

A Small Minimal Aperiodic Reversible Turing machine

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Motivation

Solve a conjecture that we had with J. Kari a few years ago:

Periodicity and Immortality in Reversible Computing

Jarkko Kari (Dept. of Mathematics, University of Turku, Finland)
Nicolas Ollinger (LIF, Aix-Marseille Université, CNRS, France)

Toruń, Poland — August 27, 2008

J. Kari and N. Ollinger. Periodicity and Immortality in Reversible Computing.
E. Ochmanski and J. Tyszkiewicz (Eds.), MFCS 2008, LNCS 5162, pp. 419–430, 2008.

...

Open Problems with conjectures

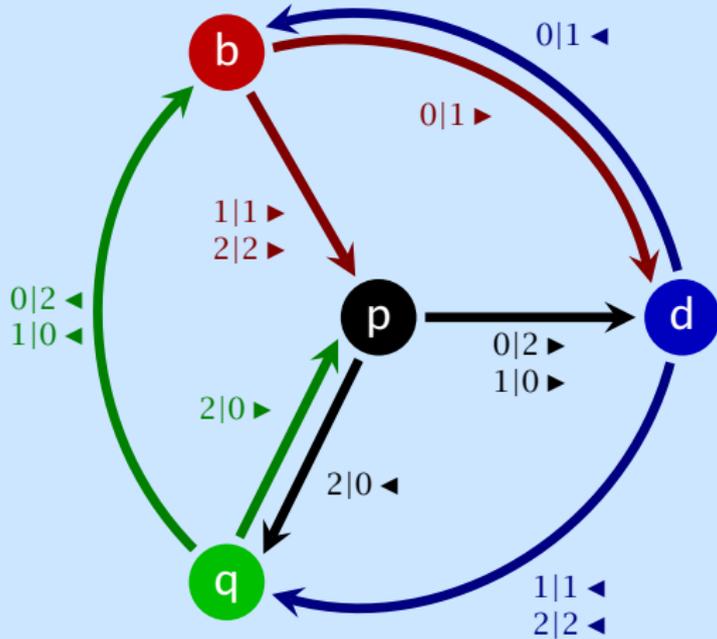


Conjecture 1 It is undecidable whether a given complete 2-RCM admits a periodic configuration. (*proven if you remove complete or replace 2 by 3*)

Conjecture 2 There exists a complete RTM without a periodic configuration. (*known for DTM [BCN02]*)

Conjecture 3 It is undecidable whether a given complete RTM admits a periodic configuration. (*known for DTM [BCN02]*)

Theorem To find if a given **complete reversible Turing machine** admits a **periodic orbit** is Σ_1 -complete.



1. Dynamics of Turing machines

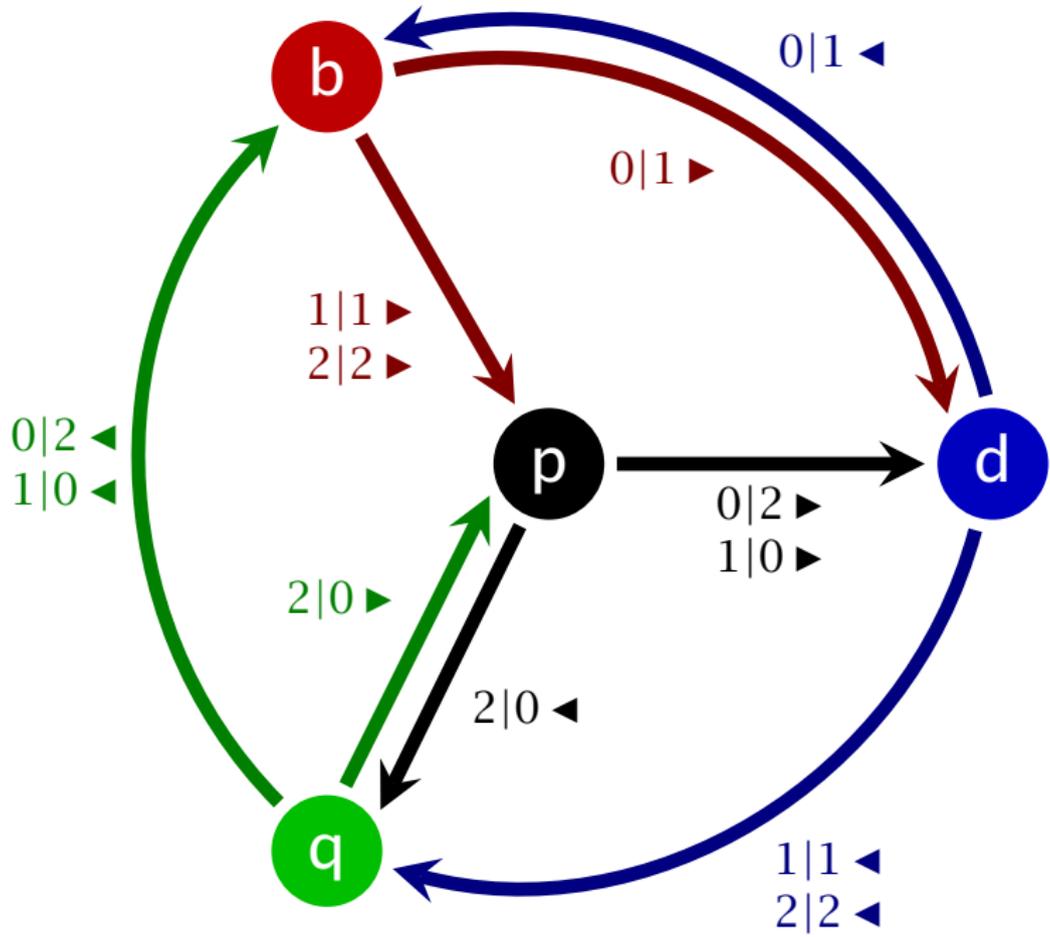
Turing machines

Definition A **Turing machine** is a triple (Q, Σ, δ) where Q is the finite set of states, Σ is the finite set of tape symbols and $\delta : Q \times \Sigma \rightarrow Q \times \Sigma \times \{\blacktriangleleft, \blacktriangleright\}$ is the transition function.

Transition $\delta(s, a) = (t, b, d)$ means:

“in state s , when reading the symbol a on the tape, replace it by b move the head in direction d and enter state t .”

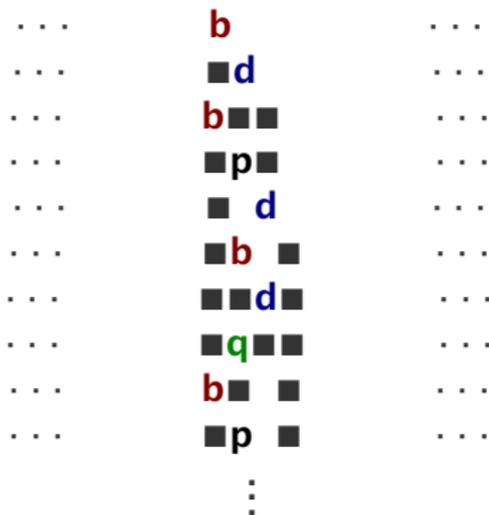
Remark We do not care about blank symbol or initial and final states, we see Turing machines as dynamical systems.



Moving head dynamics

$$X_H = Q \times \mathbb{Z} \times \Sigma^{\mathbb{Z}} \cup \Sigma^{\mathbb{Z}}$$

$$T_H : X_H \rightarrow X_H$$



Hergé. *On a marché sur la lune*. Casterman, 1954.



Long shot

Trace subshift

$$S_T \subseteq (Q \times \Sigma)^\omega$$

0 0 1 1 0 0 1 1 1 0 ...
b d b p d b d q b p ...

Hergé. *On a marché sur la lune*. Casterman, 1954.



Point of view shot

Simple dynamical properties

Definition A point $x \in X$ is **periodic** if it admits a **period** $p > 0$ such that $T^p(x) = x$.

Definition A machine is **periodic** if every point is periodic.

Remark Periodicity implies uniform periodicity: $T^p = \text{Id}$.

Theorem[KO08] The **periodicity problem** is Σ_1 -complete.

Definition A machine is **aperiodic** if it has no periodic point.

Partial vs complete machines

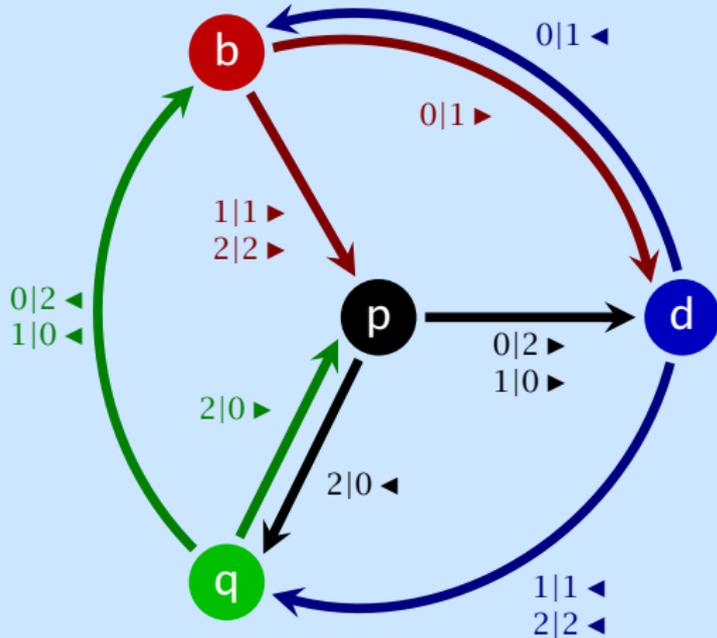
Definition A TM is **complete** if δ is completely defined, otherwise **undefined transitions** of a partial δ correspond to **halting configurations**.

Definition A point is **mortal** if it eventually **halts**.

Thm[Hooper66] The **immortality problem** is Π_1 -complete.

Rk Mortality is different from **totality** which is Π_2 -complete.

Thm[KO08] The result is the same for **reversible TM**.



2. Reversible Turing machines

Reversible Turing machines

Intuitively, a TM is **reversible** if there exists another TM to compute backwards: “ $T_2 = T_1^{-1}$ ”. **Forget technical details...**

Definition A TM is **reversible** if δ can be decomposed as:

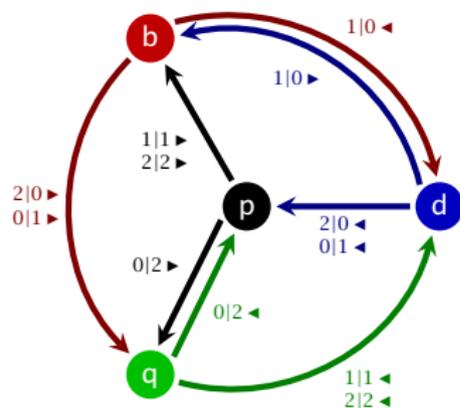
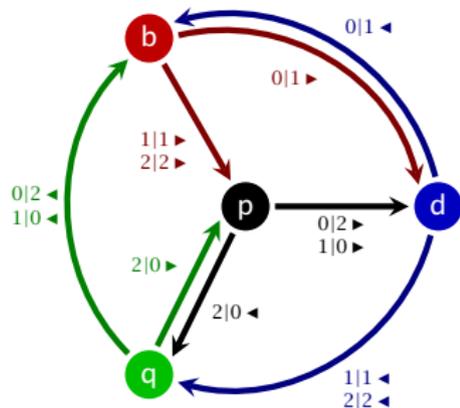
$$\delta(s, a) = (t, b, \rho(t)) \quad \text{where } (t, b) = \sigma(s, a)$$

$$\rho : Q \rightarrow \{\blacktriangleleft, \blacktriangleright\}$$

$$\sigma \in \mathfrak{S}_{Q \times \Sigma}$$

Remark $\delta^{-1}(t, b) = (s, a, \blacklozenge(\rho(s)))$

A complete RTM

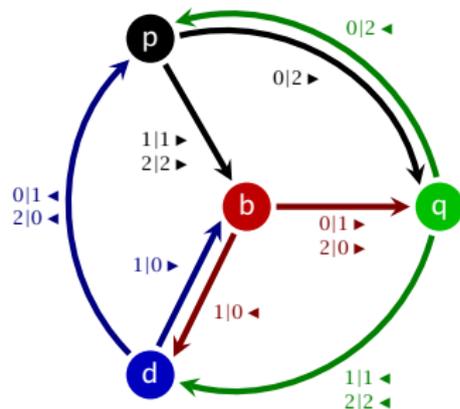


It is **time-symmetric**:
its own inverse up to
state/symbol permutation.

1 \Leftrightarrow 2

b \Leftrightarrow p

d \Leftrightarrow q



Searching for a reduction

We want to prove the following:

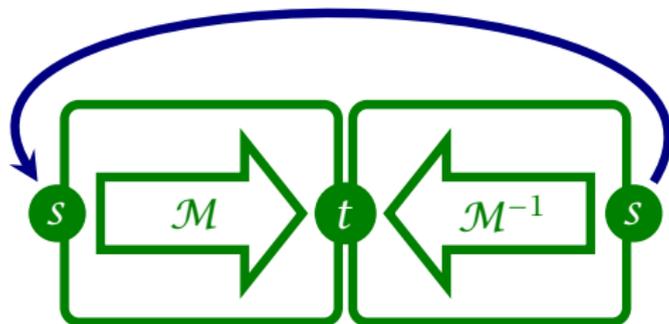
Theorem To find if a given **complete reversible Turing machine** admits a **periodic orbit** is Σ_1 -complete.

In the partial case we use the following tool:

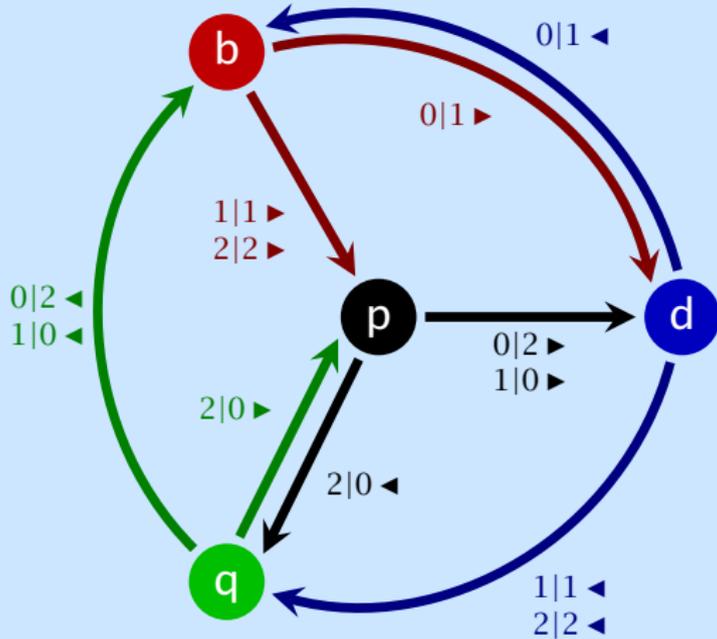
Prop[KO08] To find if a given **(aperiodic) RTM** can reach a given state t from a given state s is Σ_1 -complete.

The partial case

Principle of the reduction Associate to an (aperiodic) RTM \mathcal{M} with given s and t a new machine with a periodic orbit if and only if t is reachable from s .



We need to find a way to **complete** the constructed machine.



3. a SMART machine

The SMART machine \mathcal{C}

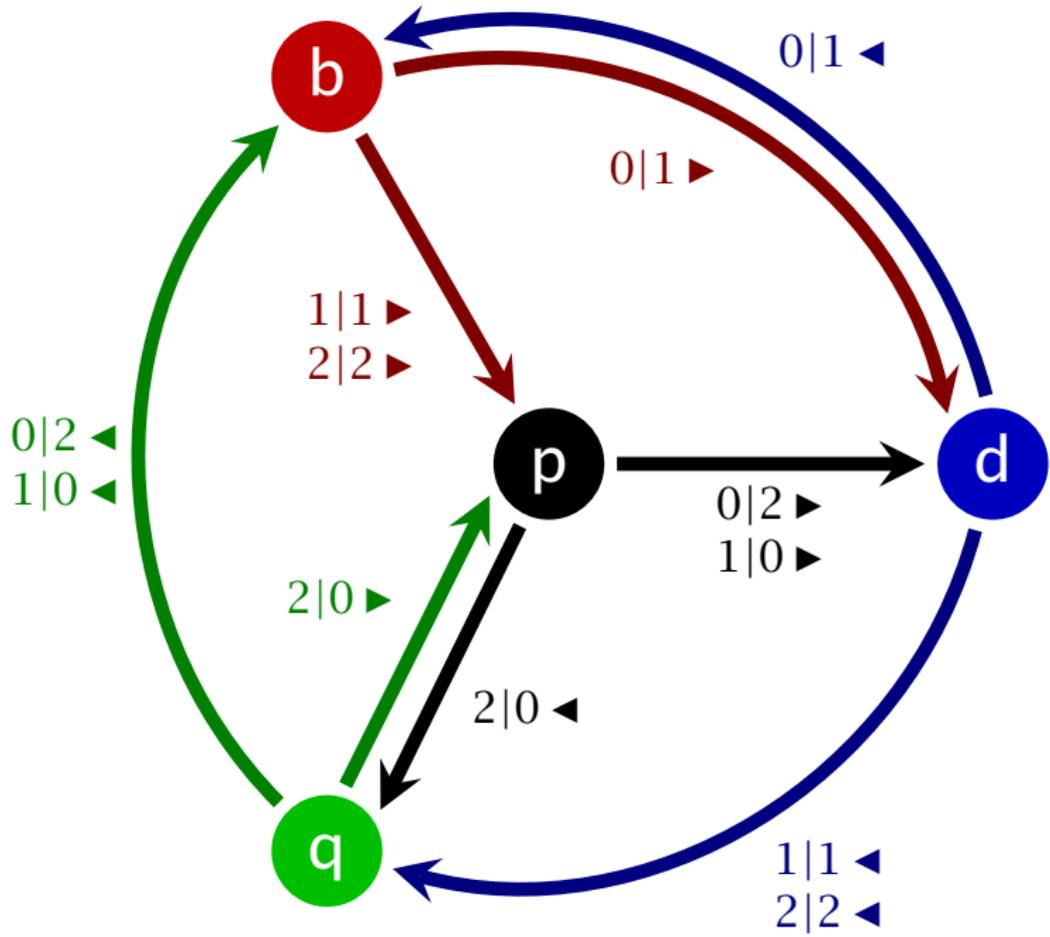
Conj[Kůrka97] Every **complete** TM has a **periodic** point.

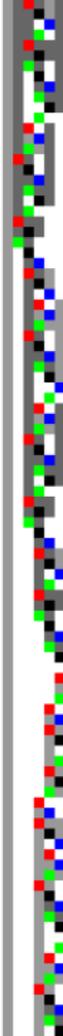
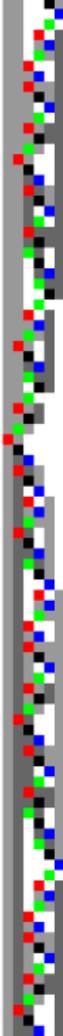
Thm[BCN02] No, here is an **aperiodic** complete TM.

Rk It relies on the **bounded search** technique [Hooper66].

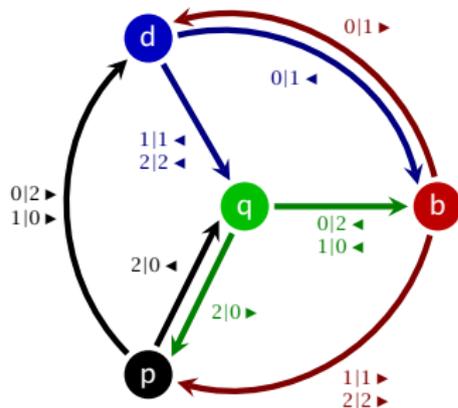
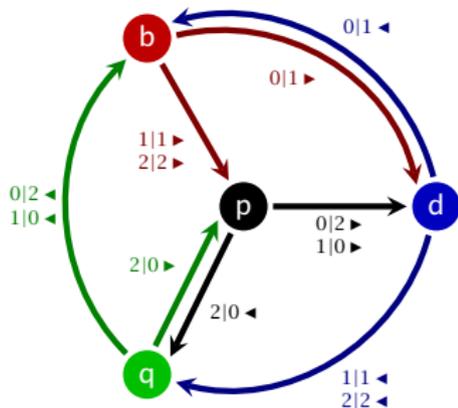
In 2008, I asked **J. Cassaigne** if he had a reversible version of the BCN construction. . .

. . . he answered with a small machine \mathcal{C} which is a reversible and (drastic) simplification of the BCN machine.





Symmetry

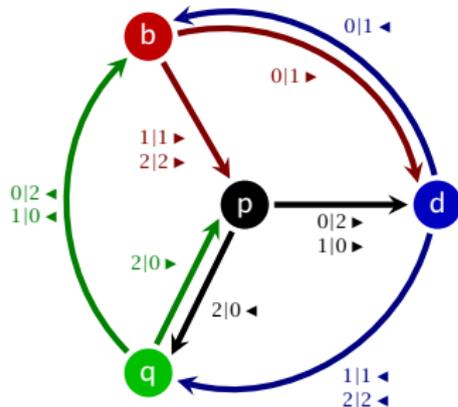


It is both **space-** and **time-symmetric.**

◀ ⇔ ▶

b ⇔ d

p ⇔ q



Aperiodicity

Proposition The machine \mathcal{C} is **aperiodic**.

Idea of the proof

1. The behavior starting from a tape of 0 is aperiodic;
2. Every block of 0 eventually grows;
3. Thus \mathcal{C} is aperiodic.

Minimality

The behavior of \mathcal{C} can be precisely described.

Proposition The behavior starting from a tape of 0 is **dense**.

Proposition The trace subshift of \mathcal{C} is **minimal**.

Proposition The trace subshift of \mathcal{C} is **substitutive**.

Substitutive trace subshift

$$\varphi \begin{pmatrix} 0 \\ \mathbf{b} \end{pmatrix} = \begin{matrix} 0 & 0 & 1 & 1 \\ \mathbf{b} & \mathbf{d} & \mathbf{b} & \mathbf{p} \end{matrix}$$

$$\varphi \begin{pmatrix} x \\ \mathbf{b} \end{pmatrix} = \begin{matrix} x \\ \mathbf{b} \end{matrix}$$

$$\varphi \begin{pmatrix} 0 \\ \mathbf{p} \end{pmatrix} = \begin{matrix} 0 & 0 & 2 & 1 \\ \mathbf{p} & \mathbf{d} & \mathbf{b} & \mathbf{p} \end{matrix}$$

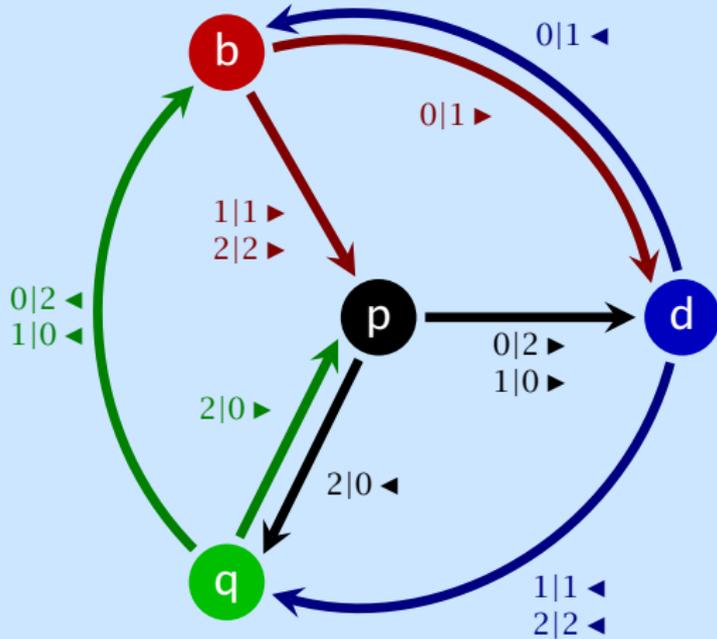
$$\varphi \begin{pmatrix} x \\ \mathbf{p} \end{pmatrix} = \begin{matrix} 0 & x & 2 & x \\ \mathbf{p} & \mathbf{d} & \mathbf{q} & \mathbf{p} \end{matrix}$$

$$\varphi \begin{pmatrix} 0 \\ \mathbf{d} \end{pmatrix} = \begin{matrix} 0 & 0 & 1 & 1 \\ \mathbf{d} & \mathbf{b} & \mathbf{d} & \mathbf{q} \end{matrix}$$

$$\varphi \begin{pmatrix} x \\ \mathbf{d} \end{pmatrix} = \begin{matrix} x \\ \mathbf{d} \end{matrix}$$

$$\varphi \begin{pmatrix} 0 \\ \mathbf{q} \end{pmatrix} = \begin{matrix} 0 & 0 & 2 & 1 \\ \mathbf{q} & \mathbf{b} & \mathbf{d} & \mathbf{q} \end{matrix}$$

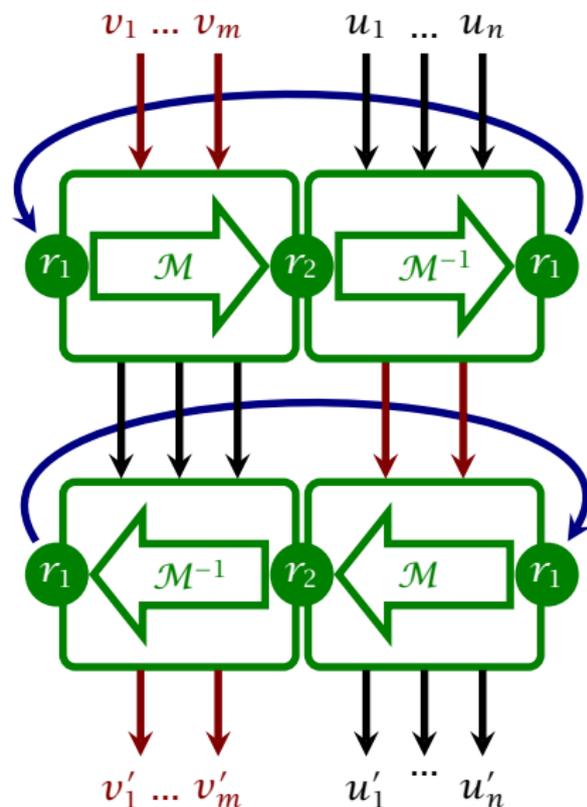
$$\varphi \begin{pmatrix} x \\ \mathbf{q} \end{pmatrix} = \begin{matrix} 0 & x & 2 & x \\ \mathbf{q} & \mathbf{b} & \mathbf{p} & \mathbf{q} \end{matrix}$$



4. Embedding the machine

Embedding trick

Use the transitions of the **Cassaigne machine** to connect the u'_i to the u_i and the v'_i to the v_i .



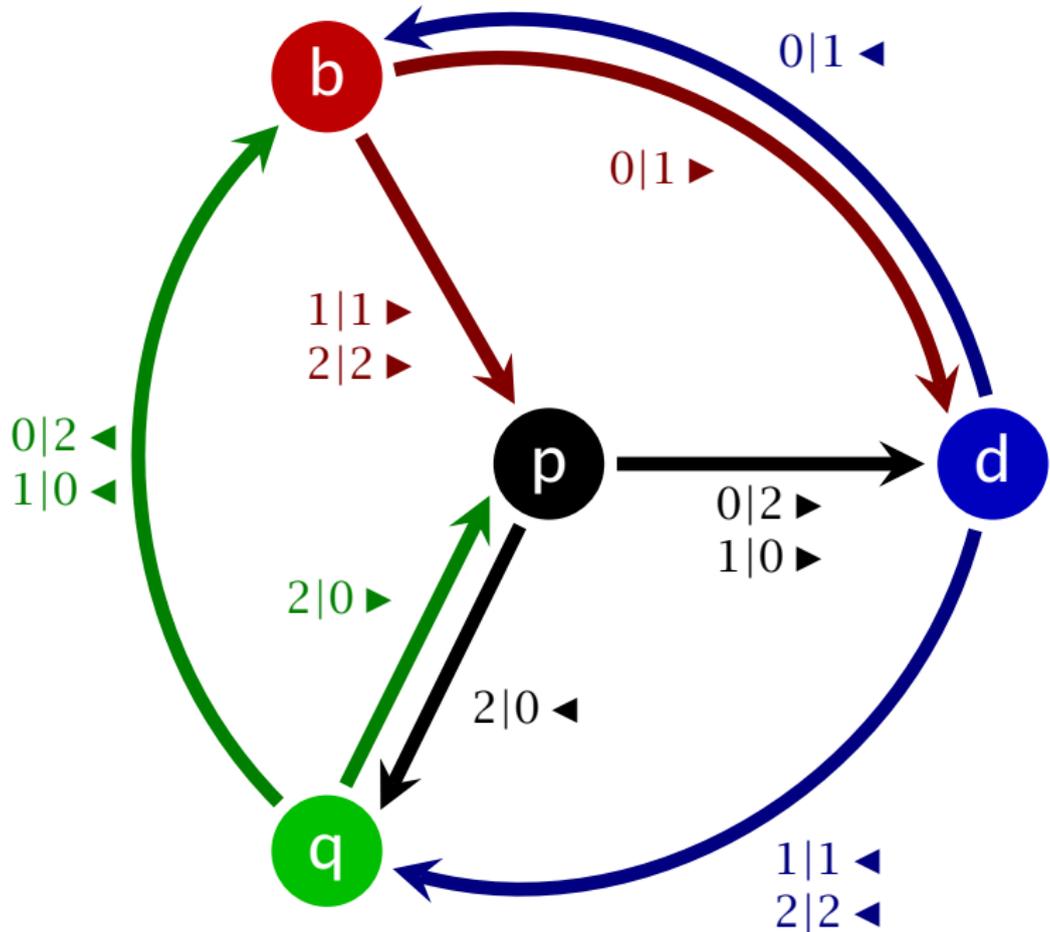


Table of contents

1. Dynamics of Turing machines

2. Reversible Turing machines

3. a SMART machine

4. Embedding the machine