enter' $\langle 0 \rangle = \mathbf{0} \lambda \cancel{1} 0$ or $\langle 1 \rangle = \mathbf{00} \lambda \cancel{1}$ in state u_1 it gets deleted:

$u_1, \dots 00 \underline{\lambda} \lambda$

We exit left in state u_1

Simulation of reading 0

$00, 1010, 10$ 0010010
⊢ $00, \mathbf{1010}, 10$ 010010

$\lambda \mathbf{0} \lambda \cancel{1} 000 \lambda \cancel{1}$ $\lambda \mathbf{0} \lambda \cancel{1} 000 \lambda \cancel{1} 0 \lambda \cancel{1} 000 \lambda \cancel{1}$ $\lambda \mathbf{0} \lambda \cancel{1} 00 \lambda \cancel{1} 0$ 0010010

If we 'enter' $\langle 0 \rangle = \mathbf{0} \lambda \cancel{1} 0$ or $\langle 1 \rangle = 00 \lambda \cancel{1}$ in state u_1 it gets deleted:

$u_1, \dots \underline{0} \lambda \lambda \lambda$

We exit left in state u_1

Simulation of reading 0

$00, 1010, 10$ 0010010
⊢ $00, \mathbf{1010}, 10$ 010010

$\lambda 0 \lambda \cancel{1} 0 0 0 \lambda \cancel{1}$ $\lambda 0 \lambda \cancel{1} 0 0 0 \lambda \cancel{1} 0 \lambda \cancel{1} 0 0 0 \lambda \cancel{1}$ $\lambda 0 \lambda \cancel{1} 0 0 \lambda \cancel{1} 0$ 0010010

If we 'enter' $\langle 0 \rangle = 0 \lambda \cancel{1} 0$ or $\langle 1 \rangle = 0 0 \lambda \cancel{1}$ in state u_1 it gets deleted:

$u_1, \dots _ \lambda \lambda \lambda \lambda$

We exit left in state u_1

Simulation of reading 0

$00, 1010, 10 \quad 0010010$
 $\vdash \quad 00, \mathbf{1010}, 10 \quad 010010$

$u_1, \dots \lambda \mathbf{0\lambda\cancel{1}000\lambda\cancel{1}} \lambda \mathbf{0\lambda\cancel{1}000\lambda\cancel{1}0\lambda\cancel{1}000\lambda\cancel{1}} \lambda \mathbf{0\lambda\cancel{1}00\lambda\cancel{1}0} \quad \underline{0}010010$

If we 'enter' $\langle 0 \rangle = \mathbf{0\lambda\cancel{1}0}$ or $\langle 1 \rangle = \mathbf{00\lambda\cancel{1}}$ in state u_1 it gets deleted

$u_1, \dots \mathbf{0\lambda\cancel{1}\underline{0}} \quad \vdash^* \quad u_1, \dots _ \lambda\lambda\lambda\lambda$

We exit in state u_1

Simulation of reading 0

$00, 1010, 10 \quad 0010010$
 $\vdash \quad 00, \mathbf{1010}, 10 \quad 010010$

$u_1, \dots \lambda \mathbf{0\lambda\cancel{1}000\lambda\cancel{1}} \lambda \mathbf{0\lambda\cancel{1}000\lambda\cancel{1}0\lambda\cancel{1}000\lambda\cancel{1}} \lambda \mathbf{0\lambda\cancel{1}00\lambda\cancel{1}0} \quad \lambda 010010$

If we 'enter' $\langle 0 \rangle = \mathbf{0\lambda\cancel{1}0}$ or $\langle 1 \rangle = \mathbf{00\lambda\cancel{1}}$ in state u_1 it gets deleted

$u_1, \dots \mathbf{0\lambda\cancel{1}0} \quad \vdash^* \quad u_1, \dots _ \lambda \lambda \lambda \lambda$

We exit in state u_1

Simulation of reading 0

$00, 1010, 10 \quad 0010010$
 $\vdash \quad 00, \mathbf{1010}, 10 \quad 010010$

$u_1, \dots \lambda \mathbf{0\lambda\cancel{1}000\lambda\cancel{1}} \lambda \mathbf{0\lambda\cancel{1}000\lambda\cancel{1}} \mathbf{0\lambda\cancel{1}000\lambda\cancel{1}} \lambda \mathbf{0\lambda\cancel{1}0} \lambda\lambda\lambda\lambda \quad \lambda 010010$

If we 'enter' $\langle 0 \rangle = \mathbf{0\lambda\cancel{1}0}$ or $\langle 1 \rangle = \mathbf{00\lambda\cancel{1}}$ in state u_1 it gets deleted

$u_1, \dots \mathbf{0\lambda\cancel{1}0} \quad \vdash^* \quad u_1, \dots _ \lambda\lambda\lambda\lambda$

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Simulation of reading 0

$00, 1010, 10 \quad 0010010$
 $\vdash \quad 00, \mathbf{1010}, 10 \quad 010010$

$u_1, \dots \lambda 0 \lambda \cancel{1} 000 \lambda \cancel{1} \lambda 0 \lambda \cancel{1} 000 \lambda \cancel{1} 0 \lambda \cancel{1} 000 \lambda \cancel{1} \underline{\lambda \lambda \lambda \lambda \lambda \lambda \lambda \lambda} \quad \lambda 010010$

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$u_1, \dots 0 \lambda \cancel{1} \underline{0} \quad \vdash^* \quad u_1, \dots _ \lambda \lambda \lambda \lambda$

We exit in state u_1

Simulation of reading 0

00, 1010, 10 0010010
⊢ 00, **1010**, 10 010010

u_2 , ... λ 0 ~~λ~~ 1000 ~~λ~~ 1 ~~λ~~ λ 0 ~~λ~~ 1000 ~~λ~~ 1 ~~λ~~ 0 ~~λ~~ 1000 ~~λ~~ 1 ~~λ~~ 0 λ λ λ λ λ λ λ λ 010010

Move right, switching between two states, exit in state u_1 , iterate.

Simulation of reading 0

00, 1010, 10 0010010
⊢ 00, **1010**, 10 010010

ν_1 , ... λ 0 ~~λ~~ 1000 ~~λ~~ 1 λ 0 ~~λ~~ 1000 ~~λ~~ 10 ~~λ~~ 1000 ~~λ~~ 1 **00** λ λ λ λ λ λ λ 010010

Move right, switching between two states, exit in state ν_1 , iterate.

Simulation of reading 0

00, 1010, 10 0010010
⊢ 00, **1010**, 10 010010

u_2 , ... λ 0 ~~λ~~ 1000 ~~λ~~ 1 λ 0 ~~λ~~ 1000 ~~λ~~ 10 ~~λ~~ 1000 ~~λ~~ 1 **000** λ λ λ λ λ λ λ 010010

Move right, switching between two states, exit in state u_1 , iterate.

Simulation of reading 0

00, 1010, 10 0010010
⊢ 00, **1010**, 10 010010

ν_1 , ... λ 0 ~~λ~~ 1000 ~~λ~~ 1 λ 0 ~~λ~~ 1000 ~~λ~~ 10 ~~λ~~ 1000 ~~λ~~ 1 **0000** λ λ λ λ λ λ 010010

Move right, switching between two states, exit in state ν_1 , iterate.

Simulation of reading 0

00, 1010, 10 0010010
⊢ 00, **1010**, 10 010010

ν_2 , ... λ 0 ~~λ~~ 1000 ~~λ~~ 1 λ 0 ~~λ~~ 1000 ~~λ~~ 10 ~~λ~~ 1000 ~~λ~~ 1 **00000** λ λ λ λ λ 010010

Move right, switching between two states, exit in state ν_1 , iterate.

Simulation of reading 0

00, 1010, 10 0010010
⊢ 00, **1010**, 10 010010

ν_1 , ... λ 0 ~~λ~~ 1000 ~~λ~~ 1 ~~λ~~ λ 0 ~~λ~~ 1000 ~~λ~~ 1 ~~λ~~ 0 ~~λ~~ 1000 ~~λ~~ 1 ~~λ~~ **000000** λ λ λ λ 010010

Move right, switching between two states, exit in state ν_1 , iterate.

Simulation of reading 0

00, 1010, 10 0010010
⊢ 00, **1010**, 10 010010

u_2 , ... λ 0 ~~λ~~ 1000 ~~λ~~ 1 ~~λ~~ λ 0 ~~λ~~ 1000 ~~λ~~ 1 ~~λ~~ 0 ~~λ~~ 1000 ~~λ~~ 1 ~~λ~~ **0000000** λ λ λ 010010

Move right, switching between two states, exit in state u_1 , iterate.

Simulation of reading 0

00, 1010, 10 0010010
⊢ 00, **1010**, 10 010010

ν_1 , ... λ 0 ~~λ~~ 1000 ~~λ~~ 1 ~~λ~~ λ 0 ~~λ~~ 1000 ~~λ~~ 1 ~~λ~~ 0 ~~λ~~ 1000 ~~λ~~ 1 ~~λ~~ **00000000** λ λ 010010

Move right, switching between two states, exit in state ν_1 , iterate.

Simulation of reading 0

00, 1010, 10 0010010
⊢ 00, **1010**, 10 010010

ν_2 , ... λ 0 ~~λ~~ 1000 ~~λ~~ 1 λ 0 ~~λ~~ 1000 ~~λ~~ 10 ~~λ~~ 1000 ~~λ~~ 1 **00000000** $\underline{\lambda}$ 010010

Move right, switching between two states, exit in state ν_1 , iterate.

Simulation of reading 0

00, 1010, 10 0010010
⊢ 00, **1010**, 10 010010

u_1 , ... $\lambda 0 \lambda \cancel{1} 000 \lambda \cancel{1} \lambda 0 \lambda \cancel{1} 000 \lambda \cancel{1} 0 \lambda \cancel{1} 000 \lambda \cancel{1} 00000000$ 0010010

Move right, switching between two states, exit in state u_1 , iterate.

Simulation of reading 10

\vdash^2 00, 1010, **10** 10010
 00, **1010**, 10 01010

$u_1, \dots \lambda \cancel{0} \lambda \cancel{1} 0 \cancel{0} 0 \lambda \cancel{1} 0^{17} 0^9 \quad 00\underline{1}0010 \ \cancel{0}\cancel{0}\cancel{0} \dots$

Simulation of reading 10

\vdash^2 00, 1010, **10** 10010
 00, **1010**, 10 01010

$u_1, \dots \lambda \cancel{0} \lambda \cancel{1} 000 \lambda \cancel{1} 0^{17} 0^9$ 0010010 $\emptyset\emptyset\emptyset \dots$

$u_2, \dots \lambda \cancel{0} \lambda \cancel{1} 000 \lambda \cancel{1} 0^{17} 0^9$ 0000010 $\emptyset\emptyset\emptyset \dots$

Simulation of reading 10

00, 1010, **10** 10010
 \vdash^2 00, **1010**, 10 01010

u_1 , ... λ ~~0~~ ~~λ~~ ~~1~~ ~~0~~ ~~0~~ ~~λ~~ ~~1~~ $0^{17} 0^9$ 0010010 $\emptyset\emptyset\emptyset\dots$

u_2 , ... λ ~~0~~ ~~λ~~ ~~1~~ ~~0~~ ~~0~~ ~~λ~~ ~~1~~ $0^{17} 0^9$ 000010 $\emptyset\emptyset\emptyset\dots$

u_2 , ... λ ~~0~~ ~~λ~~ ~~1~~ ~~0~~ ~~0~~ ~~λ~~ ~~1~~ $0^{17} 0^9$ 000 λ 010 $\emptyset\emptyset\emptyset\dots$

Simulation of reading 10

00, 1010, **10** 10010
 \vdash^2 00, **1010**, 10 01010

u_1 , ... λ ~~0~~ ~~λ~~ ~~1~~ ~~0~~ ~~0~~ ~~λ~~ ~~1~~ $0^{17} 0^9$ 0010010 $\emptyset\emptyset\emptyset \dots$

u_2 , ... λ ~~0~~ ~~λ~~ ~~1~~ ~~0~~ ~~0~~ ~~λ~~ ~~1~~ $0^{17} 0^9$ 000010 $\emptyset\emptyset\emptyset \dots$

u_2 , ... λ ~~0~~ ~~λ~~ ~~1~~ ~~0~~ ~~0~~ ~~λ~~ ~~1~~ $0^{17} 0^9$ 00λ010 $\emptyset\emptyset\emptyset \dots$

u_2 , ... λ ~~0~~ ~~λ~~ ~~1~~ ~~0~~ ~~0~~ ~~λ~~ ~~1~~ $0^{17} 0^9$ 00λ010 $\emptyset\emptyset\emptyset \dots$

Simulation of reading 10

\vdash^2

00, 1010, 10	10010
00, 1010 , 10	01010

$u_1, \dots \lambda \mathbf{0} \lambda \mathbf{1} \mathbf{0} \mathbf{0} \mathbf{0} \lambda \mathbf{1} 0^{17} 0^9$

00 <u>1</u> 0010	$\emptyset \emptyset \emptyset \dots$
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$u_2, \dots \lambda \mathbf{0} \lambda \mathbf{1} \mathbf{0} \mathbf{0} \mathbf{0} \lambda \mathbf{1} 0^{17} 0^9$

00 <u>0</u> 0010	$\emptyset \emptyset \emptyset \dots$
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$u_2, \dots \lambda \mathbf{0} \lambda \mathbf{1} \mathbf{0} \mathbf{0} \mathbf{0} \lambda \mathbf{1} 0^{17} 0^9$

00 <u>0</u> λ 010	$\emptyset \emptyset \emptyset \dots$
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$u_2, \dots \lambda \mathbf{0} \lambda \mathbf{1} \mathbf{0} \mathbf{0} \mathbf{0} \lambda \mathbf{1} 0^{17} 0^9$

0 <u>0</u> 0 λ 010	$\emptyset \emptyset \emptyset \dots$
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$u_2, \dots \lambda \mathbf{0} \lambda \mathbf{1} \mathbf{0} \mathbf{0} \mathbf{0} \lambda \mathbf{1} 0^{17} 0^9$

<u>0</u> λ 0 λ 010	$\emptyset \emptyset \emptyset \dots$
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Simulation of reading 10

\vdash^2

00, 1010, 10	10010
00, 1010 , 10	01010

$u_1, \dots \lambda 0 \lambda \cancel{1} 0 0 0 \lambda \cancel{1} 0^{17} 0^9$	00 <u>1</u> 0010 $\emptyset \emptyset \emptyset \dots$
$u_2, \dots \lambda 0 \lambda \cancel{1} 0 0 0 \lambda \cancel{1} 0^{17} 0^9$	00 <u>0</u> 0010 $\emptyset \emptyset \emptyset \dots$
$u_2, \dots \lambda 0 \lambda \cancel{1} 0 0 0 \lambda \cancel{1} 0^{17} 0^9$	00 <u>0</u> λ 010 $\emptyset \emptyset \emptyset \dots$
$u_2, \dots \lambda 0 \lambda \cancel{1} 0 0 0 \lambda \cancel{1} 0^{17} 0^9$	00 <u>0</u> λ 010 $\emptyset \emptyset \emptyset \dots$
$u_2, \dots \lambda 0 \lambda \cancel{1} 0 0 0 \lambda \cancel{1} 0^{17} 0^9$	<u>0</u> λ 0 λ 010 $\emptyset \emptyset \emptyset \dots$
$u_2, \dots \lambda 0 \lambda \cancel{1} 0 0 0 \lambda \cancel{1} \lambda^{17} \lambda^9$	$\lambda \lambda$ 0 λ 010 $\emptyset \emptyset \emptyset \dots$

Simulation of reading 10

\vdash^2 00, 1010, **10** 10010
 00, **1010**, 10 01010

$u_2, \dots \lambda \mathbf{0} \lambda \mathbf{1} \mathbf{0} \mathbf{0} \mathbf{0} \lambda \mathbf{1} \lambda^{17} \lambda^9 \lambda \lambda \mathbf{0} \lambda \mathbf{0} \mathbf{1} \mathbf{0} \emptyset \emptyset \emptyset \dots$

$\langle 1 \rangle$	$\langle 0 \rangle$
$u_2, \dots \mathbf{00} \lambda \mathbf{1}$	$u_2, \dots \mathbf{0} \lambda \mathbf{1} \mathbf{0}$
$u_3, \dots \mathbf{00} \lambda \lambda$	$u_2, \dots \mathbf{0} \lambda \mathbf{1} \lambda$
$u_4, \dots \mathbf{000} \lambda$	$u_3, \dots \mathbf{00} \lambda \lambda$
$u_3, \dots \mathbf{0000} _$	$u_4, \dots \mathbf{000} \lambda$
	$u_3, \dots \mathbf{0000} _$
	$u_4, \dots \mathbf{0000} _$

So we exit the encoded symbol in one of two states:

$u_3 \Rightarrow$ append 1; and $u_4 \Rightarrow$ append 0

Simulation of reading 10

\vdash^2 00, 1010, **10** 10010
 00, **1010**, 10 01010

$u_3, \dots \lambda \mathbf{0\lambda 1000\lambda\lambda} \lambda^{17} \lambda^9 \quad \lambda\lambda 0\lambda 010 \emptyset\emptyset\emptyset\dots$

	$\langle 1 \rangle$	$\langle 0 \rangle$
u_2, \dots	$00\lambda\underline{1}$	$0\lambda\underline{10}$
u_3, \dots	$00\underline{\lambda}\lambda$	$0\lambda\underline{1}\lambda$
u_4, \dots	$000\underline{\lambda}$	$00\underline{\lambda}\lambda$
u_3, \dots	$0000\underline{\quad}$	$000\underline{0}\lambda$
		$u_3, \dots 0000\underline{\quad}$
		$u_4, \dots 0000\underline{\quad}$

So we exit the encoded symbol in one of two states:

$u_3 \Rightarrow$ append 1; and $u_4 \Rightarrow$ append 0

Simulation of reading 10

\vdash^2 00, 1010, **10** 10010
 00, **1010**, 10 01010

$u_4, \dots \lambda \mathbf{0\lambda\cancel{1}0000\lambda} \lambda^{17} \lambda^9 \quad \lambda\lambda 0\lambda 010 \emptyset\emptyset\emptyset\dots$

	$\langle 1 \rangle$		$\langle 0 \rangle$
$u_2, \dots 00\lambda\cancel{1}$		$u_2, \dots 0\lambda\cancel{1}0$	
$u_3, \dots 00\lambda\lambda$		$u_2, \dots 0\lambda\cancel{1}\lambda$	
$u_4, \dots 000\lambda$		$u_3, \dots 00\lambda\lambda$	
$u_3, \dots 0000__$		$u_4, \dots 000\lambda$	
		$u_3, \dots 0000__$	
		$u_4, \dots 0000__$	

So we exit the encoded symbol in one of two states:

$u_3 \Rightarrow$ append 1; and $u_4 \Rightarrow$ append 0

Simulation of reading 10

\vdash^2 00, 1010, **10** 10010
 00, **1010**, 10 01010

$u_3, \dots \lambda \mathbf{0\lambda\cancel{1}00000} 0^{17} 0^9 \quad \underline{\lambda\lambda 0\lambda 010} \ 000\dots$

	$\langle 1 \rangle$		$\langle 0 \rangle$
$u_2, \dots 00\lambda\cancel{1}$		$u_2, \dots 0\lambda\cancel{1}0$	
$u_3, \dots 00\underline{\lambda}\lambda$		$u_2, \dots 0\lambda\cancel{1}\lambda$	
$u_4, \dots 000\underline{\lambda}$		$u_3, \dots 00\underline{\lambda}\lambda$	
$u_3, \dots 0000\underline{}$		$u_4, \dots 000\underline{0}\lambda$	
		$u_3, \dots 0000\underline{}$	
		$u_4, \dots 0000\underline{}$	

So we exit the encoded symbol in one of two states:

$u_3 \Rightarrow$ append 1; and $u_4 \Rightarrow$ append 0

Simulation of reading 10

00, 1010, **10** 10010
 \vdash^2 00, **1010**, 10 01010

u_3 , ... λ ~~λ~~ ~~10~~ ~~00000~~ 0^{17} 0^9 000 λ 010 $\emptyset\emptyset\emptyset\dots$

	$\langle 1 \rangle$	$\langle 0 \rangle$
u_2 , ...	$00\lambda\underline{1}$	$0\lambda\underline{10}$
u_3 , ...	$00\underline{\lambda}\lambda$	$0\lambda\underline{1}\lambda$
u_4 , ...	$000\underline{\lambda}$	$00\underline{\lambda}\lambda$
u_3 , ...	$0000\underline{}$	$000\underline{\lambda}$
		u_3 , ... $0000\underline{}$
		u_4 , ... $0000\underline{}$

So we exit the encoded symbol in one of two states:

$u_3 \Rightarrow$ append 1; and $u_4 \Rightarrow$ append 0

Simulation of reading 10

\vdash^2 00, 1010, **10** 10010
 00, **1010**, 10 01010

$u_3, \dots \lambda \mathbf{0\lambda\cancel{1}00000} 0^{17} 0^9 \quad 000\underline{\lambda}010 \ 000\dots$

	$\langle 1 \rangle$		$\langle 0 \rangle$
$u_2, \dots 00\lambda\underline{1}$		$u_2, \dots 0\lambda\cancel{1}0$	
$u_3, \dots 00\underline{\lambda}\lambda$		$u_2, \dots 0\lambda\underline{1}\lambda$	
$u_4, \dots 000\underline{\lambda}$		$u_3, \dots 00\underline{\lambda}\lambda$	
$u_3, \dots 0000\underline{}$		$u_4, \dots 000\underline{0}\lambda$	
		$u_3, \dots 0000\underline{}$	
		$u_4, \dots 0000\underline{}$	

So we exit the encoded symbol in one of two states:

$u_3 \Rightarrow$ append 1; and $u_4 \Rightarrow$ append 0

Simulation of reading 10

\vdash^2 00, 1010, **10** 10010
 00, **1010**, 10 01010

$u_4, \dots \lambda \mathbf{0\lambda\cancel{1}00000} 0^{17} 0^9 \quad 00000\underline{10} \ 000\dots$

	$\langle 1 \rangle$		$\langle 0 \rangle$
$u_2, \dots 00\lambda\underline{1}$		$u_2, \dots 0\lambda\underline{1}0$	
$u_3, \dots 00\underline{\lambda}\lambda$		$u_2, \dots 0\lambda\underline{1}\lambda$	
$u_4, \dots 000\underline{\lambda}$		$u_3, \dots 00\underline{\lambda}\lambda$	
$u_3, \dots 0000\underline{\quad}$		$u_4, \dots 000\underline{0}\lambda$	
		$u_3, \dots 0000\underline{\quad}$	
		$u_4, \dots 0000\underline{\quad}$	

So we exit the encoded symbol in one of two states:

$u_3 \Rightarrow$ append 1; and $u_4 \Rightarrow$ append 0

Simulation of reading 10

$00, 1010, \mathbf{10}$ 10010
 \vdash^2 $00, \mathbf{1010}, 10$ 01010

$u_4, \dots \lambda \mathbf{0\lambda\cancel{1}00000}$ $0^{17} 0^9$ $0000010 \underline{000}$

	$\langle 1 \rangle$		$\langle 0 \rangle$
$u_2, \dots 00\lambda\underline{1}$		$u_2, \dots 0\lambda\cancel{1}0$	
$u_3, \dots 00\underline{\lambda}\lambda$		$u_2, \dots 0\lambda\underline{1}\lambda$	
$u_4, \dots 000\underline{\lambda}$		$u_3, \dots 00\underline{\lambda}\lambda$	
$u_3, \dots 0000\underline{}$		$u_4, \dots 000\underline{0}\lambda$	
		$u_3, \dots 0000\underline{}$	
		$u_4, \dots 0000\underline{}$	

So we exit the encoded symbol in one of two states:

$u_3 \Rightarrow$ append 1; and $u_4 \Rightarrow$ append 0

Simulation of reading 10

\vdash^2 00, 1010, **10** 10010
 00, **1010**, 10 01010

$u_2, \dots \lambda \mathbf{0\lambda\cancel{1}00000} 0^{17} 0^9 \quad 00\cancel{0}0\cancel{1}0 \quad 1\cancel{0}\cancel{0}$

	$\langle 1 \rangle$		$\langle 0 \rangle$
$u_2, \dots 00\lambda\cancel{1}$		$u_2, \dots 0\lambda\cancel{1}0$	
$u_3, \dots 00\lambda\lambda$		$u_2, \dots 0\lambda\cancel{1}\lambda$	
$u_4, \dots 000\lambda$		$u_3, \dots 00\lambda\lambda$	
$u_3, \dots 0000__$		$u_4, \dots 000\lambda$	
		$u_3, \dots 0000__$	
		$u_4, \dots 0000__$	

So we exit the encoded symbol in one of two states:

$u_3 \Rightarrow$ append 1; and $u_4 \Rightarrow$ append 0

Simulation of reading 10

\vdash^2 00, 1010, **10** 10010
00, **1010**, 10 01010

$u_2, \dots \lambda \mathbf{0} \lambda \mathbf{1} \mathbf{0} \lambda \lambda \lambda \lambda \lambda \lambda^9 \lambda^{17} \lambda^9 \lambda \lambda \mathbf{0} \lambda \mathbf{0} \mathbf{1} \mathbf{0} \mathbf{1} \emptyset \emptyset$

	$\langle 1 \rangle$	$\langle 0 \rangle$
u_2, \dots	$00 \lambda \underline{1}$	$0 \lambda \mathbf{1} \mathbf{0}$
u_3, \dots	$00 \underline{\lambda} \lambda$	$0 \lambda \underline{1} \lambda$
u_4, \dots	$000 \underline{\lambda}$	$00 \underline{\lambda} \lambda$
u_3, \dots	$0000 \underline{\quad}$	$000 \underline{\lambda}$
		$u_3, \dots 0000 \underline{\quad}$
		$u_4, \dots 0000 \underline{\quad}$

So we exit the encoded symbol in one of two states:

$u_3 \Rightarrow$ append 1; and $u_4 \Rightarrow$ append 0

Simulation of reading 10

\vdash^2 00, 1010, **10** 10010
00, **1010**, 10 01010

$u_3, \dots \lambda 0000000 0^{17} 0^9$ 0000010 100

	$\langle 1 \rangle$	$\langle 0 \rangle$
u_2, \dots	00 <u>λ</u> <u>1</u>	0 <u>λ</u> <u>1</u> 0
u_3, \dots	00 <u>λ</u> λ	0 <u>λ</u> <u>1</u> λ
u_4, \dots	000 <u>λ</u>	00 <u>λ</u> λ
u_3, \dots	0000 <u> </u>	000 <u> </u> λ
		u_3, \dots 0000 <u> </u>
		u_4, \dots 0000 <u> </u>

So we exit the encoded symbol in one of two states:

$u_3 \Rightarrow$ append 1; and $u_4 \Rightarrow$ append 0

Simulation of reading 10

\vdash^2 00, 1010, **10** 10010
00, **1010**, 10 01010

$u_2, \dots \lambda 0000000 0^{17} 0^9 \quad 0000010 \underline{1} 00$

	$\langle 1 \rangle$	$\langle 0 \rangle$
u_2, \dots	00 $\lambda \underline{1}$	0 $\lambda \underline{1} 0$
u_3, \dots	00 $\underline{\lambda} \lambda$	0 $\lambda \underline{1} \lambda$
u_4, \dots	000 $\underline{\lambda}$	00 $\underline{\lambda} \lambda$
u_3, \dots	0000 $\underline{\quad}$	000 $\underline{0} \lambda$
		u_3, \dots 0000 $\underline{\quad}$
		u_4, \dots 0000 $\underline{\quad}$

So we exit the encoded symbol in one of two states:

$u_3 \Rightarrow$ append 1; and $u_4 \Rightarrow$ append 0

Simulation of reading 10

\vdash^2 00, 1010, **10** 10010
00, **1010**, 10 01010

$u_2, \dots \underline{\lambda\lambda\lambda\lambda\lambda\lambda\lambda\lambda} \lambda^{17} \lambda^9 \quad \lambda\lambda 0 \lambda 010 \quad 10\emptyset$

	$\langle 1 \rangle$	$\langle 0 \rangle$
u_2, \dots	00 <u>$\lambda\lambda$</u>	0 <u>$\lambda\lambda$</u> 0
u_3, \dots	00 <u>λ</u> λ	0 <u>λ</u> $\lambda\lambda$
u_4, \dots	000 <u>λ</u>	00 <u>$\lambda\lambda$</u>
u_3, \dots	0000 <u> </u>	000 <u>λ</u>
		u_3, \dots 000 <u>λ</u>
		u_4, \dots 0000 <u> </u>

So we exit the encoded symbol in one of two states:

$u_3 \Rightarrow$ append 1; and $u_4 \Rightarrow$ append 0

Simulation of reading 10

\vdash^2 00, 1010, **10** 10010
00, **1010**, 10 01010

$\nu_1, \dots 0^9 0^{17} 0^9$ 000λ010 10∅

Simulation of reading 10

00, 1010, **10** 10010
 \vdash^2 00, **1010**, 10 01010

$u_1, \dots \lambda 0 \lambda 1 0 0 0 \lambda 1 0 \lambda 1 0 0 0 \lambda 1 \lambda 0 \lambda 1 0 0 \lambda 1 0$ 0^9 0^{17} 0^9 $00\underline{0}\lambda 010$ $10\emptyset$

Simulation of reading 10

\vdash^2 00, 1010, **10** 10010
00, **1010**, 10 01010

$u_1, \dots \lambda \text{0} \lambda \text{1} \text{000} \lambda \text{1} \text{0} \lambda \text{1} \text{000} \lambda \text{1} \text{0}^9 \text{0}^9 \text{0}^{17} \text{0}^9 \quad 000\underline{00}10 \text{10}\emptyset \dots$

After the simulation of reading 10:

- we have appended the appendant 10
- we have indexed two further appendants
- dataword is easily decodable (from head to blank symbol)

- Use of parity in $U_{4,5}$
- Key point: encode symbols via shifted subwords & parity
- For both machines:
- Simulation runs in polynomial time $O(t^4 \log^2 t)$
- Encoding in logspace (actually constant space & linear time)
- Prediction is P-complete (even for finite configurations)

- Find more semi-weak machines to complete the 'semi-weak universal curve'
- Explore encoding and decoding issues in a formal way?
- Exploring the 'open' space for standard machines (via weakness and other generalisations)
- Lower bounds on size for weak/semi-weak machines?
- Time complexity upper and lower bounds?
- New techniques for even smaller semi-weak machines?